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# AXIAL PISTON PUMPS SERIES PVPLUS

Design Series 47  
Variable Displacement



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## Table of Contents

Introduction and general Information .....	4
Technical Data .....	5
Ordering Code .....	6
Pressure Controls .....	18
Remote Pressure Controls .....	20
Load Sensing Controls .....	22
Horse Power/Torque Controls .....	26
Performance Curves .....	30
Electronic P/Q Controls .....	32
Efficiency and Case Drain Flows .....	34
Accessories Control .....	40
Proportional pressure relief valve PVACRE* .....	42
Proportional pressure relief valve with OBE PVACRE*T .....	44
Electronic Module PQDXXA .....	46
Electronic Module PQDXXA-PROFINET-Z10 .....	47
PVplus Condition Monitoring .....	48
Pump Dimensions .....	50
Control Dimensions .....	63
Through Drive – Mounting Kits .....	67
Through Drive – Flange Load Limitation .....	68
Through Drive – Shaft Load Limitations .....	69

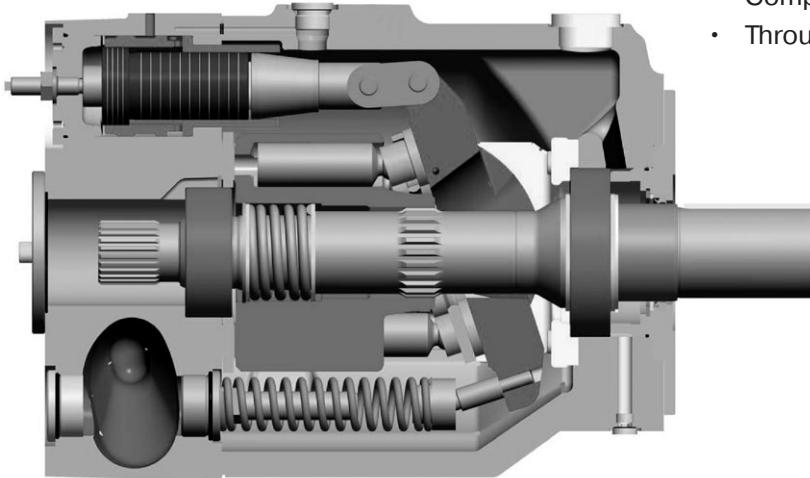


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**Parker Hannifin EMEA Sàrl European Headquarters**  
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# INTRODUCTION

## With through drive for single and multiple pumps

Swash plate type for open circuit



## Technical Features

- Low noise level
- Fast response
- Service-friendly
- High self-priming speed
- Compact design
- Through drive for 100 % nominal torque

## General Information

### Fluid recommendations

Premium quality hydraulic mineral fluid is recommended, like HLP oils to DIN 51524 (part 2 & 3) or ISO6743/4(HM & HV). Brugger-value recommended to be 30 N/mm<sup>2</sup> minimum for general application and 50 N/mm<sup>2</sup> for heavily loaded hydraulic equipment and fast cycling machines and/or high dynamic loads, measured in accordance with DIN 51 347-2. See also Document MSG30-3248/UK Parker Hydraulic Fluids.

### Viscosity

The normal operating viscosity should range between 16 and 100 mm<sup>2</sup>/s (cSt). Max. start-up viscosity is 1000 mm<sup>2</sup>/s (cSt).

### Filtration

For maximum pump and system component functionality and life, the system should be protected from contamination by effective filtration.

Fluid cleanliness should be in accordance with ISO classification ISO 4406:1999. The quality of filter elements should be in accordance with ISO standards.

General hydraulic systems for satisfactory operation: Class 20/18/15, according to ISO 4406:1999  
Recommended cleanliness for maximum component life and functionality: Class 18/16/13, according to ISO 4406:1999

### Seals

Check hydraulic fluid specification for chemical resistance of seal material.

Check temperature range of seal material and compare with max. system and ambient temperature.

N – Nitrile (FKM shaft seal) -25...+ 90 °C

V – FKM (FKM shaft seal) -25...+115 °C

W – Nitrile (PTFE shaft seal) -30...+ 90 °C

**Note:** The highest fluid temperature will be at the drain port of the pump, up to 25 °C higher than in the reservoir.

# TECHNICAL DATA

		PV016	PV020	PV023	PV028	PV032	PV040	PV046
Frame size		1	1	1	1	2	2	2
Max. displacement	[cm <sup>3</sup> /rev.]	16	20	23	28	32	40	46
Output flow at 1500 rpm	[l/min]	24	30	34,5	42	48	60	69
Nominal pressure pN	[bar]	350	350	350	350	350	350	350
Min. outlet pressure	[bar]	15	15	15	15	15	15	15
Max. pressure pmax at 20 % working cycle <sup>1)</sup>	[bar]	420	420	420	420	420	420	420
Case drain pressure, continuous	[bar]	0.5	0.5	0.5	0.5	0.5	0.5	0.5
Case drain pressure, max. peak	[bar]	2.0	2.0	2.0	2.0	2.0	2.0	2.0
Min. inlet pressure, abs.	[bar]	0.8	0.8	0.8	0.8	0.8	0.8	0.8
Max. inlet pressure	[bar]	16	16	16	16	16	16	16
Input power at 1500 rpm and 350 bar	[kW]	15.9	19.7	22.4	26.9	31.1	38.5	43.8
Max. input torque at 350 bar	[Nm]	94.5	118.1	135.9	165.4	184.3	230.4	265.0
Max speed at 1 bar, abs, inlet pressure	[rpm]	3000	3000	3000	3000	2800	2800	2800
Min. speed	[rpm]	50	50	50	50	50	50	50
Moment of inertia	[kgm <sup>2</sup> ]	0.0016	0.0016	0.0016	0.0016	0.0047	0.0047	0.0047
Weight	[kg]	19	19	19	19	30	30	30

		PV063	PV080	PV092	PV140	PV180	PV270	PV360
Frame size		3	3	3	4	4	5	6
Max. displacement	[cm <sup>3</sup> /rev.]	63	80	92	140	180	270	360
Output flow at 1500 rpm	[l/min]	94.5	120	138	210	270	405	540
Nominal pressure pN	[bar]	350	350	350	350	350	350	350
Min. outlet pressure	[bar]	15	15	15	15	15	15	15
Max. pressure pmax at 20 % working cycle <sup>1)</sup>	[bar]	420	420	420	420	420	420	420
Case drain pressure, continuous	[bar]	0.5	0.5	0.5	0.5	0.5	0.5	0.5
Case drain pressure, max. peak	[bar]	2.0	2.0	2.0	2.0	2.0	2.0	2.0
Min. inlet pressure, abs.	[bar]	0.8	0.8	0.8	0.8	0.8	0.8	0.8
Max. inlet pressure	[bar]	16	16	16	16	16	16	16
Input power at 1500 rpm and 350 bar	[kW]	61.3	76.9	87.5	136.1	173.1	259.6	338.7
Max. input torque at 350 bar	[Nm]	365.2	463.7	533.3	812.4	1044.5	1550.5	2067.4
Max speed at 1 bar, abs, inlet pressure	[rpm]	2800	2500	2300	2400	2200	1800	1750
Min. speed	[rpm]	50	50	50	50	50	50	50
Moment of inertia	[kgm <sup>2</sup> ]	0.018	0.018	0.018	0.030	0.030	0.098	0.103
Weight	[kg]	59	59	59	90	90	172	180

<sup>1)</sup> Check adjustment range each compensator.

# ORDERING CODE FRAME SIZE 1

<b>P</b>	<b>V</b>				<b>R</b>	<b>1</b>	<b>K</b>	<b>1</b>	<b>T</b>	<b>1</b>	<b>N</b>			
axial piston pump variable displace- ment	size and displacement		rotation		mounting interface		through drive code		seals		control			
			variation		threads code		coupling code					see next page		
<b>Code</b>	<b>Displacement</b>	<b>Size</b>												
016	16 cm <sup>3</sup> /rev	1												
020	20 cm <sup>3</sup> /rev	1												
023	23 cm <sup>3</sup> /rev	1												
028	28 cm <sup>3</sup> /rev	1												
<b>Code</b>	<b>Rotation 1)</b>													
R	Clockwise													
L	Counter clockwise													
1) When looked on shaft														
<b>Code</b>	<b>Variation</b>													
1	Standard													
4	Electronic displacement sensor (CIP) <sup>2)</sup>													
5	CIP-Sensor & Spec. adjustment <sup>3)</sup> (4 & 9)													
9	Special adjustment <sup>3)</sup>													
2) not for horse power control, mandatory with FDV/UD*														
3) requires Kxxxx number														
<b>Code</b>	<b>Mounting interface</b>				<b>Shaft</b>									
K	metr. ISO 3019/2	4-hole flange Ø100 mm			Cylindric, key									
L		4-hole flange Ø100 mm			Splined, DIN 5480									
D	SAE ISO 3019/1	4-hole flange SAE B			Cylindric, key									
E		4-hole flange SAE B-B			Splined, SAE									
<b>Code</b>	<b>Port<sup>4)</sup></b>	<b>Threads<sup>5)</sup></b>												
1	BSPP	metric												
3	UNF	UNC												
8 <sup>6)</sup>	ISO 6149	metric												

4) Drain and flushing ports

5) All mounting and connecting threads

6) Mounting interface, code K and L only

Standard pump is not painted. Black painted pump and ATEX (excludes electronic components) certification (Zone 2) is available as special option. For additional informations please contact Parker Hannifin.

# ORDERING CODE FRAME SIZE 1

Code			Control options
0	0	1	No control
1	0	0	With cover plate, no control function (fixed displacement pump)
M	M		Standard pressure control
M	R		Remote pressure control
M	F		Load Sensing (flow) control
M	T		Two spool LS control
Control variation			
C			Standard version, integrated pilot valve <sup>1)</sup>
1			NG6 interface top side for pilot valves <sup>1)</sup>
2			Remote pressure port int. supply , NG6 interface <sup>2)</sup>
3			Remote pressure port ext. supply <sup>2)</sup>
W			With unloading function, 24VDC solenoid <sup>1)</sup>
K			Prop.-pilot valve type PVACRE...K35 mounted
Z			Without integrated pilot valve, NG6 interface, for mounting of accessory code PVAC*
B			Without integrated pilot valve, without NG6 interface <sup>3)</sup>
P			MTZ with mounted pilot valve PVAC1P <sup>2)</sup>
F			Prop.-pilot valve PVACRE*35T with OBE mounted, command signal 0 - 10V
R			Prop.-pilot valve PVACRE*35T with OBE mounted, command signal 4 - 20 mA

<sup>1)</sup> not for MT & \*Z

<sup>2)</sup> only for MT & \*Z

<sup>3)</sup> not for MT & MM

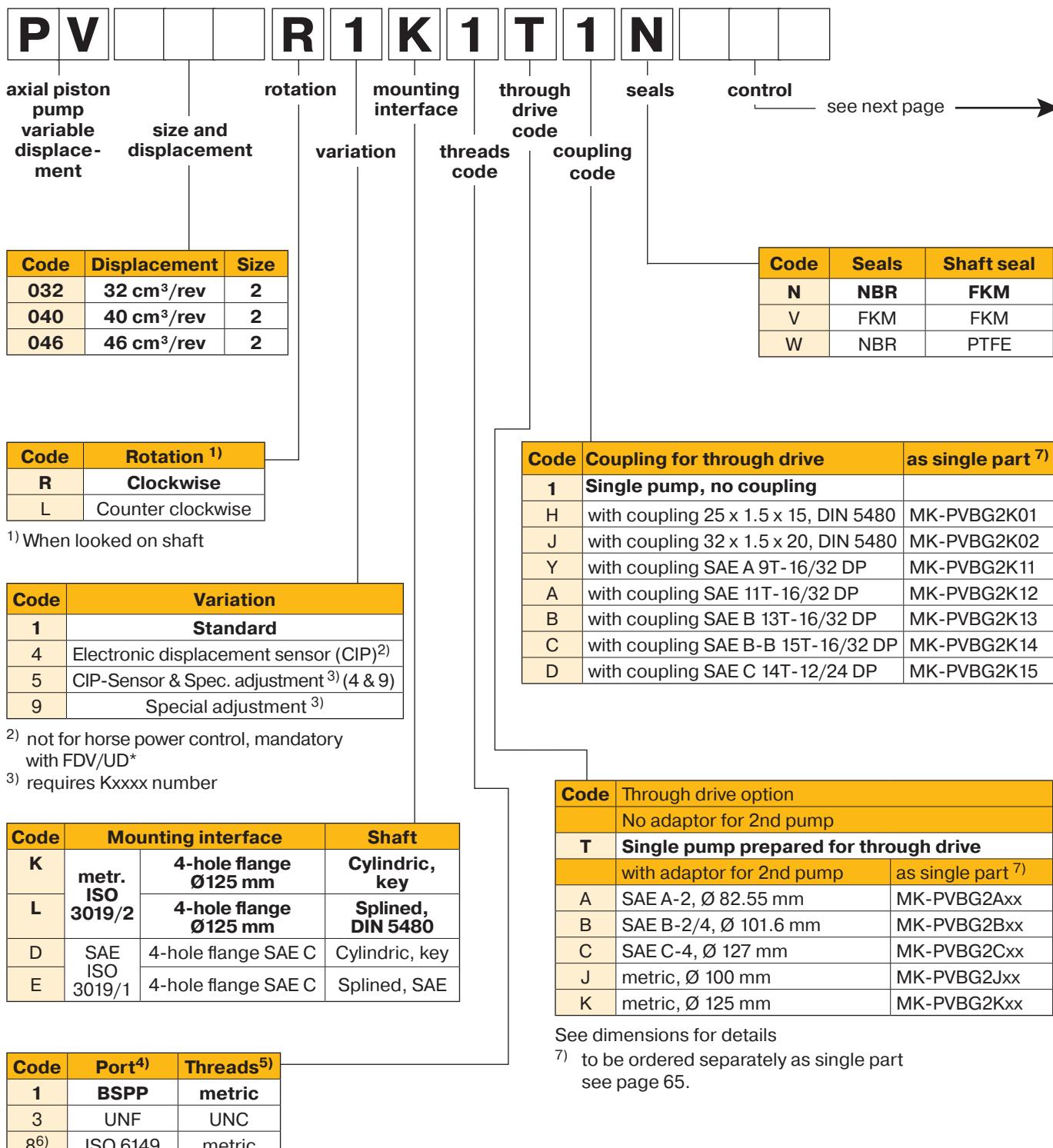
Horse power / Torque control			
Code		Nominal HP at 1.500 rpm	Nominal torque
B		3 kW	20 Nm
C		4 kW	25 Nm
D		5.5 kW	35 Nm
E		7.5 kW	50 Nm
G		11 kW	71 Nm
H		15 kW	97 Nm
K		18.5 kW	120 Nm
Function			
L		Horse power control with pressure control <sup>4)</sup>	
C		Horse power control with load sensing (single spool)	
Z		Horse power control with two spool LS control	
Control variation			
C		Standard version, integrated pilot valve <sup>1)</sup>	
1		NG 6 interface top side	
W		With unloading function, 24 VDC solenoid	
K		Prop.-pilot valve type PVACRE...K35 mounted	
Z		Without integrated pilot valve, NG6 interface, for mounting of accessory code PVAC* <sup>4)</sup>	
B		Without integrated pilot valve, without NG6 interface <sup>1), 4)</sup>	
P		*ZZ with mounted pilot valve PVAC1P <sup>2)</sup>	
F		Prop.-pilot valve PVACRE*35T with OBE mounted, command signal 0 - 10V	
R		Prop.-pilot valve PVACRE*35T with OBE mounted, command signal 4 - 20 mA	

<sup>4)</sup> control variation Z and B without pressure pilot

Code		Control option	
Electro hydraulic control <sup>5)</sup>			
F	D	V	Proportional displacement control, no pressure compensation
U	D		Proportional displacement control, with pressure compensation
Control variation			
	R		pilot operated pressure control, open NG6 interface
	K		pilot operated pressure control, proportional pilot valve type PVACRE...K35 mounted
	M		pilot operated pressure control, pressure sensor and proportional pilot valve type PVACRE...K35 mounted for pressure control and/or power control

<sup>5)</sup> further info in MSG30-3254

# ORDERING CODE FRAME SIZE 2



4) Drain and flushing ports

5) All mounting and connecting threads

6) Mounting interface, code K and L only

Standard pump is not painted. Black painted pump and ATEX (excludes electronic components) certification (Zone 2) is available as special option. For additional informations please contact Parker Hannifin.

# ORDERING CODE FRAME SIZE 2

Code			Control options
0	0	1	No control
1	0	0	With cover plate, no control function (fixed displacement pump)
M	M		Standard pressure control
M	R		Remote pressure control
M	F		Load Sensing (flow) control
M	T		Two spool LS control
Control variation			
	C		Standard version, integrated pilot valve <sup>1)</sup>
	1		NG6 interface top side for pilot valves <sup>1)</sup>
	2		Remote pressure port int. supply , NG6 interface <sup>2)</sup>
	3		Remote pressure port ext. supply <sup>2)</sup>
	W		With unloading function, 24VDC solenoid <sup>1)</sup>
	K		Prop.-pilot valve type PVACRE...K35 mounted
	Z		Without integrated pilot valve, NG6 interface, for mounting of accessory code PVAC*
	B		Without integrated pilot valve, without NG6 interface <sup>3)</sup>
	P		MTZ with mounted pilot valve PVAC1P <sup>2)</sup>
	F		Prop.-pilot valve PVACRE*35T with OBE mounted, command signal 0 - 10V
	R		Prop.-pilot valve PVACRE*35T with OBE mounted, command signal 4 - 20 mA

<sup>1)</sup> not for MT & \*Z

<sup>2)</sup> only for MT & \*Z

<sup>3)</sup> not for MT & MM

Horse power / Torque control		
Code		
Nominal HPat 1.500 rpm		
D		5.5 kW
E		7.5 kW
G		11 kW
H		15 kW
K		18.5 kW
M		22 kW
S		30 kW
Nominal torque		
		35 Nm
		50 Nm
		71 Nm
		97 Nm
		120 Nm
		142 Nm
		195 Nm
Function		
L		Horse power control with pressure control <sup>4)</sup>
C		Horse power control with load sensing (single spool)
Z		Horse power control with two spool LS control
Control variation		
	C	Standard version, integrated pilot valve <sup>1)</sup>
	1	NG 6 interface top side
	W	With unloading function, 24 VDC solenoid
	K	Prop.-pilot valve type PVACRE...K35 mounted
	Z	Without integrated pilot valve, NG6 interface, for mounting of accessory code PVAC* <sup>4)</sup>
	B	Without integrated pilot valve, without NG6 interface <sup>1), 4)</sup>
	P	*ZZ with mounted pilot valve PVAC1P <sup>2)</sup>
	F	Prop.-pilot valve PVACRE*35T with OBE mounted, command signal 0 - 10V
	R	Prop.-pilot valve PVACRE*35T with OBE mounted, command signal 4 - 20 mA

<sup>4)</sup> control variation Z and B without pressure pilot

Code			Control option
			Electro hydraulic control <sup>5)</sup>
F	D	V	Proportional displacement control, no pressure compensation
U	D		Proportional displacement control, with pressure compensation
Control variation			
	R		pilot operated pressure control, open NG6 interface
	K		pilot operated pressure control, proportional pilot valve type PVACRE...K35 mounted
	M		pilot operated pressure control, pressure sensor and proportional pilot valve type PVACRE...K35 mounted for pressure control and/or power control

<sup>5)</sup> further info in MSG30-3254

# ORDERING CODE FRAME SIZE 3

P	V				R	1	K	1	T	1	N			
axial piston pump					rotation		mounting interface		through drive code		seals		control	
variable displacement		size and displacement			variation		threads code		coupling code					see next page
Code	Displacement	Size												
063	63 cm <sup>3</sup> /rev	3												
080	80 cm <sup>3</sup> /rev	3												
092	92 cm <sup>3</sup> /rev	3												
Code	Seals	Shaft seal												
N	NBR	FKM												
V	FKM	FKM												
W	NBR	PTFE												
Code	Rotation <sup>1)</sup>													
R	Clockwise													
L	Counter clockwise													
1) When looked on shaft														
Code	Variation													
1	Standard													
4	Electronic displacement sensor (CIP) <sup>2)</sup>													
5	CIP-Sensor & Spec. adjustment <sup>3)</sup> (4 & 9)													
9	Special adjustment <sup>3)</sup>													
2) not for horse power control, mandatory with FDV/UD*														
3) requires Kxxxx number														
Code	Mounting interface	Shaft												
K	metr. ISO 3019/2	4-hole flange Ø160 mm	Cylindric, key											
L		4-hole flange Ø160 mm	Splined, DIN 5480											
D	SAE ISO 3019/1	4-hole flange SAE D	Cylindric, key											
E		4-hole flange SAE D	Splined, SAE											
Code	Port <sup>4)</sup>	Threads <sup>5)</sup>												
1	BSPP	metric												
3	UNF	UNC												
4 <sup>6)</sup>	BSPP	metr. M14												
8 <sup>7)</sup>	ISO 6149	metric												

4) Drain and flushing ports

5) All mounting and connecting threads

6) For PV063-PV092 only: pressure port 1 1/4" with 4 x M14 instead of 4 x M12

7) for mounting interface K and L only

Standard pump is not painted. Black painted pump and ATEX (excludes electronic components) certification (Zone 2) is available as special option. For additional informations please contact Parker Hannifin.

# ORDERING CODE FRAME SIZE 3

Code			Control options
0	0	1	No control
1	0	0	With cover plate, no control function (fixed displacement pump)
M	M		Standard pressure control
M	R		Remote pressure control
M	F		Load Sensing (flow) control
M	T		Two spool LS control
Control variation			
	C		Standard version, integrated pilot valve <sup>1)</sup>
	1		NG6 interface top side for pilot valves <sup>1)</sup>
	2		Remote pressure port int. supply , NG6 interface <sup>2)</sup>
	3		Remote pressure port ext. supply <sup>2)</sup>
	W		With unloading function, 24VDC solenoid <sup>1)</sup>
	K		Prop.-pilot valve type PVACRE...K35 mounted
	Z		Without integrated pilot valve, NG6 interface, for mounting of accessory code PVAC*
	B		Without integrated pilot valve, without NG6 interface <sup>3)</sup>
	P		MTZ with mounted pilot valve PVAC1P <sup>2)</sup>
	F		Prop.-pilot valve PVACRE*35T with OBE mounted, command signal 0 - 10V
	R		Prop.-pilot valve PVACRE*35T with OBE mounted, command signal 4 - 20 mA

<sup>1)</sup> not for MT & \*Z

<sup>2)</sup> only for MT & \*Z

<sup>3)</sup> not for MT & MM

Horse power / Torque control			
Code		Nominal HP at 1.500 rpm	
		Nominal HP at 1.500 rpm	Nominal torque
G		11 kW	71 Nm
H		15 kW	97 Nm
K		18.5 kW	120 Nm
M		22 kW	142 Nm
S		30 kW	195 Nm
T		37 kW	240 Nm
U		45 kW	290 Nm
W		55 kW	355 Nm
Function			
L		Horse power control with pressure control <sup>4)</sup>	
C		Horse power control with load sensing (single spool)	
Z		Horse power control with two spool LS control	
Control variation			
	C	Standard version, integrated pilot valve <sup>1)</sup>	
	1	NG 6 interface top side	
	W	With unloading function, 24 VDC solenoid	
	K	Prop.-pilot valve type PVACRE...K35 mounted	
	Z	Without integrated pilot valve, NG6 interface, for mounting of accessory code PVAC* <sup>4)</sup>	
	B	Without integrated pilot valve, without NG6 interface <sup>1), 4)</sup>	
	P	*ZZ with mounted pilot valve PVAC1P <sup>2)</sup>	
	F	Prop.-pilot valve PVACRE*35T with OBE mounted, command signal 0 - 10V	
	R	Prop.-pilot valve PVACRE*35T with OBE mounted, command signal 4 - 20 mA	

<sup>4)</sup> control variation Z and B without pressure pilot

Code		Control option	
Electro hydraulic control <sup>5)</sup>			
F	D	V	Proportional displacement control, no pressure compensation
U	D		Proportional displacement control, with pressure compensation
Control variation			
	R		pilot operated pressure control, open NG6 interface
	K		pilot operated pressure control, proportional pilot valve type PVACRE...K35 mounted
	M		pilot operated pressure control, pressure sensor and proportional pilot valve type PVACRE...K35 mounted for pressure control and/or power control

<sup>5)</sup> further info in MSG30-3254

# ORDERING CODE FRAME SIZE 4

P V  R 1 K 1 T 1 N

axial piston  
pump  
variable  
displace-  
ment

rotation

mounting  
interface  
variation

through  
drive  
code  
threads  
code

seals  
coupling  
code

control

see next page

Code	Displacement	Size
140	140 cm <sup>3</sup> /rev	4
180	180 cm <sup>3</sup> /rev	4

Code	Seals	Shaft seal
N	NBR	FKM
V	FKM	FKM
W	NBR	PTFE

Code	Rotation <sup>1)</sup>
R	Clockwise
L	Counter clockwise

1) When looked on shaft

Code	Variation
1	Standard
4	Electronic displacement sensor (CIP) <sup>2)</sup>
5	CIP-Sensor & Spec. adjustment <sup>3)</sup> (4 & 9)
9	Special adjustment <sup>3)</sup>

2) not for horse power control, mandatory  
with FDV/UD\*

3) requires Kxxxx number

Code	Mounting interface	Shaft
K	metr. ISO 3019/2	4-hole flange Ø160 mm Cylindric, key
L		4-hole flange Ø160 mm Splined, DIN 5480
D	SAE ISO 3019/1	4-hole flange SAE D Cylindric, key, SAE F
E		4-hole flange SAE D Splined, SAE F, SAE D
F		4-hole flange SAE D Cylindric, key, SAE D
G		4-hole flange SAE D Splined, SAE D

Code	Port <sup>4)</sup>	Threads <sup>5)</sup>
1	BSPP	metric
3	UNF	UNC
4 <sup>6)</sup>	BSPP	metr. M14
8 <sup>7)</sup>	ISO 6149	metric

Code	Coupling for through drive	as single part <sup>8)</sup>
1	Single pump, no coupling	
H	with coupling 25 x 1.5 x 15, DIN 5480	MK-PVBG4K01
J	with coupling 32 x 1.5 x 20, DIN 5480	MK-PVBG4K02
K	with coupling 40 x 1.5 x 25, DIN 5480	MK-PVBG4K03
L	with coupling 50 x 2 x 24, DIN 5480	MK-PVBG4K04
Y	with coupling SAE A 9T-16/32 DP	MK-PVBG4K11
A	with coupling SAE 11T-16/32 DP	MK-PVBG4K12
B	with coupling SAE B 13T-16/32 DP	MK-PVBG4K13
C	with coupling SAE B-B 15T-16/32 DP	MK-PVBG4K14
D	with coupling SAE C 14T-12/24 DP	MK-PVBG4K15
E	with coupling SAE C-C 17T-12/24 DP	MK-PVBG4K16
F	with coupling SAE D, E 13T-8/16 DP	MK-PVBG4K17
G	with coupling SAE F 15T-8/16 DP	MK-PVBG4K18

Code	Through drive option
	No adaptor for 2nd pump
T	Single pump prepared for through drive
	with adaptor for 2nd pump
A	as single part <sup>8)</sup>
B	SAE A-2, Ø 82.55 mm
C	SAE B-2/4, Ø 101.6 mm
D	SAE C-2/4, Ø 127.0 mm
J	SAE D-4, Ø 152.4 mm
K	metric, Ø 100 mm
L	metric, Ø 125 mm
	metric, Ø 160 mm

See dimensions for details

<sup>8)</sup> to be ordered separately as single part  
see page 65.

4) Drain and flushing ports

5) All mounting and connecting threads

6) Pressure port 1 1/4" with 4 x M14 instead of 4 x M12

7) Mounting interface, code K and L only

Standard pump is not painted. Black painted pump and ATEX (excludes electronic components) certification (Zone 2) is available as special option. For additional informations please contact Parker Hannifin.

# ORDERING CODE FRAME SIZE 4

Code			Control options
0	0	1	No control
1	0	0	With cover plate, no control function (fixed displacement pump)
M	M		Standard pressure control
M	R		Remote pressure control
M	F		Load Sensing (flow) control
M	T		Two spool LS control
Control variation			
	C		Standard version, integrated pilot valve <sup>1)</sup>
	1		NG6 interface top side for pilot valves <sup>1)</sup>
	2		Remote pressure port int. supply , NG6 interface <sup>2)</sup>
	3		Remote pressure port ext. supply <sup>2)</sup>
	W		With unloading function, 24VDC solenoid <sup>1)</sup>
	K		Prop.-pilot valve type PVACRE...K35 mounted
	Z		Without integrated pilot valve, NG6 interface, for mounting of accessory code PVAC*
	B		Without integrated pilot valve, without NG6 interface <sup>3)</sup>
	P		MTZ with mounted pilot valve PVAC1P <sup>2)</sup>
	F		Prop.-pilot valve PVACRE*35T with OBE mounted, command signal 0 - 10V
	R		Prop.-pilot valve PVACRE*35T with OBE mounted, command signal 4 - 20 mA

<sup>1)</sup> not for MT & \*Z

<sup>2)</sup> only for MT & \*Z

<sup>3)</sup> not for MT & MM

Horse power / Torque control			
Code		Nominal HP at 1.500 rpm	
		Nominal HP at 1.500 rpm	Nominal torque
K		18.5 kW	120 Nm
M		22 kW	142 Nm
S		30 kW	195 Nm
T		37 kW	240 Nm
U		45 kW	290 Nm
W		55 kW	355 Nm
Y		75 kW	485 Nm
Z		90 kW	585 Nm
2		110 kW	700 Nm
Function			
L		Horse power control with pressure control <sup>4)</sup>	
C		Horse power control with load sensing (single spool)	
Z		Horse power control with two spool LS control	
Control variation			
	C	Standard version, integrated pilot valve <sup>1)</sup>	
	1	NG 6 interface top side	
	W	With unloading function, 24 VDC solenoid	
	K	Prop.-pilot valve type PVACRE...K35 mounted	
	Z	Without integrated pilot valve, NG6 interface, for mounting of accessory code PVAC* <sup>4)</sup>	
	B	Without integrated pilot valve, without NG6 interface <sup>1), 4)</sup>	
	P	*ZZ with mounted pilot valve PVAC1P <sup>2</sup>	
	F	Prop.-pilot valve PVACRE*35T with OBE mounted, command signal 0 - 10V	
	R	Prop.-pilot valve PVACRE*35T with OBE mounted, command signal 4 - 20 mA	

<sup>4)</sup> control variation Z and B without pressure pilot

Code		Control option	
Electro hydraulic control <sup>5)</sup>			
F	D	V	Proportional displacement control, no pressure compensation
U	D		Proportional displacement control, with pressure compensation
Control variation			
	R		pilot operated pressure control, open NG6 interface
	K		pilot operated pressure control, proportional pilot valve type PVACRE...K35 mounted
	M		pilot operated pressure control, pressure sensor and proportional pilot valve type PVACRE...K35 mounted for pressure control and/or power control

<sup>5)</sup> further info in MSG30-3254

# ORDERING CODE FRAME SIZE 5

P V  R 1 K 1 T 1 N

axial piston  
pump  
variable  
displace-  
ment

size and  
displacement

rotation

mounting  
interface

variation

through  
drive  
code

seals

coupling  
code

control

see next page

Code	Displacement	Size
270	270 cm <sup>3</sup> /rev	5

Code	Seals	Shaft seal
N	NBR	FKM
V	FKM	FKM
W	NBR	PTFE

Code	Rotation <sup>1)</sup>
R	Clockwise
L	Counter clockwise

<sup>1)</sup> When looked on shaft

Code	Variation
1	Standard
4	Electronic displacement sensor (CIP) <sup>2)</sup>
5	CIP-Sensor & Spec. adjustment <sup>3)</sup> (4 & 9)
9	Special adjustment <sup>3)</sup>

<sup>2)</sup> not for horse power control, mandatory  
with FDV/UD\*

<sup>3)</sup> requires Kxxxx number

Code	Mounting interface	Shaft
K	metr. ISO 3019/2	4-hole flange Ø200 mm
L		4-hole flange Ø200 mm
D	SAE ISO 3019/1	4-hole flange SAE E
E		4-hole flange SAE E

Code	Port <sup>4)</sup>	Threads <sup>5)</sup>
1	BSPP	metric
3	UNF	UNC
8	ISO 6149	metric

<sup>4)</sup> Drain and flushing ports

<sup>5)</sup> All mounting and connecting threads

Code	Coupling for through drive	as single part <sup>6)</sup>
1	Single pump, no coupling	
H	with coupling 25 x 1.5 x 15, DIN 5480	MK-PVBG5K01
J	with coupling 32 x 1.5 x 20, DIN 5480	MK-PVBG5K02
K	with coupling 40 x 1.5 x 25, DIN 5480	MK-PVBG5K03
L	with coupling 50 x 2 x 24, DIN 5480	MK-PVBG5K04
M	with coupling 60 x 2 x 28, DIN 5480	MK-PVBG5K05
Y	with coupling SAE A 9T-16/32 DP	MK-PVBG5K11
A	with coupling SAE 11T-16/32 DP	MK-PVBG5K12
B	with coupling SAE B 13T-16/32 DP	MK-PVBG5K13
C	with coupling SAE B-B 15T-16/32 DP	MK-PVBG5K14
D	with coupling SAE C 14T-12/24 DP	MK-PVBG5K15
E	with coupling SAE C-C 17T-12/24 DP	MK-PVBG5K16
F	with coupling SAE D, E 13T-8/16 DP	MK-PVBG5K17
G	with coupling SAE F 15T-8/16 DP	MK-PVBG5K18

Code	Through drive option
	No adaptor for 2nd pump
T	Single pump prepared for through drive
	with adaptor for 2nd pump
	as single part <sup>6)</sup>
A	SAE A-2, Ø 82.55 mm
B	SAE B-2/4, Ø 101.6 mm
C	SAE C-2/4, Ø 127 mm
D	SAE D-4, Ø 152.4 mm
E	SAE E-4, Ø 165.1 mm
J	metric, Ø 100 mm
K	metric, Ø 125 mm
L	metric, Ø 160 mm
M	metric, Ø 200 mm

See dimensions for details

<sup>6)</sup> to be ordered separately as single part  
see page 65.

Standard pump is not painted. Black painted pump and ATEX (excludes electronic components) certification (Zone 2) is available as special option. For additional informations please contact Parker Hannifin.

# ORDERING CODE FRAME SIZE 5

Code			Control options
0	0	1	No control
1	0	0	With cover plate, no control function (fixed displacement pump)
M	M		Standard pressure control
M	R		Remote pressure control
M	F		Load Sensing (flow) control
M	T		Two spool LS control
Control variation			
	C		Standard version, integrated pilot valve <sup>1)</sup>
	1		NG6 interface top side for pilot valves <sup>1)</sup>
	2		Remote pressure port int. supply , NG6 interface <sup>2)</sup>
	3		Remote pressure port ext. supply <sup>2)</sup>
	W		With unloading function, 24VDC solenoid <sup>1)</sup>
	K		Prop.-pilot valve type PVACRE...K35 mounted
	Z		Without integrated pilot valve, NG6 interface, for mounting of accessory code PVAC*
	B		Without integrated pilot valve, without NG6 interface <sup>3)</sup>
	P		MTZ with mounted pilot valve PVAC1P <sup>2)</sup>
	F		Prop.-pilot valve PVACRE*35T with OBE mounted, command signal 0 - 10 V
	R		Prop.-pilot valve PVACRE*35T with OBE mounted, command signal 4 - 20 mA

<sup>1)</sup> not for MT & \*Z

<sup>2)</sup> only for MT & \*Z

<sup>3)</sup> not for MT & MM

Horse power / Torque control			
Code		Nominal HP at 1.500 rpm	Nominal torque
T		37 kW	240 Nm
U		45 kW	290 Nm
W		55 kW	350 Nm
Y		75 kW	480 Nm
Z		90 kW	580 Nm
2		110 kW	700 Nm
3		132 kW	840 Nm
4		160 kW	1020 Nm
5		180 kW	1150 Nm
6		200 kW	1280 Nm
Function			
L		Horse power control with pressure control <sup>4)</sup>	
C		Horse power control with load sensing (single spool)	
Z		Horse power control with two spool LS control	
Control variation			
	C	Standard version, integrated pilot valve <sup>1)</sup>	
	1	NG 6 interface top side	
	W	With unloading function, 24 VDC solenoid	
	K	Prop.-pilot valve type PVACRE...K35 mounted	
	Z	Without integrated pilot valve, NG6 interface, for mounting of accessory code PVAC* <sup>4)</sup>	
	B	Without integrated pilot valve, without NG6 interface <sup>1), 4)</sup>	
	P	*ZZ with mounted pilot valve PVAC1P <sup>2)</sup>	
	F	Prop.-pilot valve PVACRE*35T with OBE mounted, command signal 0 - 10V	
	R	Prop.-pilot valve PVACRE*35T with OBE mounted, command signal 4 - 20mA	

<sup>4)</sup> control variation Z and B without pressure pilot

Code		Control option	
Electro hydraulic control <sup>5)</sup>			
F	D	V	Proportional displacement control, no pressure compensation
U	D		Proportional displacement control, with pressure compensation
Control variation			
	R		pilot operated pressure control, open NG6 interface
	K		pilot operated pressure control, proportional pilot valve type PVACRE...K35 mounted
	M		pilot operated pressure control, pressure sensor and proportional pilot valve type PVACRE...K35 mounted for pressure control and/or power control

<sup>5)</sup> further info in MSG30-3254

# ORDERING CODE FRAME SIZE 6

P	V				R	1	K	1	T	1	N			
axial piston pump					rotation		mounting interface		through drive code		seals		control	
variable displace- ment		size and displacement				variation		threads code		coupling code				see next page →
<b>Code</b>	<b>Displacement</b>	<b>Size</b>												
360	360 cm <sup>3</sup> /rev	6												
<b>Code</b>	<b>Rotation 1)</b>													
R	Clockwise													
L	Counter clockwise													
1) When looked on shaft														
<b>Code</b>	<b>Variation</b>													
1	Standard													
4	Electronic displacement sensor (CIP) <sup>2)</sup>													
5	CIP-Sensor & Spec. adjustment <sup>3)</sup> (4 & 9)													
9	Special adjustment <sup>3)</sup>													
2) not for horse power control, mandatory with FDV/UD*														
3) requires Kxxxx number														
<b>Code</b>	<b>Mounting interface</b>	<b>Shaft</b>												
K	metr. ISO 3019/2	4-hole flange Ø250 mm	Cylindric, key											
L		4-hole flange Ø250 mm	Splined, DIN 5480											
R		4-hole flange Ø224 mm	Cylindric, key											
T		4-hole flange Ø224 mm	Splined, DIN 5480											
D	SAE ISO 3019/1	4-hole flange SAE E	Cylindric, key											
E		4-hole flange SAE E	Splined, DIN 5480											
<b>Code</b>	<b>Port<sup>4)</sup></b>	<b>Threads<sup>5)</sup></b>												
1	BSPP	metric												
3	UNF	UNC												

4) Drain and flushing ports

5) All mounting and connecting threads

Code	Seals	Shaft seal
N	NBR	FKM
V	FKM	FKM

Code	Coupling for through drive	as single part <sup>6)</sup>
1	Single pump, no coupling	
H	with coupling 25 x 1.5 x 15, DIN 5480	MK-PVBG5K01
J	with coupling 32 x 1.5 x 20, DIN 5480	MK-PVBG5K02
K	with coupling 40 x 1.5 x 25, DIN 5480	MK-PVBG5K03
L	with coupling 50 x 2 x 24, DIN 5480	MK-PVBG5K04
M	with coupling 60 x 2 x 28, DIN 5480	MK-PVBG5K05
P	with coupling 70 x 3 x 22, DIN 5480	MK-PVBG5K06
Y	with coupling SAE A 9T-16/32 DP	MK-PVBG5K11
A	with coupling SAE 11T-16/32 DP	MK-PVBG5K12
B	with coupling SAE B 13T-16/32 DP	MK-PVBG5K13
C	with coupling SAE B-B 15T-16/32 DP	MK-PVBG5K14
D	with coupling SAE C 14T-12/24 DP	MK-PVBG5K15
E	with coupling SAE C-C 17T-12/24 DP	MK-PVBG5K16
F	with coupling SAE D, E 13T-8/16 DP	MK-PVBG5K17
G	with coupling SAE F 15T-8/16 DP	MK-PVBG5K18

Code	Through drive option
	No adaptor for 2nd pump
T	Single pump prepared for through drive
	with adaptor for 2nd pump as single part <sup>6)</sup>
A	SAE A-2, Ø 82.55 mm
B	SAE B-2/4, Ø 101.6 mm
C	SAE C-2/4, Ø 127 mm
D	SAE D-4, Ø 152.4 mm
E	SAE E-4, Ø 165.1 mm
J	metric, Ø 100 mm
K	metric, Ø 125 mm
L	metric, Ø 160 mm
M	metric, Ø 200 mm

See dimensions for details

6) to be ordered separately as single part  
see page 65.

Standard pump is not painted. Black painted pump and ATEX (excludes electronic components) certification (Zone 2) is available as special option. For additional informations please contact Parker Hannifin.

# ORDERING CODE FRAME SIZE 6

Code			Control options
0	0	1	No control
1	0	0	With cover plate, no control function (fixed displacement pump)
M	M		Standard pressure control
M	R		Remote pressure control
M	F		Load Sensing (flow) control
M	T		Two spool LS control
Control variation			
	C		Standard version, integrated pilot valve <sup>1)</sup>
	1		NG6 interface top side for pilot valves <sup>1)</sup>
	2		Remote pressure port int. supply , NG6 interface <sup>2)</sup>
	3		Remote pressure port ext. supply <sup>2)</sup>
	W		With unloading function, 24VDC solenoid <sup>1)</sup>
	K		Prop.-pilot valve type PVACRE...K35 mounted
	Z		Without integrated pilot valve, NG6 interface, for mounting of accessory code PVAC*
	B		Without integrated pilot valve, without NG6 interface <sup>3)</sup>
	P		MTZ with mounted pilot valve PVAC1P <sup>2)</sup>
	F		Prop.-pilot valve PVACRE*35T with OBE mounted, command signal 0 - 10V
	R		Prop.-pilot valve PVACRE*35T with OBE mounted, command signal 4 - 20 mA

<sup>1)</sup> not for MT & \*Z<sup>2)</sup> only for MT & \*Z<sup>3)</sup> not for MT & MM

Horse power / Torque control			
Code		Nominal HP at 1.500 rpm	
		Nominal HP at 1.500 rpm	Nominal torque
U		45 kW	290 Nm
W		55 kW	350 Nm
Y		75 kW	480 Nm
Z		90 kW	580 Nm
2		110 kW	700 Nm
3		132 kW	840 Nm
4		160 kW	1020 Nm
5		180 kW	1150 Nm
6		200 kW	1280 Nm
Function			
L		Horse power control with pressure control <sup>4)</sup>	
C		Horse power control with load sensing (single spool)	
Z		Horse power control with two spool LS control	
Control variation			
	C	Standard version, integrated pilot valve <sup>1)</sup>	
	1	NG 6 interface top side for pilot valve	
	W	With unloading function, 24 VDC solenoid	
	K	Prop.-pilot valve type PVACRE...K35 mounted	
	Z	Without integrated pilot valve, NG6 interface, for mounting of accessory code PVAC* <sup>4)</sup>	
	B	Without integrated pilot valve, without NG6 interface <sup>1), 4)</sup>	
	P	*ZZ with mounted pilot valve PVAC1P <sup>2)</sup>	
	F	Prop.-pilot valve PVACRE*35T with OBE mounted, command signal 0 - 10V	
	R	Prop.-pilot valve PVACRE*35T with OBE mounted, command signal 4 - 20 mA	

**Remark:**

As torque is pretty much speed independent power at alternative speeds can get recalculated to 1500 rpm for code selection easily.

**Example:**

Your engine allows 90 kW @ 1800 rpm →  $\frac{90 \text{ kW}}{1800 \text{ rpm}} \times 1500 \text{ rpm} = 75 \text{ kW}$

→ select a first digit "Y" -control.

<sup>4)</sup> control variation Z and B without pressure pilot

<sup>5)</sup> further info in MSG30-3254

Code			Control option
			Electro hydraulic control <sup>5)</sup>
F	D	V	Proportional displacement control, no pressure compensation
U	D		Proportional displacement control, with pressure compensation
Control variation			
	R		pilot operated pressure control, open NG6 interface
	K		pilot operated pressure control, proportional pilot valve type PVACRE...K35 mounted
	M		pilot operated pressure control, pressure sensor and proportional pilot valve type PVACRE...K35 mounted for pressure control and/or power control

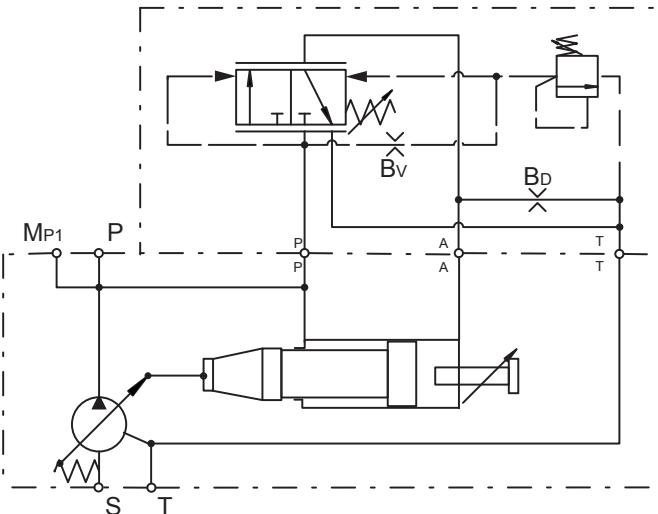
# PRESSURE CONTROLS

## Standard Pressure Control

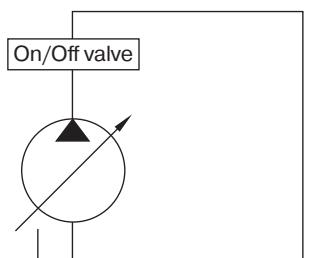
## Control option MMC

The standard pressure control adjusts the pump displacement according to the actual need of flow in the system in order to keep the pressure constant.

## Control schematics



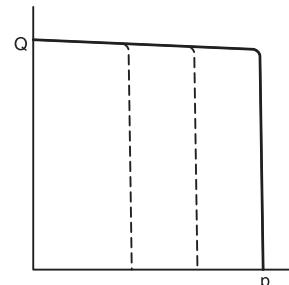
Response times of the pump are collected from a circuit as below by measuring the pumps swash angle movement at different pressures.



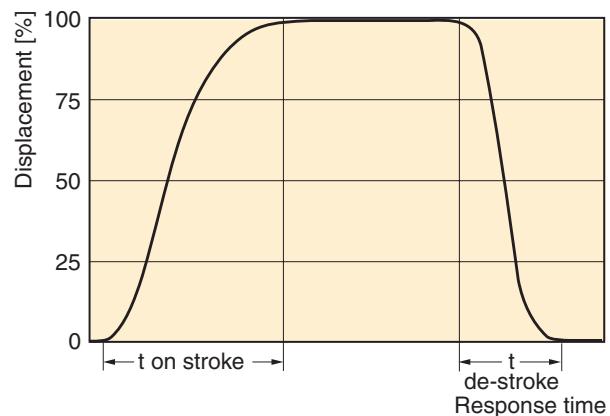
	Time on-stroke [ms]		Time de-stroke [ms]	
	against 50 bar	against 350 bar	zero stroke 50 bar	zero stroke 350 bar
PV360	520	180	120	82

Pressure adjustment range	15 to 420 bar
Factory setting pressure	50 bar
Differential pressure adjustment range	10 to 40 bar
Factory setting differential pressure	15 bar
Control oil consumption	Max 8.0 l/min
Typical pilot flow	approx 1.5 l/min

**Note:** Upgrade to the MRC control by simply removing the ISO 6149 M14x1.5-plug. Thread adapters PVCK\*\* (last two digits defining seal and thread) are available separately if required. PVCKN1 for ex. for NBR-sealed and towards G1/4 BSPP. Please consult spares list for all further versions.



## Dynamic characteristic of flow control \*



\* Curve shown exaggerated

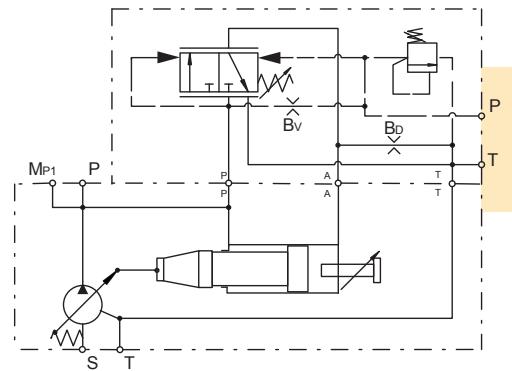
# PRESSURE CONTROLS

## Standard Pressure Control with NG6 Interface

### Control option MM1

With code MM1 the standard pressure control has a valve interface size NG 6 DIN 24340 (CETOP 03 acc. RP35H, NFPA D03) on the top side.

This interface allows the mounting of accessories like multiple pressure selectors without the need of external piping and valve mounting.

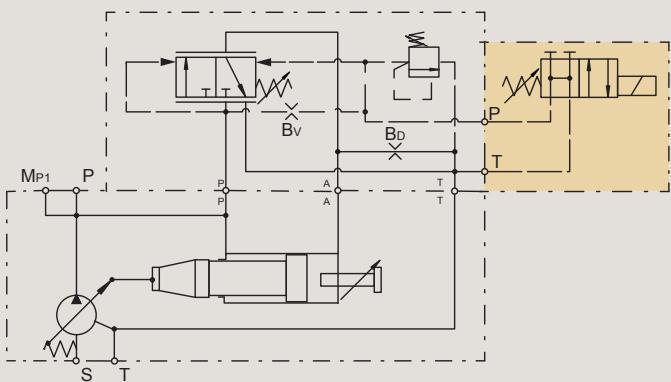


## Standard Pressure Control with Electrical Unloading

### Control option MMW

With code MMW a solenoid operated directional control valve (D1VW002KNJW) for electrical unloading is mounted on the control top side.

When the solenoid is de-energised, the pump compensates at a stand-by pressure of typically 15 bar. When the solenoid is energised, the pump compensates at the pressure adjusted on the integrated pilot valve.

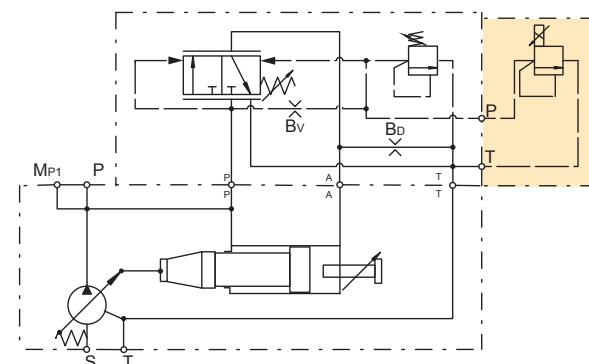


## Standard Pressure Control with Proportional Pilot Valve

### Control option MMK

With code MMK a proportional pilot valve of type PVACRE... K35 (see page 43) is mounted on the top side interface.

This allows a variation of the pump compensating pressure between 20 and 350 bar by an electrical signal.



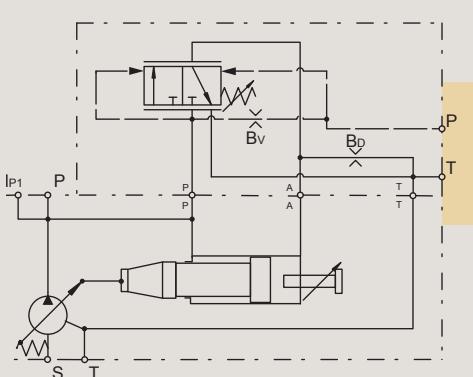
## Standard Pressure Control without Integrated Pressure Pilot Valve

### Control option MMZ

Control MMZ has no integrated pilot valve but a valve interface NG6 DIN 24340 on the top.

This version is recommended for valve accessories.

For operation at >350 bar please select respective valve accessories (see page 40)



# PRESSURE CONTROLS

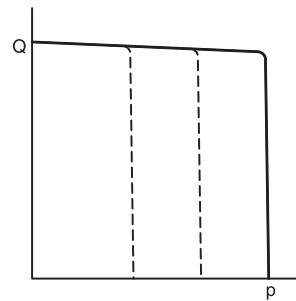
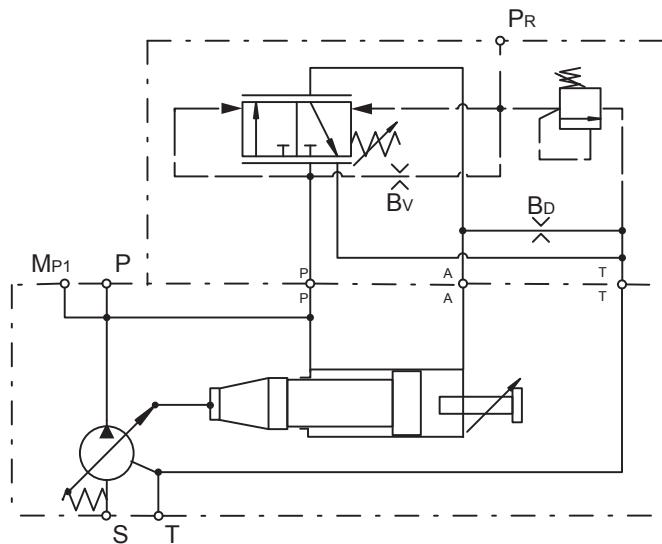
## Remote Pressure Control

### Control option MRC

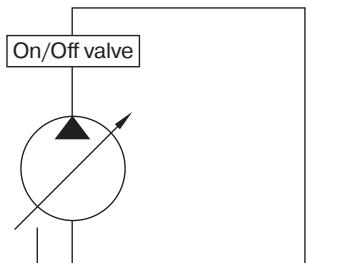
The remote pressure control adjusts the pump displacement according to the actual need of flow in the system

in order to keep the pressure constant at a level given by a remotely installed pilot valve.

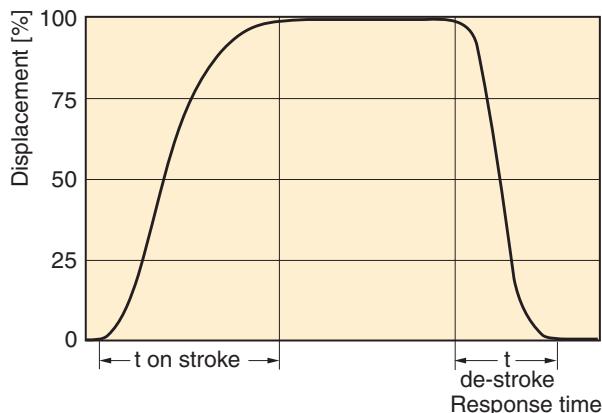
### Control schematics



Response times of the pump are collected from a circuit as below by measuring the pumps swash angle movement at different pressures.



### Dynamic characteristic of flow control \*



\* Curve shown exaggerated

	Time on-stroke [ms]	Time de-stroke [ms]
	against 50 bar	against 350 bar
PV360	520	180
	zero stroke 50 bar	zero stroke 350 bar
	120	82

Pressure adjustment range	15 to 420 bar
Factory setting pressure	50 bar
Differential pressure adjustment range	10 to 40 bar
Factory setting differential pressure	15 bar
Control oil consumption	Max 8.0 l/min
Typical pilot flow	approx 1.5 l/min

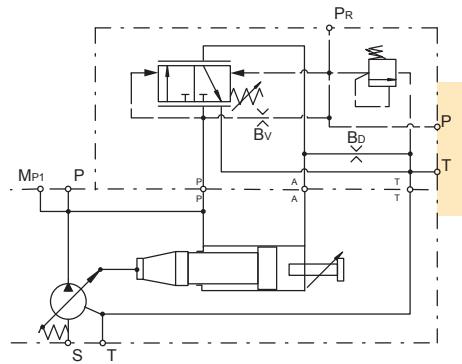
# PRESSURE CONTROLS

## Remote Pressure Control with NG6 Interface

### Control option MR1

With code MR1 the remote pressure control has a valve interface size NG 6 DIN 24340 (CETOP 03 acc. RP35H, NFPA D03) on the top side.

This interface allows the mounting of accessories like multiple pressure selectors without the need of external piping and valve mounting.

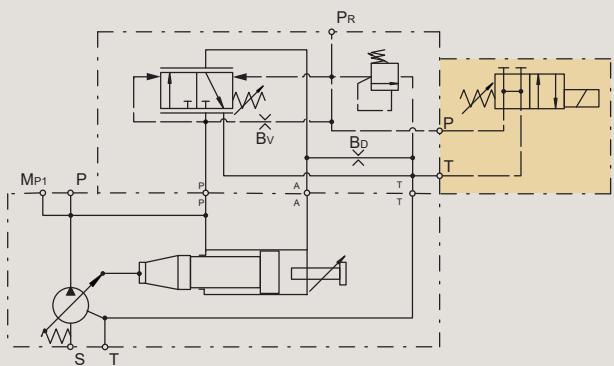


## Remote Pressure Control with Electrical Unloading

### Control option MRW

With code MRW a solenoid operated directional control valve (D1VW002KNJW) for electrical unloading is mounted on the control top side.

When the solenoid is de-energised, the pump compensates at a stand-by pressure of typically 15 bar. When the solenoid is energised, the pump compensates at the pressure adjusted on the integrated pilot valve.

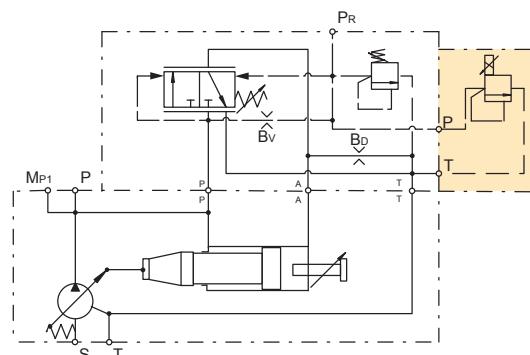


## Remote Pressure Control with Proportional Pilot Valve

### Control option MRK

With code MRK a proportional pilot valve of type PVACRE...K35 (see page 43) is mounted on the top side interface.

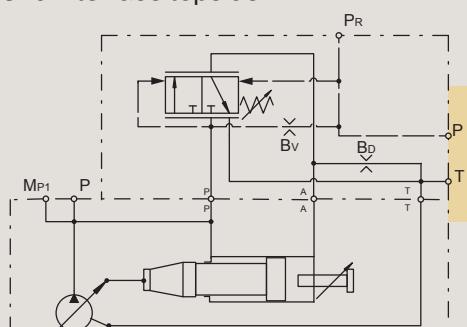
This allows a variation of the pump compensating pressure between 20 and 350 bar by an electrical signal.



## Remote Pressure Control without Integrated Pressure Pilot Valve

### Control option MRZ

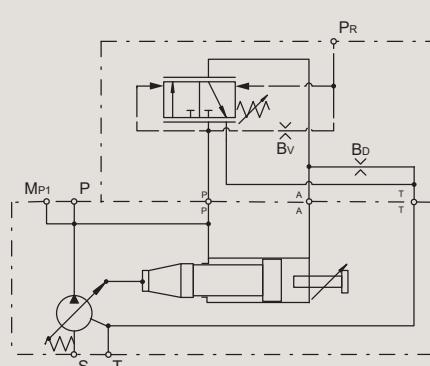
Control MRZ has no integrated pilot valve but a NG 6 DIN 24340 interface topside.



This version is recommended for valve accessories.

### Control option MRB

Control MRB has no integrated pilot valve.



# LOAD SENSING CONTROLS

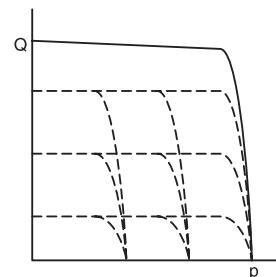
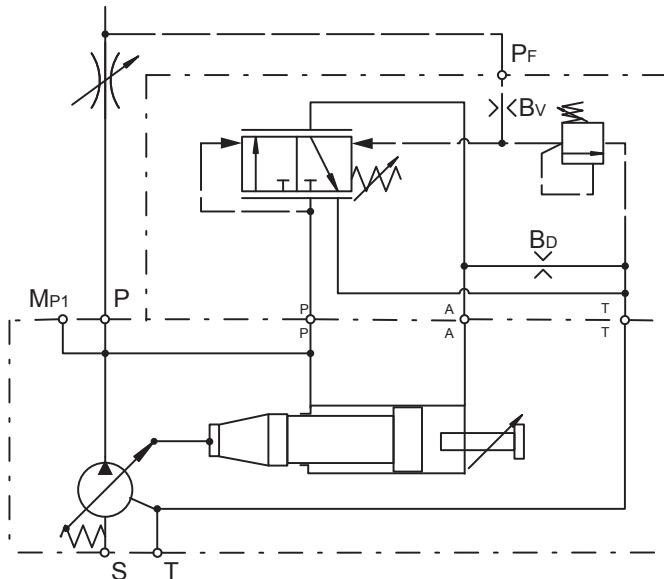
## Load Sensing Control

### Control option MFC

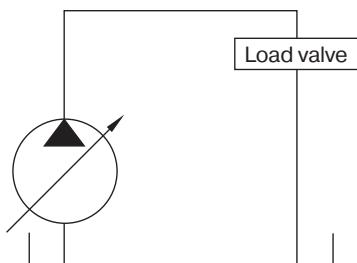
The pilot pressure of the load sensing control is taken from a load sensing port in the hydraulic system. It is

used to match pump flow to system demands. Integrated pilot valve allows  $p_{max}$  adjustment.

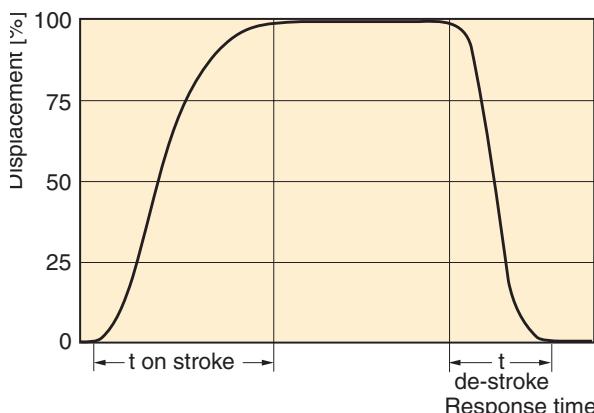
### Control schematics



Response times of the pump are collected from a circuit as below by measuring the pumps swash angle movement at different pressures.



### Dynamic characteristic of flow control \*



\* Curve shown exaggerated

	Time on-stroke [ms]	Time de-stroke [ms]
	stand-by to 50 bar	stand-by to 350 bar
PV360	500	690
	50 bar to stand-by	350 bar to stand-by
	830	50

Pressure adjustment range	15 to 420 bar
Factory setting pressure	50 bar
Differential pressure adjustment range	10 to 40 bar
Factory setting differential pressure	10 bar
Control oil consumption	Max 8.0 l/min
Typical pilot flow	approx 1.5 l/min

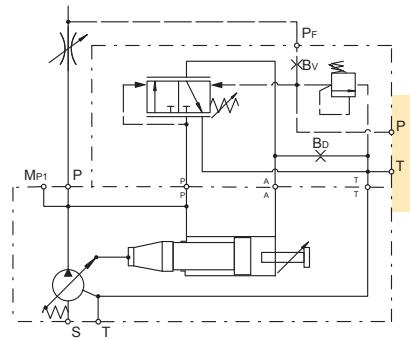
# LOAD SENSING CONTROLS

## Load Sensing Control with NG6 Interface

### Control option MF1

With code MF1 the remote pressure control has a valve interface size NG 6 DIN 24340 (CETOP 03 acc. RP35H, NFPA D03) on the top side.

This interface allows the mounting of accessories like multiple pressure selectors without the need of external piping and valve mounting.

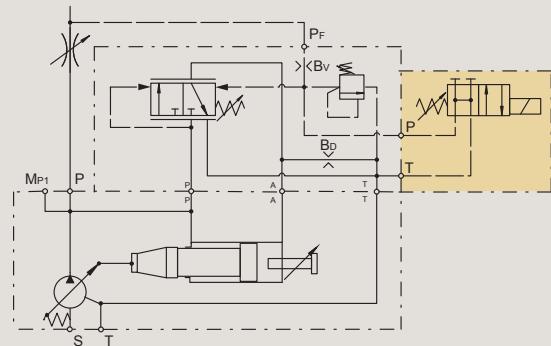


## Load Sensing Control with Electrical Unloading

### Control option MFW

With code MFW a solenoid operated directional control valve (D1VW002KNJW) for electrical unloading is mounted on the control top side.

When the solenoid is de-energised, the pump compensates at a stand-by pressure of typically 15 bar. When the solenoid is energised, the pump compensates at the pressure adjusted on the integrated pilot valve.

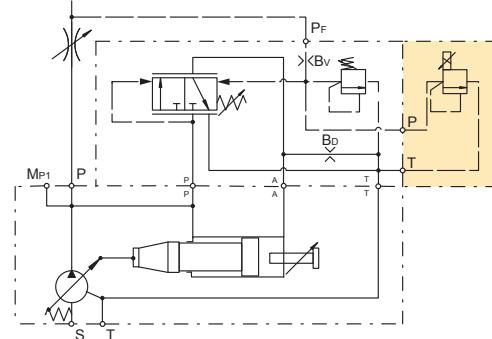


## Load Sensing Control with Proportional Pilot Valve

### Control option MFK

With code MFK a proportional pilot valve of type PVACRE...K35 (see page 43) is mounted on the top side interface.

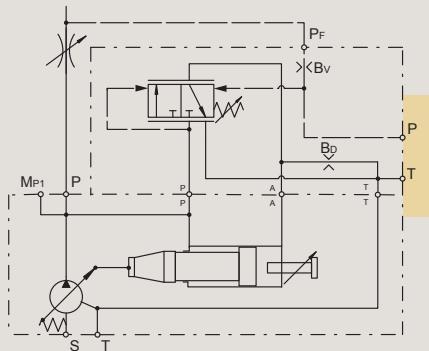
This allows a variation of the pump compensating pressure between 20 and 350 bar by an electrical signal.



## Load Sensing Control without Integrated Pressure Pilot Valve

### Control option MFZ

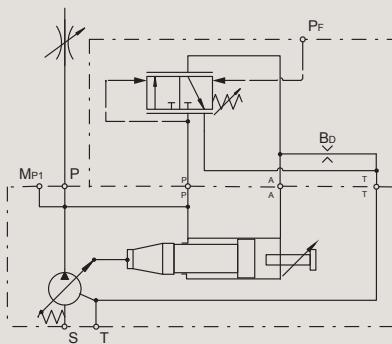
Control MFZ has no integrated pilot valve but a NG6 DIN 24340 interface topside.



This version is recommended for valve accessories.

### Control option MFB

Control MFB has no integrated pilot valve.



# LOAD SENSING CONTROLS

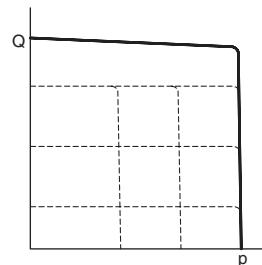
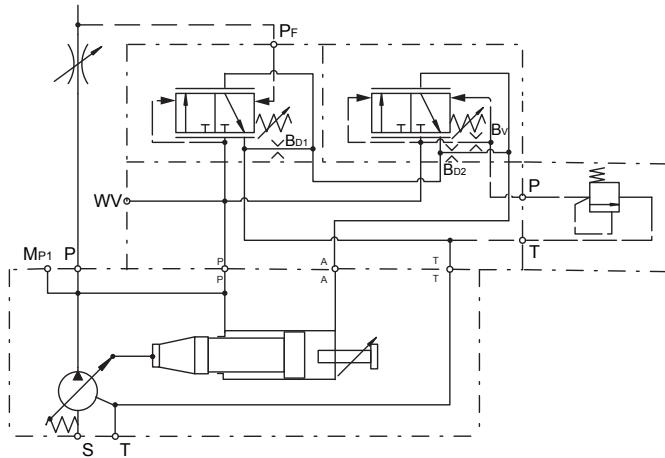
## 2 Spool Load Sensing Control

### Control option MTP

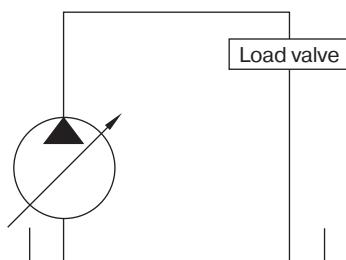
The pilot pressure of the load sensing control is taken from a load sensing port in the hydraulic system. It is used to match pump flow to system demands. With the 2

spool control the interaction of the two control functions is avoided by using two separate control valves for flow and pressure compensation.

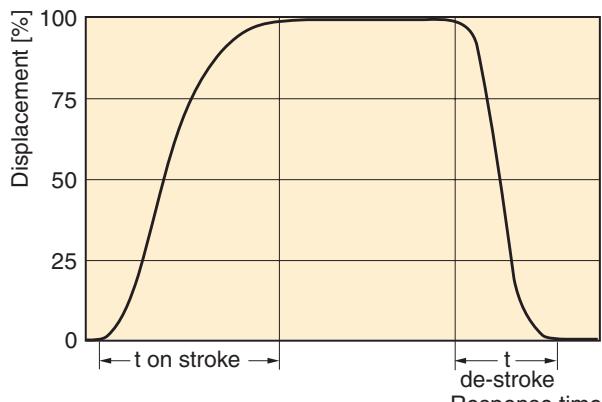
### Control schematics



Response times of the pump are collected from a circuit as below by measuring the pumps swash angle movement at different pressures.



### Dynamic characteristic of flow control \*



\* Curve shown exaggerated

	Time on-stroke [ms]	Time de-stroke [ms]
stand-by to 50 bar	920	670
stand-by to 350 bar	1000	170

Pressure adjustment range	15 to 420 bar
Factory setting pressure	50 bar
Differential pressure adjustment range	10 to 40 bar
Factory setting differential pressure load sensing	10 bar
Factory setting differential pressure, pressure control	15 bar
Control oil consumption	Max 8.0 l/min
Typical pilot flow	approx 1.5 l/min

# LOAD SENSING CONTROLS

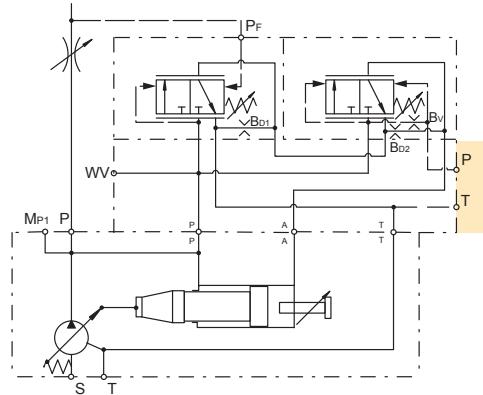
## 2 Spool Load Sensing Control with NG6 Interface without Integrated Pressure Pilot Valve

### Control option MTZ

Control MTZ has no integrated pressure pilot valve but NG 6 DIN 24340 (CETOP 03 acc. RP35H, NFPA D03) on the top side.

This interface allows the mounting of accessories like multiple pressure selectors without the need of external piping and valve mounting.

**Note:** The MT1 control option is not available for new releases as is it identical to the MTZ control.

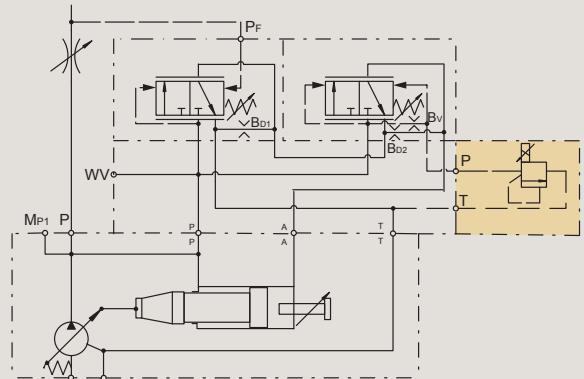


## 2 Spool Load Sensing Control with Proportional Pilot Valve

### Control option MTK

With code MTK a proportional pilot valve of type PVACRE...K35 (see page 43) is mounted on the top side interface.

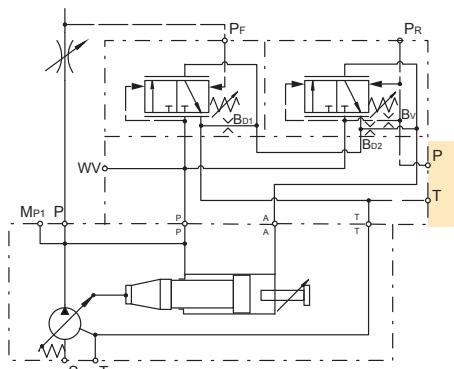
This allows a variation of the pump compensating pressure between 20 and 350 bar by an electrical signal.



## 2 Spool Load Sensing Control without Integrated Pressure Pilot Valve

### Control option MT2

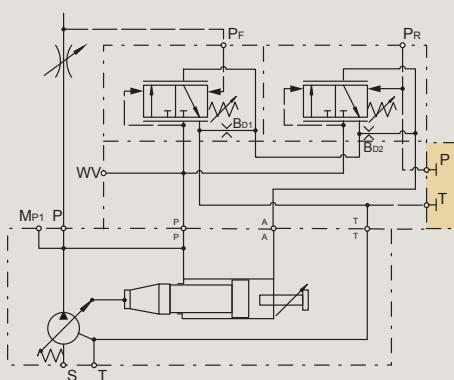
Control MT2 has a valve interface NG6 DIN 24340 on the top side and remote pressure port internal supply.



## 2 Spool Load Sensing Control without Integrated Pressure Pilot Valve

### Control option MT3

Control MT3 with pressure remote port external supply. Incl. closed NG6-pad.



# HORSE POWER/TORQUE CONTROLS

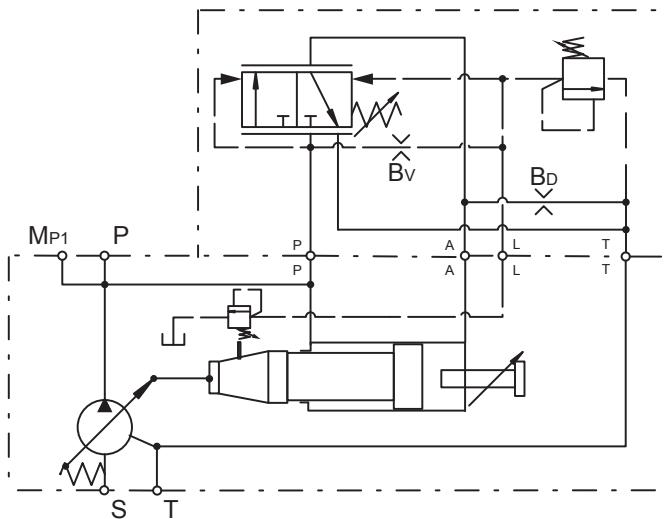
## Horse Power/Torque Controls with Pressure Control

### Control option \*LC

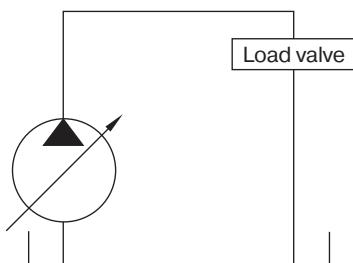
The horse power control type \*L\* provides the benefit of the pressure control, plus the ability to limit the input power the pump will draw. These controls are beneficial when the power available from the prime mover for the

hydraulics is limited or the application power demand has both high flow/low pressure and low flow/high pressure duty cycles.

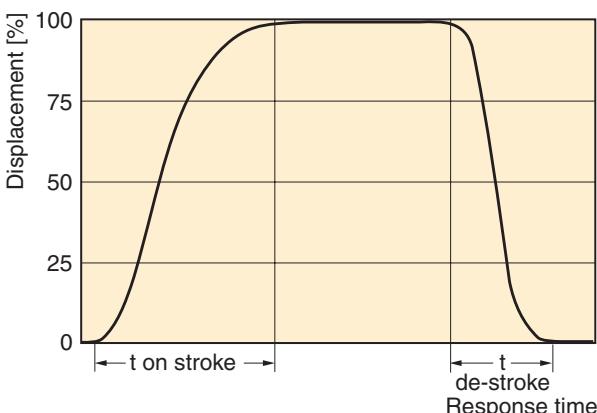
### Control schematics



Response times of the pump are collected from a circuit as below by measuring the pumps swash angle movement at different pressures.



### Dynamic characteristic of flow control \*



\* Curve shown exaggerated

	Time on-stroke [ms]	Time de-stroke [ms]
	against 50 bar	against 350 bar
PV360	90	90

See Horse Power characteristic curves on page 30

Pressure adjustment range	15 to 350 bar
Factory setting pressure	350 bar
Differential pressure adjustment range	10 to 40 bar
Factory setting differential pressure	15 bar
Control oil consumption	Max 8.0 l/min
Typical pilot flow	approx 1.5 l/min

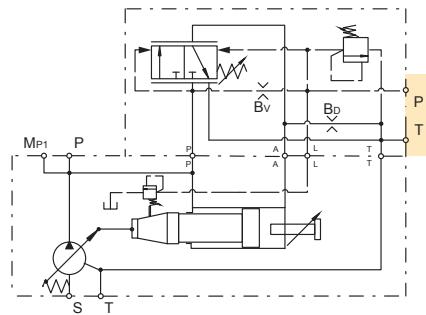
# HORSE POWER/TORQUE CONTROLS

## Horse Power/Torque Control with NG6 Interface

## Control option \*L1

With code \*L1 the horse power control has a valve interface size NG 6 DIN 24340 (CETOP 03 acc. RP35H, NFPA D03) on the top side.

This interface allows the mounting of accessories like multiple pressure selectors without the need of external piping and valve mounting.

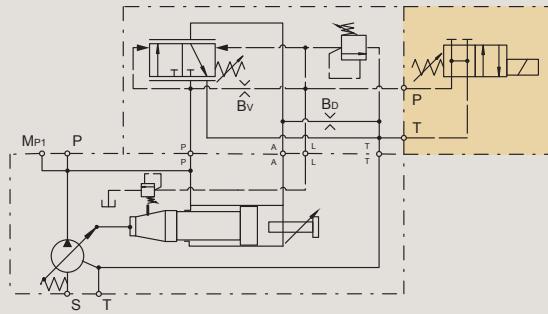


## Horse Power/Torque Control with Electrical Unloading

## Control option \*LW

With code \*LW a solenoid operated directional control valve (D1VW002KNJW) for electrical unloading is mounted on the control top side.

When the solenoid is de-energised, the pump compensates at a stand-by pressure of typically 15 bar. When the solenoid is energised, the pump compensates at the pressure adjusted on the integrated pilot valve.

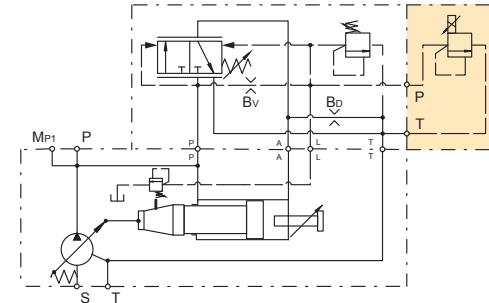


## Horse Power/Torque Control with Proportional Pilot Valve

## Control option \*LK

With code \*LK a proportional pilot valve of type PVACRE...K35 (see page 43) is mounted on the top side interface.

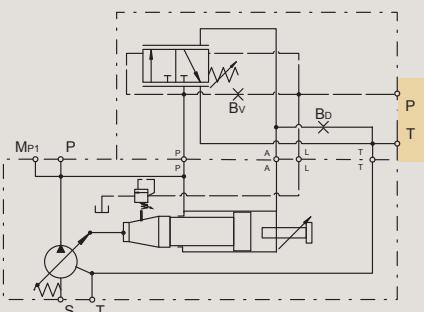
This allows a variation of the pump compensating pressure between 20 and 350 bar by an electrical signal.



## **Horse Power/Torque Control without Integrated Pressure Pilot Valve**

## Control option \*LZ

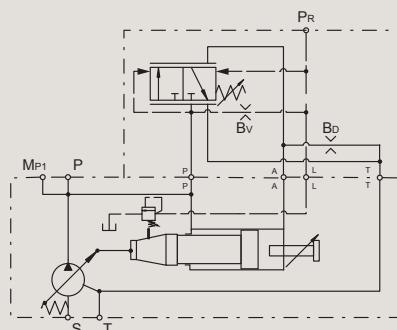
Control \*LZ has no integrated pilot valve but a NG6 DIN 24340 interface topside.



This version is recommended for valve accessories.

## Control option \*LB

Control \*LB has no integrated pilot valve.



# HORSE POWER/TORQUE CONTROLS

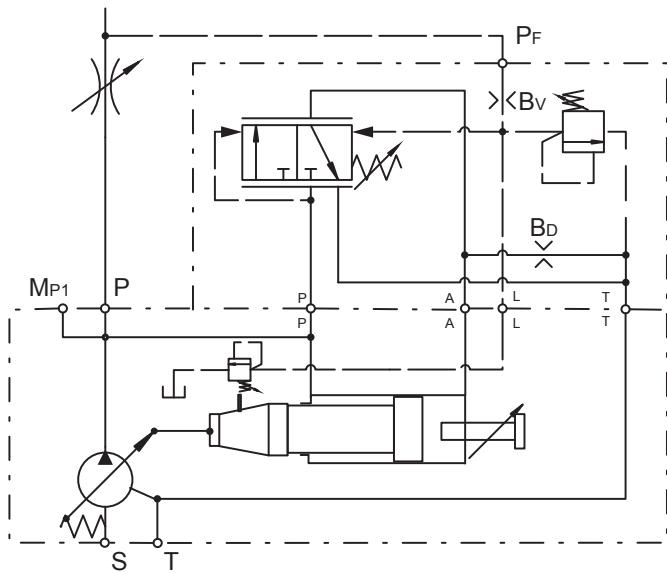
## Horse Power/Torque Controls with Load Sensing

### Control option \*CC

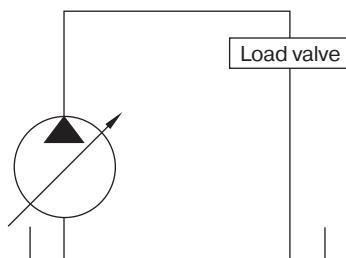
The horse power control type \*C\* provides the benefit of the load sensing control, plus the ability to limit the input power the pump will draw. These controls are beneficial when the power available from the prime mover for the

hydraulics is limited or the application power demand has both high flow/low pressure and low flow/high pressure duty cycles.

### Control schematics



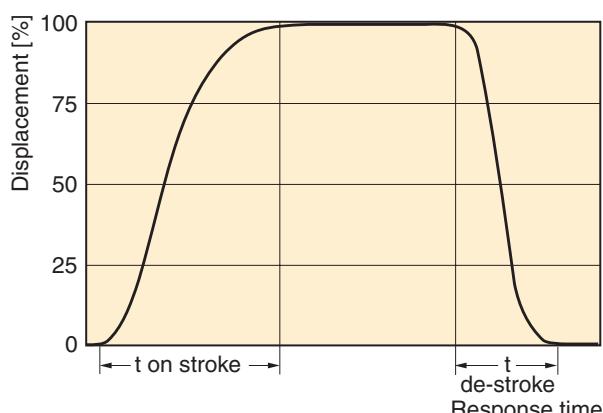
Response times of the pump are collected from a circuit as below by measuring the pumps swash angle movement at different pressures.



	Time on-stroke [ms]	Time de-stroke [ms]	
	stand-by to 50 bar	stand-by to 350 bar	50 bar to stand-by
PV360	90	90	350 bar to stand-by

Pressure adjustment range	15 to 350 bar
Factory setting pressure	350 bar
Differential pressure adjustment range	10 to 40 bar
Factory setting differential pressure	15 bar
Control oil consumption	Max 8.0 l/min
Typical pilot flow	approx 1.5 l/min

### Dynamic characteristic of flow control \*



\* Curve shown exaggerated

See Horse Power characteristic curves on page 30

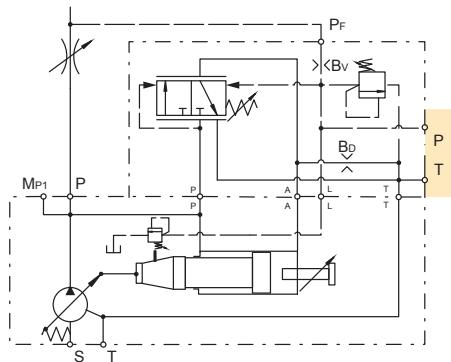
# HORSE POWER/TORQUE CONTROLS

## Horse Power/Torque Control with Load Sensing & NG6 Interface

### Control option \*C1

With code \*C1 the horse power control has a valve interface size NG 6 DIN 24340 (CETOP 03 acc. RP35H, NFPA D03) on the top side.

This interface allows the mounting of accessories like multiple pressure selectors without the need of external piping and valve mounting.

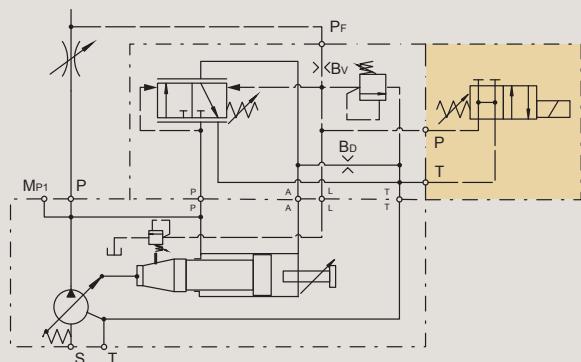


## Horse Power/Torque Control with Load Sensing & Electrical Unloading

### Control option \*CW

With code \*CW a solenoid operated directional control valve (D1VW002KNJW) for electrical unloading is mounted on the control top side.

When the solenoid is de-energised, the pump compensates at a stand-by pressure of typically 15 bar. When the solenoid is energised, the pump compensates at the pressure adjusted on the integrated pilot valve.

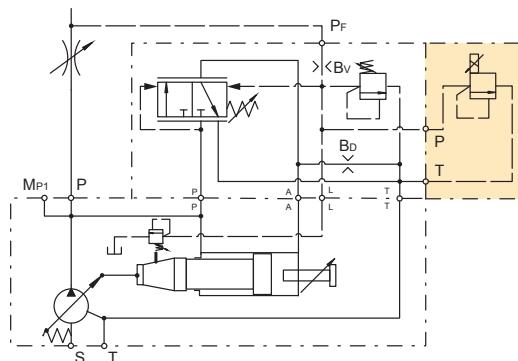


## Horse Power/Torque Control with Load Sensing & Proportional Valve

### Control option \*CK

With code \*CK a proportional pilot valve of type PVACRE...K35 (see page 43) is mounted on the top side interface.

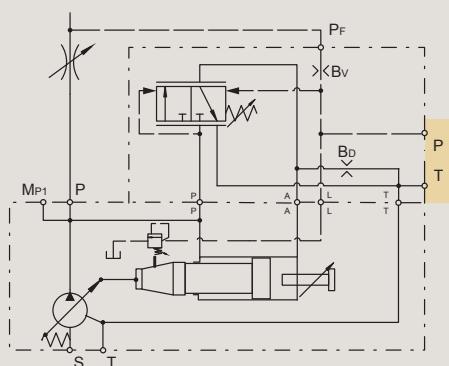
This allows a variation of the pump compensating pressure between 20 and 350 bar by an electrical signal.



## Horse Power/Torque Control with Load Sensing without Integrated Pilot Valve

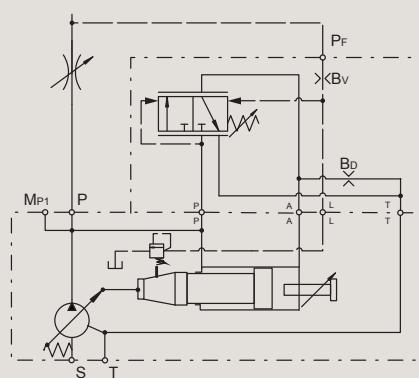
### Control option \*CZ

Control \*CZ has no integrated pilot valve but NG6 DIN 24340 interface topside.



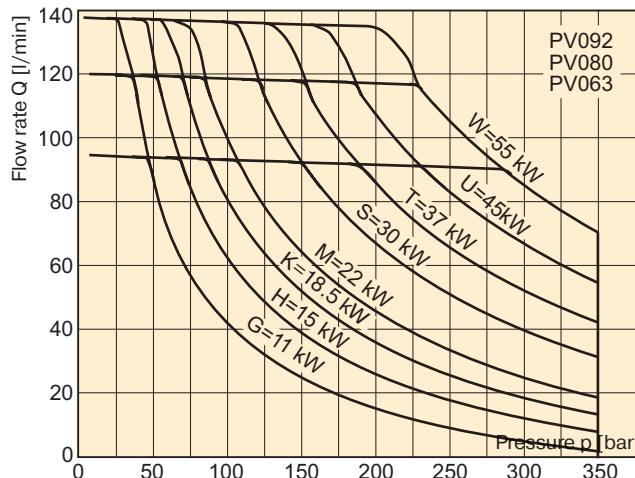
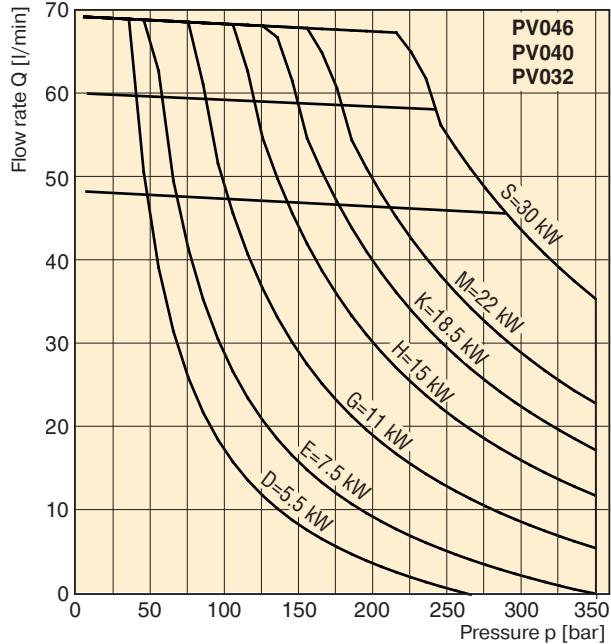
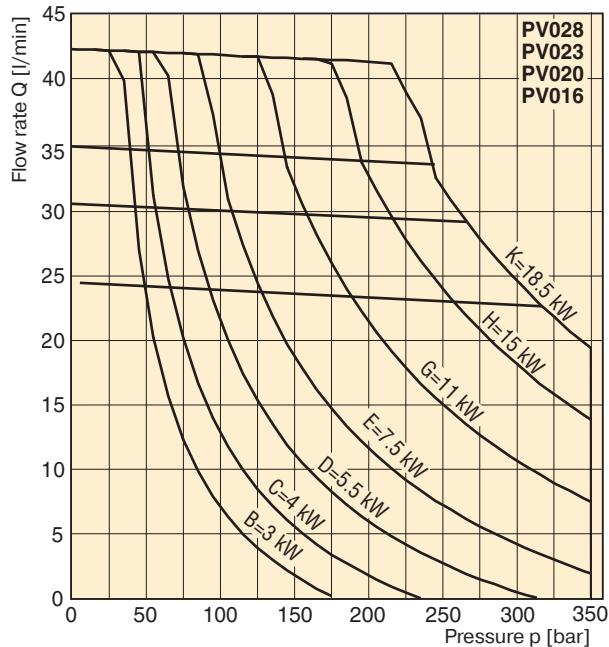
### Control option \*CB

Control \*CB has no integrated pilot valve.



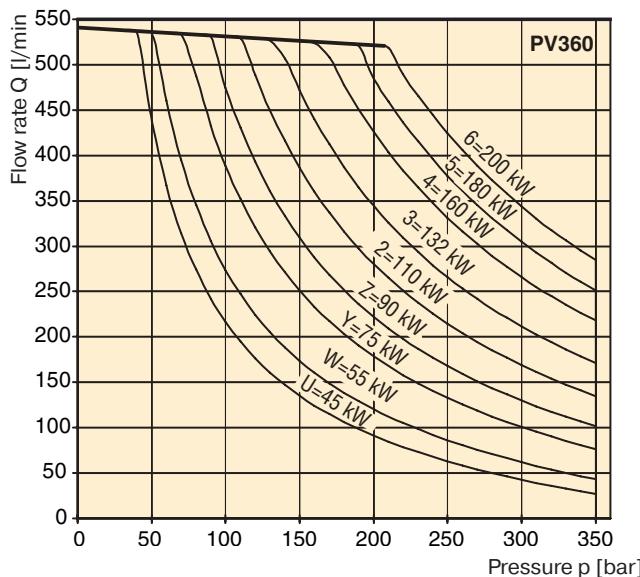
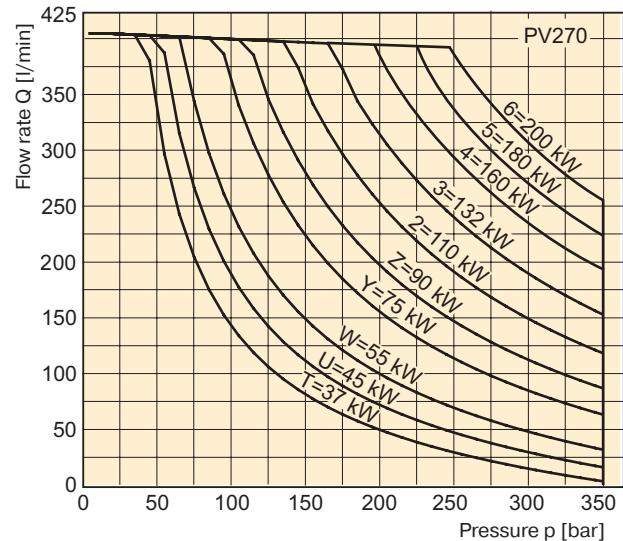
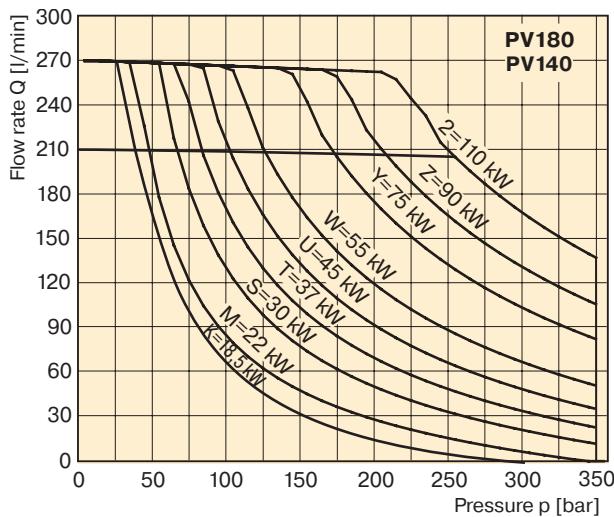
# PERFORMANCE CURVES

## Typical Horse Power/Torque Control Characteristics



# PERFORMANCE CURVES

## Typical Horse Power/Torque Control Characteristics



Speed :  $n = 1500$  rev/min  
 Temperature :  $t = 50^\circ\text{C}$   
 Fluid : HLP, ISO VG46  
 Viscosity :  $\nu = 46 \text{ mm}^2/\text{s}$  at  $40^\circ\text{C}$   
 Pressure : Maximum 350 bar, depending on HP level

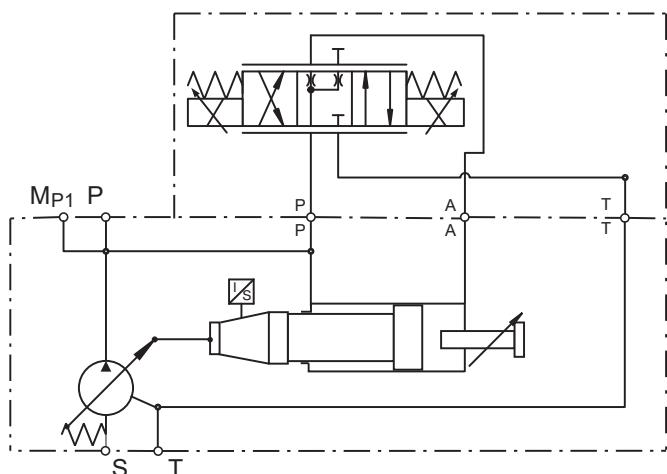
# ELECTRONIC P/Q CONTROLS

## Proportional Displacement Control

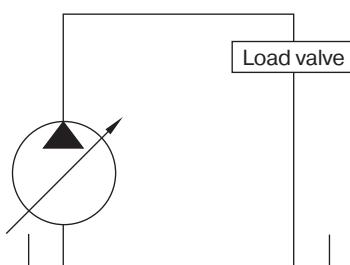
### Control option FDV

The proportional displacement control allows the adjustment of the pump's output flow by an electrical input signal. The actual displacement of the pump is monitored by an electronic displacement sensor and compared with the commanded displacement in an electronic control module PQDXXA-Z10. The command is given as an electrical input signal (0 – 10 V alternatively 4 – 20 mA) from the supervising machine control or a potentiometer.

### Control schematics



Response times of the pump are collected from a circuit as below by measuring the pumps swash angle movement at different pressures.

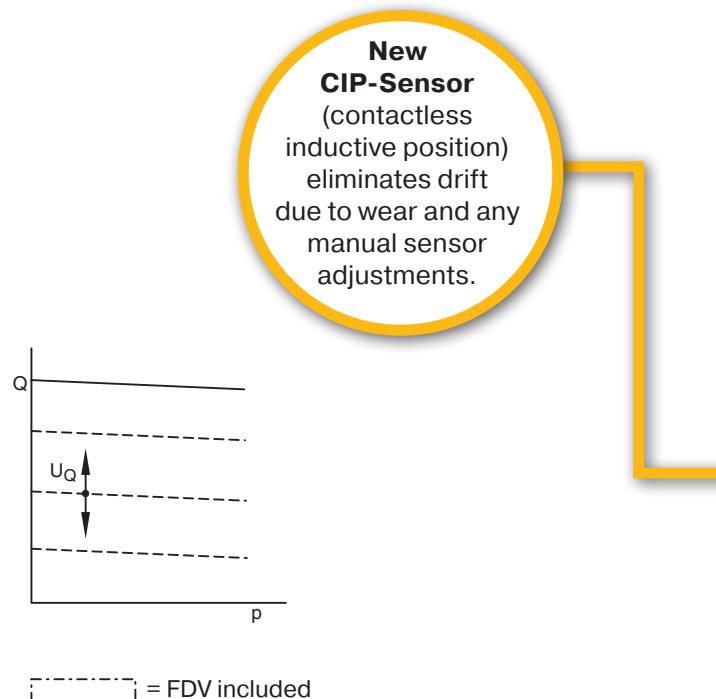


	Time on-stroke [ms]	Time de-stroke [ms]
	stand-by to 50 bar	stand-by to 350 bar
PV360	255	154

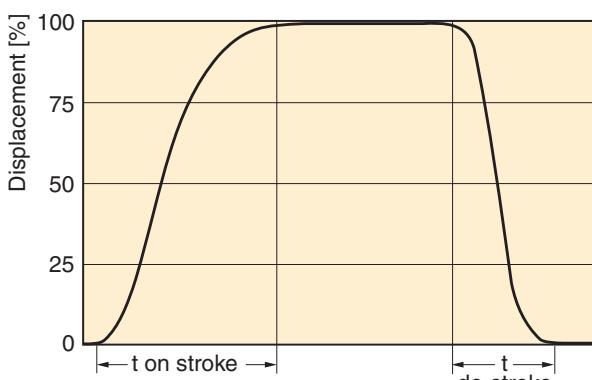
Pressure adjustment range*	35 to 350 bar
Differential pressure adjustment range *	10 to 40 bar
Factory setting differential pressure *	15 bar
Control oil consumption (FDV only)	Max 0.3 l/min

\* Data valid for UD\* version

Version FDV of the proportional control does not provide pressure compensation. Therefore the hydraulic circuit must be protected by a pressure relief valve.



### Dynamic characteristic of flow control \*



\* Curve shown exaggerated

Internal pilot pressure required to control the pump	
FDV	15 bar
UDR	25 bar
UDK	25 bar
UDM	25 bar

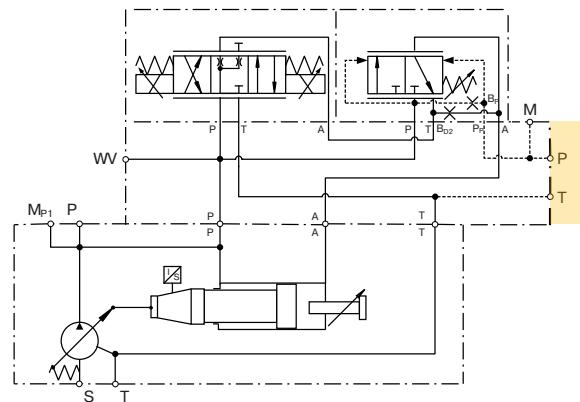
# ELECTRONIC P/Q CONTROLS

## Proportional Displacement Control with Overriding Pressure Control

### Control option UDR without pressure relief pilot valve

Control version UDR provides electro-hydraulic displacement control and pressure stage mounted on an elbow manifold.

The elbow manifold provides NG6/D03 interface on top to mount a pressure pilot valve (not included in UDR).

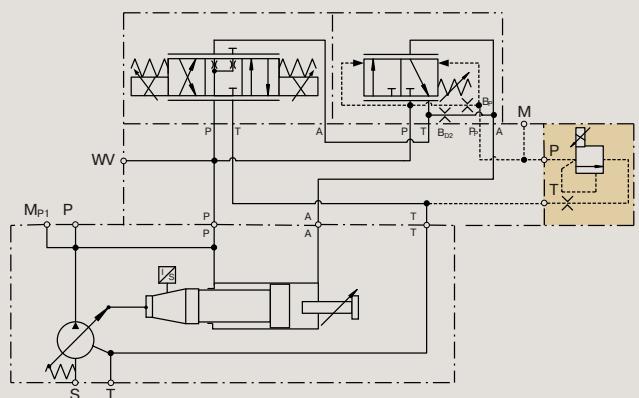


## Proportional Displacement Control with Proportional Pressure Control

### Control option UDK

Control version UDK features proportional pressure pilot valve PVACRE...K35, which enables for electro-hydraulic p/Q control.

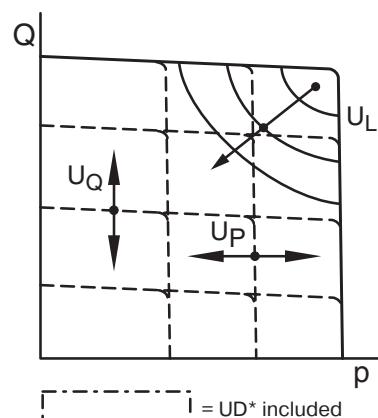
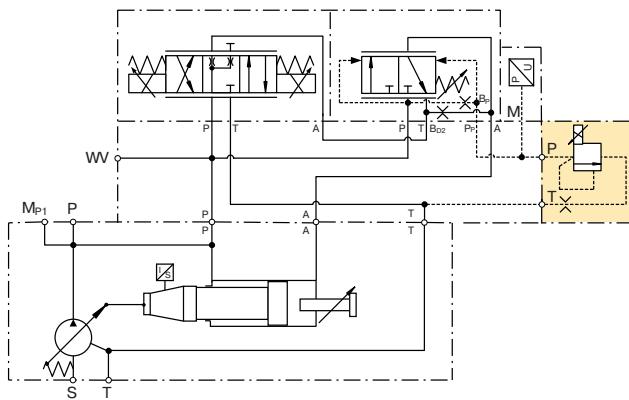
By using the digital module PQDXXA-Z10 it is possible to control the displacement proportionally with overriding open loop proportional pressure control.



## Proportional Displacement Control with Closed Loop Pressure Control

### Control option UDM

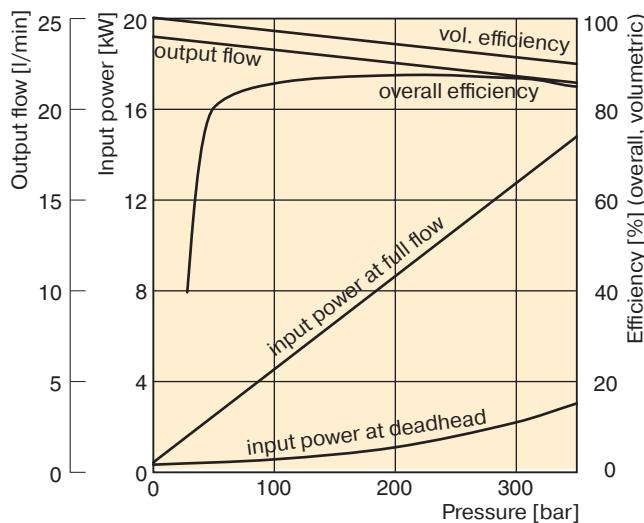
Control version UDM includes pressure transducer Parker SCP 8181 CE. In combination with control module PQDXXA-Z10 both closed loop pressure control as well as electronic power limitation can be realized.



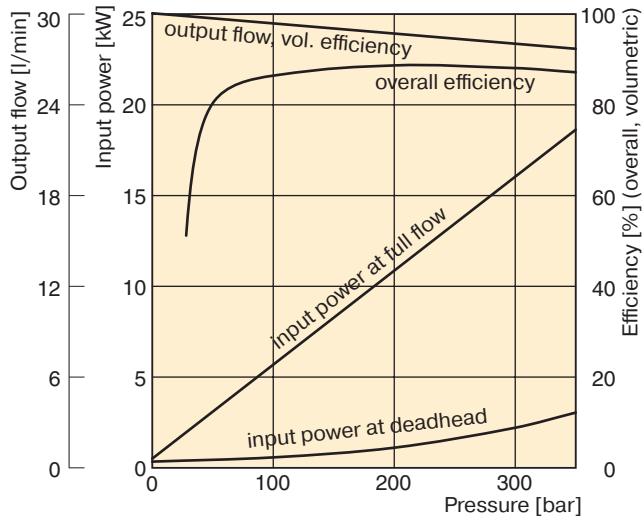
# EFFICIENCY & CASE DRAIN FLOWS

## Efficiency, power consumption

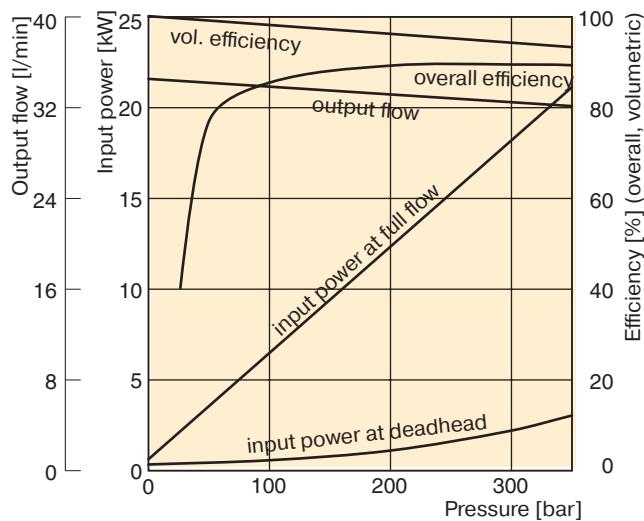
### PV016



### PV020



### PV023



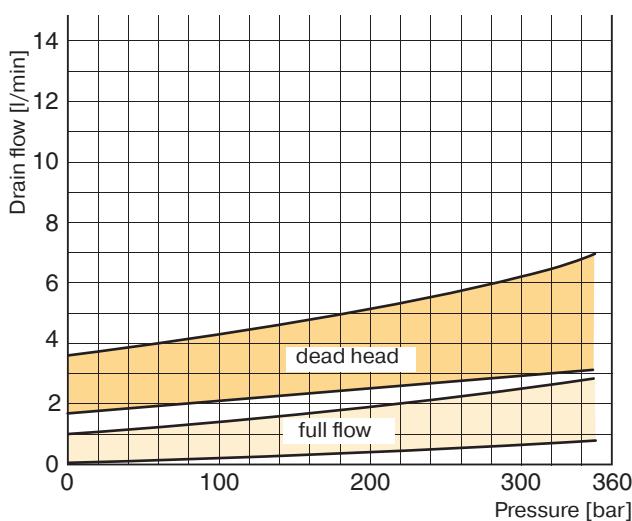
## Efficiency and case drain flows PV016, PV020, PV023 and PV028

The efficiency and power graphs are measured at an input speed of  $n = 1500$  rpm, a temperature of  $50^\circ\text{C}$  and a fluid viscosity of  $30 \text{ mm}^2/\text{s}$ .

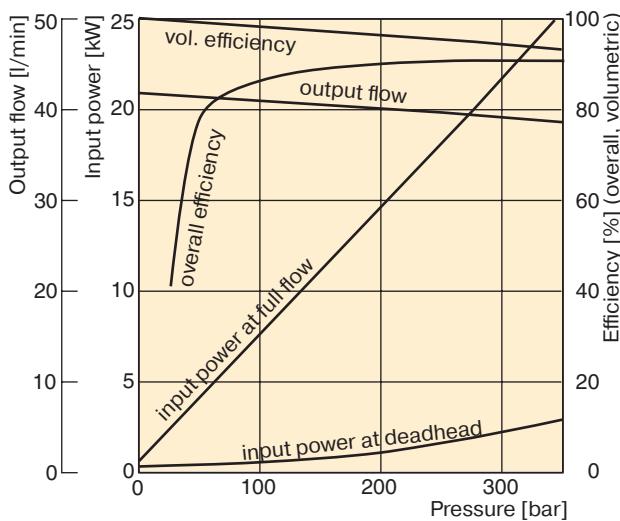
Case drain flow and compensator control flow leave via the drain port of the pump. To the values shown are to be added 1 to 1.2 l/min, if at pilot operated compensators the control flow of the pressure pilot valve also goes through the pump.

**Please note:** The values shown below are only valid for static operation. Under dynamic conditions and at rapid compensation of the pump the volume displaced by the servo piston also leaves the case drain port. This dynamic control flow can reach up to 40 l/min! Therefore the case drain line is to lead to the reservoir at full size and without restrictions as short and direct as possible.

## Case drain flow PV016-028 with pressure compensator



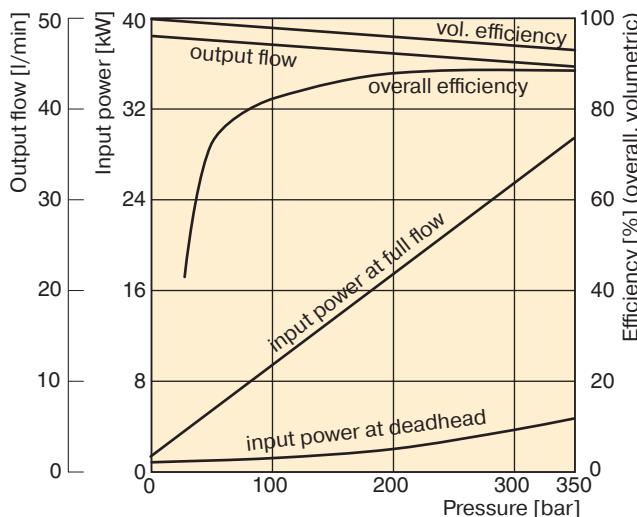
### PV028



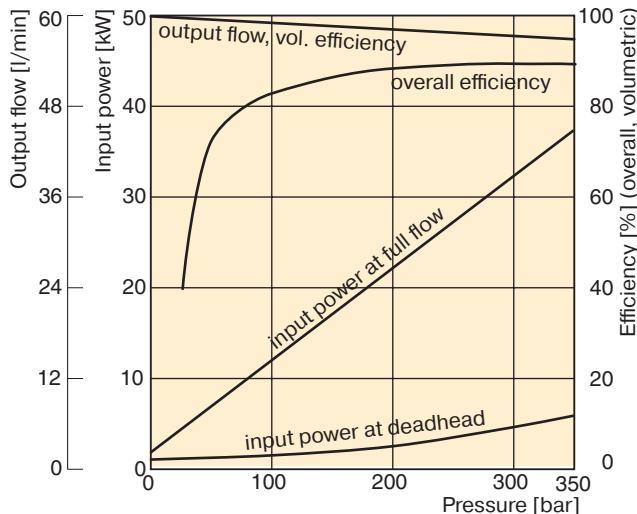
# EFFICIENCY & CASE DRAIN FLOWS

## Efficiency, power consumption

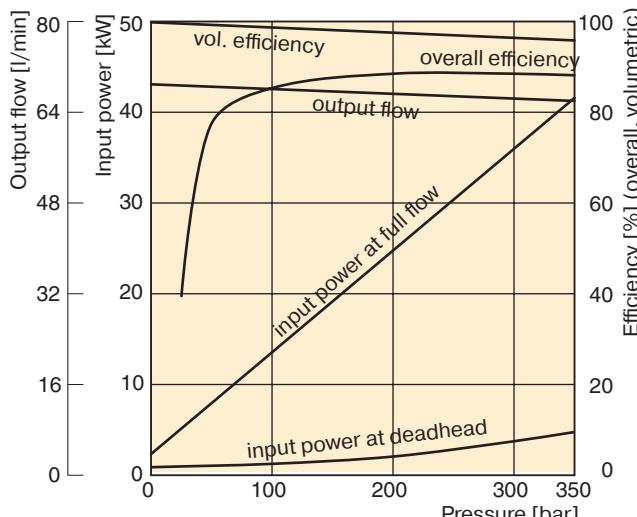
### PV032



### PV040



### PV046



## Efficiency and case drain flows

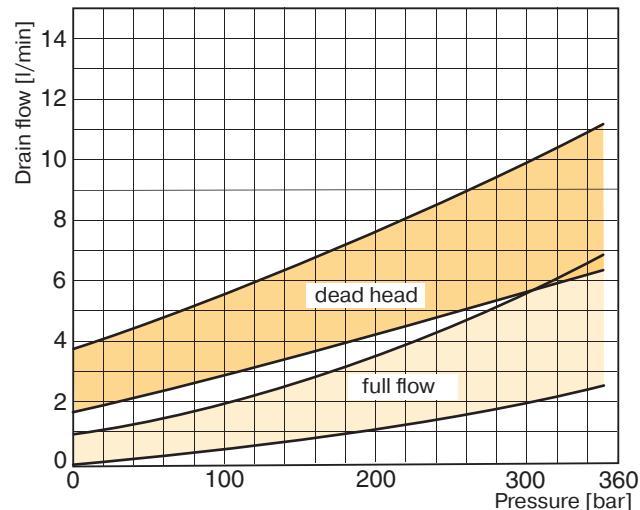
### PV032 to PV046

The efficiency and power graphs are measured at an input speed of  $n = 1500$  rpm, a temperature of  $50^\circ\text{C}$  and a fluid viscosity of  $30 \text{ mm}^2/\text{s}$ .

Case drain flow and compensator control flow leave via the drain port of the pump. To the values shown are to be added 1 to 1.2 l/min, if at pilot operated compensators the control flow of the pressure pilot valve also goes through the pump.

**Please note:** The values shown below are only valid for static operation. Under dynamic conditions and at rapid compensation of the pump the volume displaced by the servo piston also leaves the case drain port. This dynamic control flow can reach up to 60 l/min! Therefore the case drain line is to lead to the reservoir at full size and without restrictions as short and direct as possible.

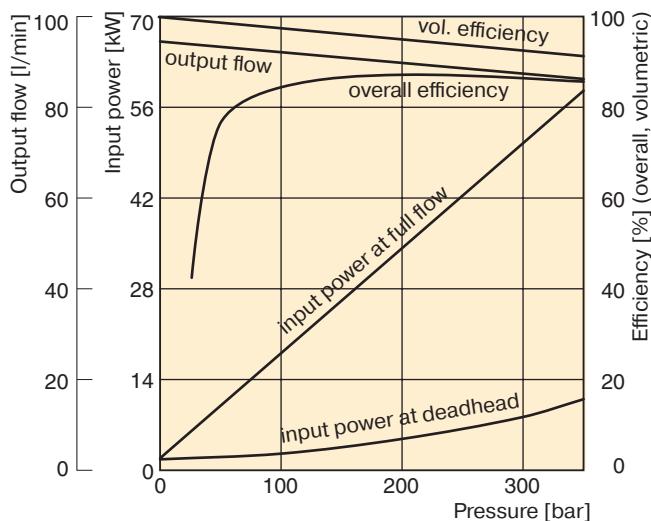
## Case drain flow PV032-046 with pressure compensator



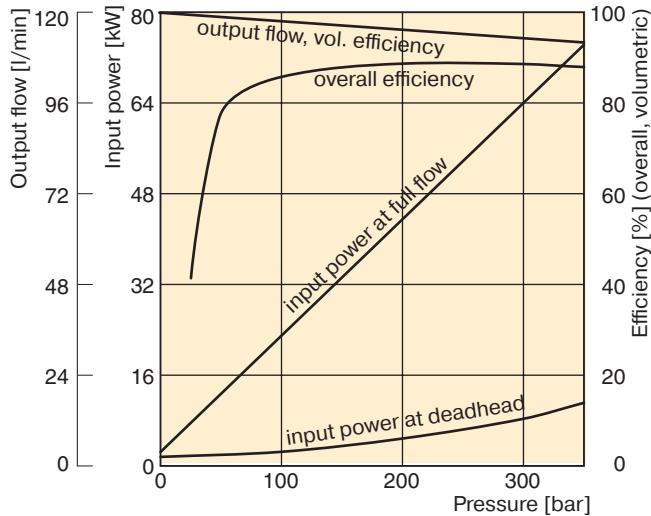
# EFFICIENCY & CASE DRAIN FLOWS

## Efficiency, power consumption

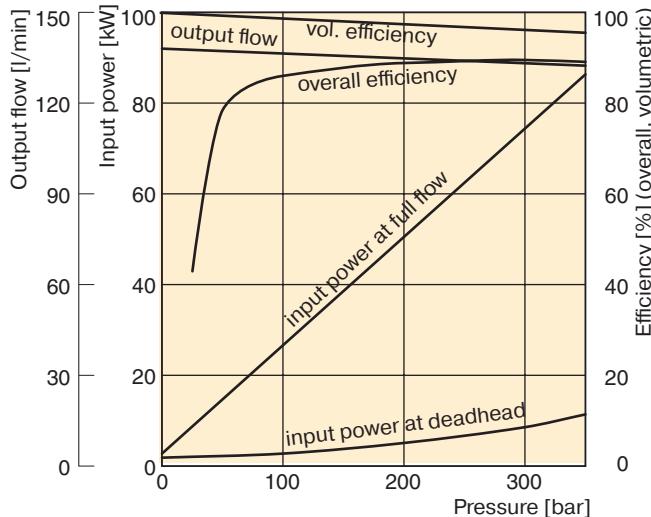
### PV063



### PV080



### PV092



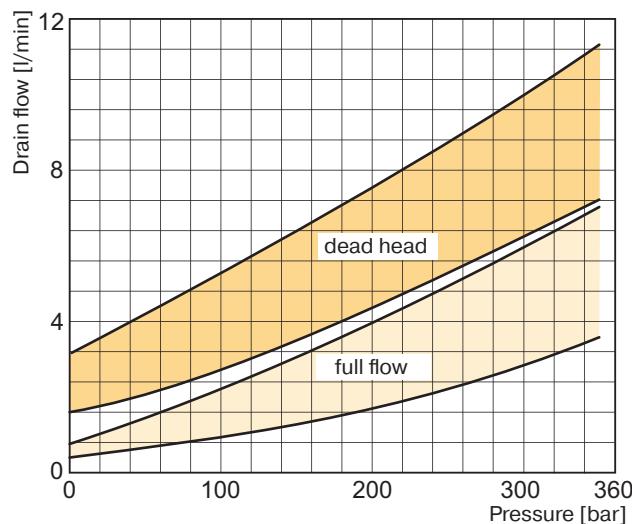
## Efficiency and case drain flows PV063, PV080, PV092

The efficiency and power graphs are measured at an input speed of  $n = 1500$  rpm, a temperature of  $50^\circ\text{C}$  and a fluid viscosity of  $30 \text{ mm}^2/\text{s}$ .

Case drain flow and compensator control flow leave via the drain port of the pump. To the values shown are to be added 1 to 1.2 l/min, if at pilot operated compensators the control flow of the pressure pilot valve also goes through the pump.

**Please note:** The values shown below are only valid for static operation. Under dynamic conditions and at rapid compensation of the pump the volume displaced by the servo piston also leaves the case drain port. This dynamic control flow can reach up to 80 l/min! Therefore the case drain line is to lead to the reservoir at full size and without restrictions as short and direct as possible.

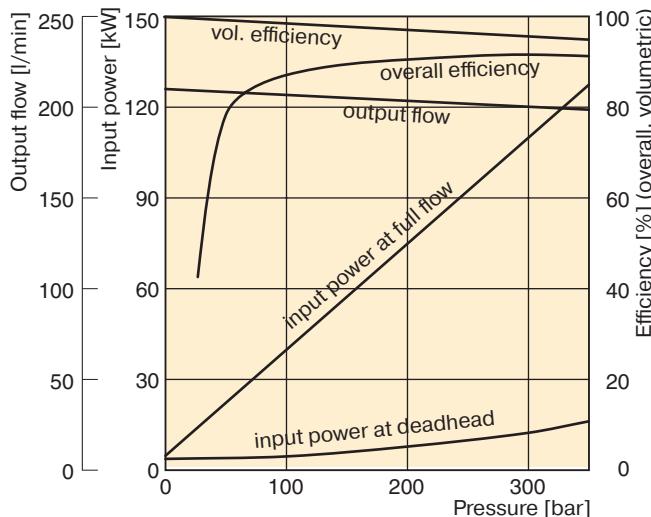
## Case drain flows PV063-092



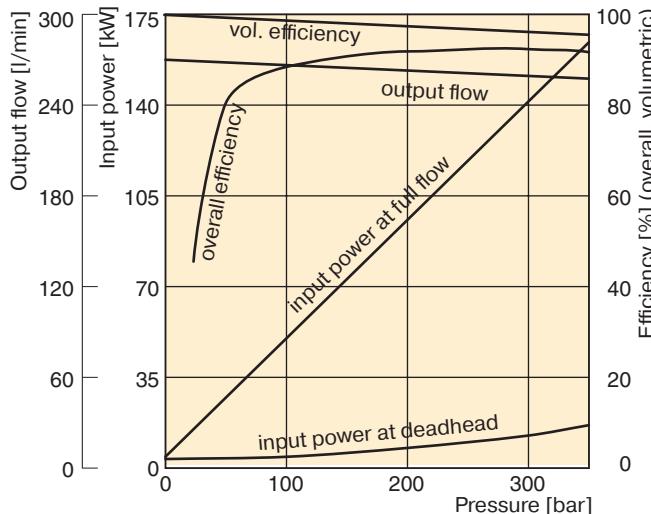
# EFFICIENCY & CASE DRAIN FLOWS

## Efficiency, power consumption

### PV140



### PV180



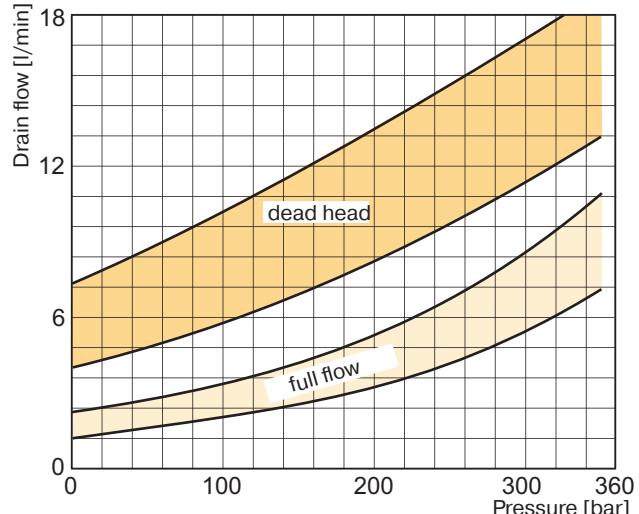
## Efficiency and case drain flows PV140, PV180

The efficiency and power graphs are measured at an input speed of  $n = 1500$  rpm, a temperature of  $50^\circ\text{C}$  and a fluid viscosity of  $30 \text{ mm}^2/\text{s}$ .

Case drain flow and compensator control flow leave via the drain port of the pump. To the values shown are to be added 1 to 1.2 l/min, if at pilot operated compensators the control flow of the pressure pilot valve also goes through the pump.

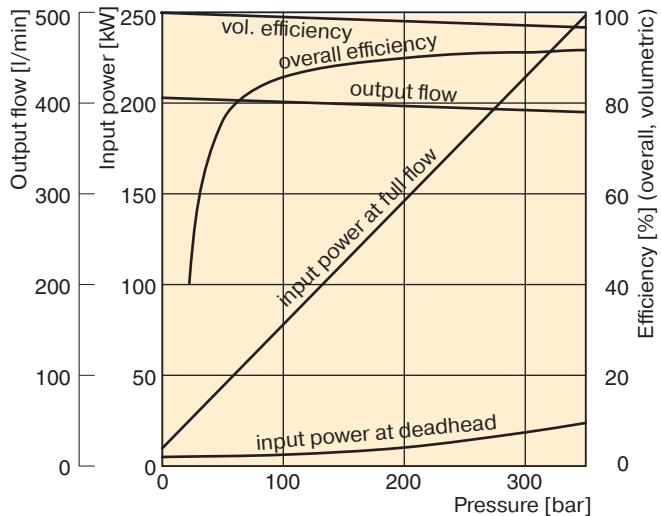
**Please note:** The values shown below are only valid for static operation. Under dynamic conditions and at rapid compensation of the pump the volume displaced by the servo piston also leaves the case drain port. This dynamic control flow can reach up to 120 l/min! Therefore the case drain line is to lead to the reservoir at full size and without restrictions as short and direct as possible.

## Case drain flows PV140-180

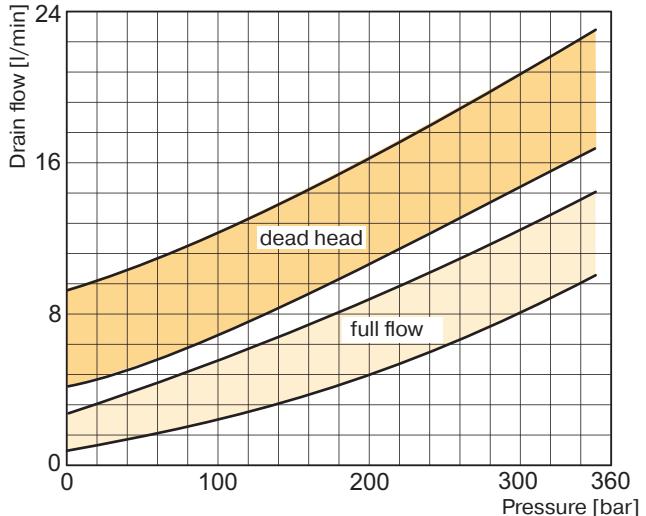


# EFFICIENCY & CASE DRAIN FLOWS

## Efficiency, power consumption PV270



## Case drain flows PV270



## Efficiency and case drain flows PV270

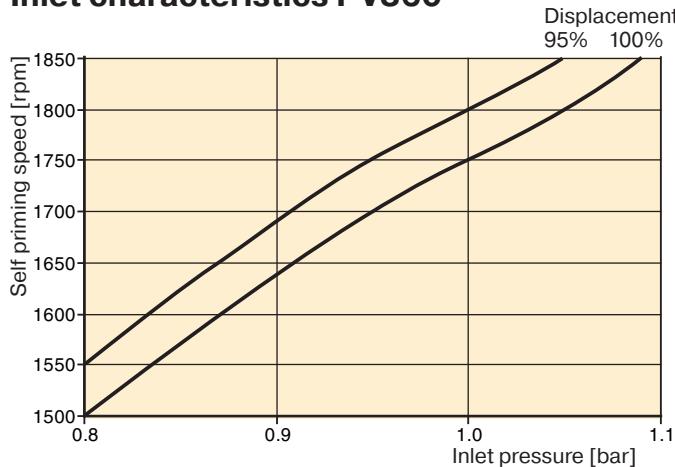
The efficiency and power graphs are measured at an input speed of  $n = 1500$  rpm, a temperature of  $50^\circ\text{C}$  and a fluid viscosity of  $30 \text{ mm}^2/\text{s}$ .

Case drain flow and compensator control flow leave via the drain port of the pump. To the values shown are to be added 1 to 1.2 l/min, if at pilot operated compensators the control flow of the pressure pilot valve also goes through the pump.

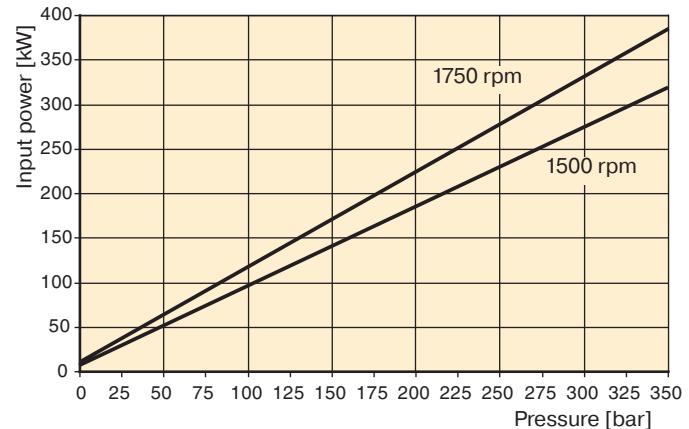
**Please note:** The values shown below are only valid for static operation. Under dynamic conditions and at rapid compensation of the pump the volume displaced by the servo piston also leaves the case drain port. This dynamic control flow can reach up to 120 l/min! Therefore the case drain line is to lead to the reservoir at full size and without restrictions as short and direct as possible.

# PERFORMANCE CURVES

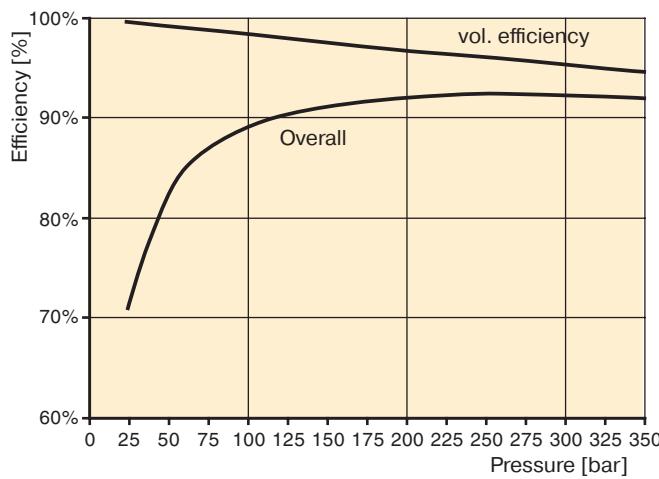
## Typical inlet characteristics vs. speed at various percentage displacements Inlet characteristics PV360



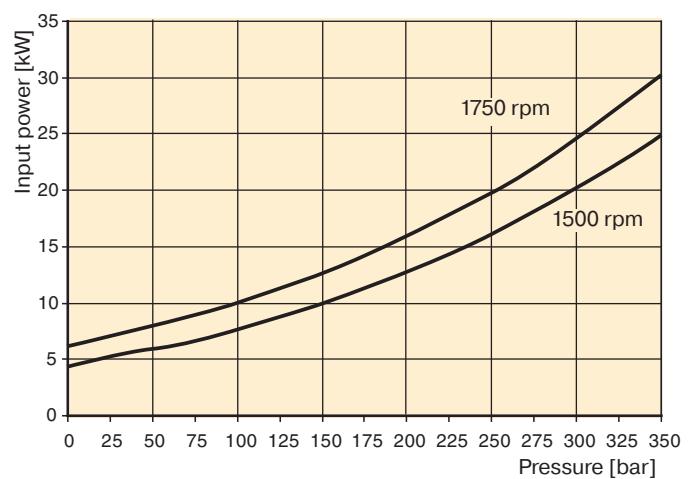
## Typical drive power at full displacement Input power – full stroke PV360



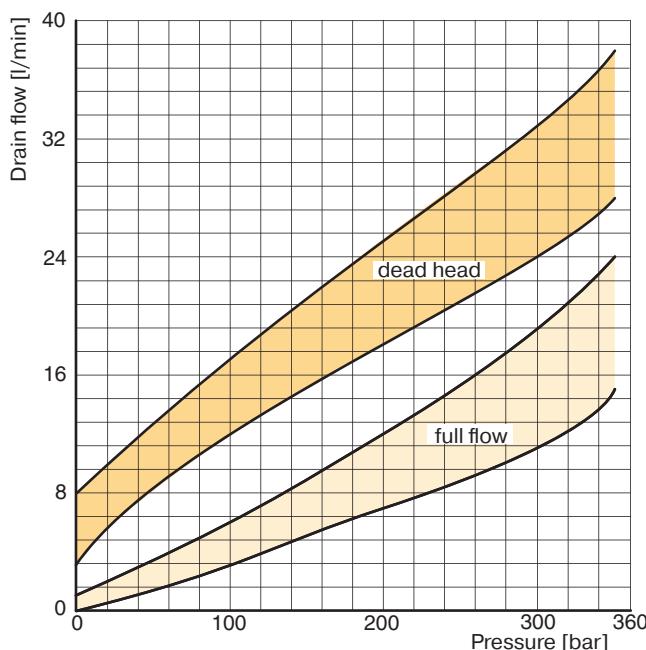
## Typical efficiency at full displacement and 1500 rpm PV360



## Typical compensated power Input power – zero stroke PV360

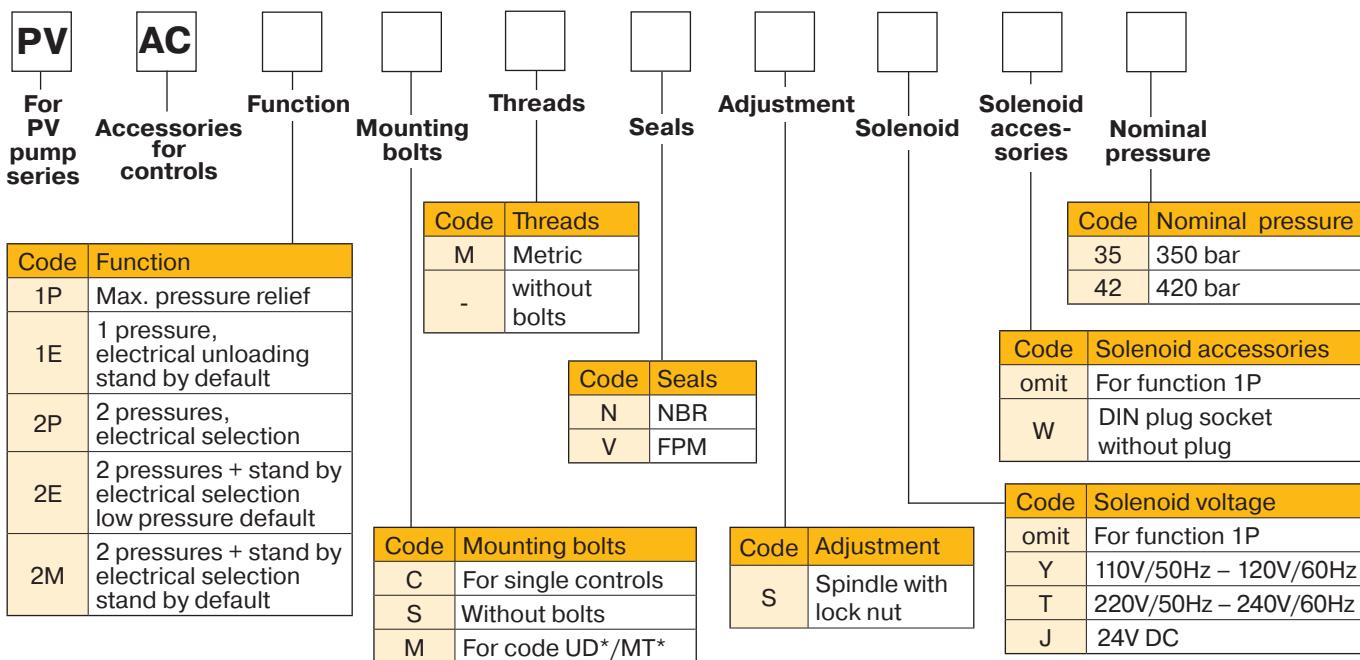


## Case drain flows PV360



The curves show typical characteristics measured under following conditions:  
Fluid: Mineral oil ISO VG 22 at 32 °C  
Inlet pressure 1,0 bar (absolute), measured at inlet port.

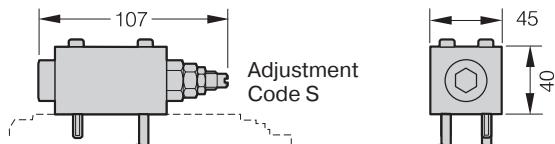
# ACCESSORIES CONTROL



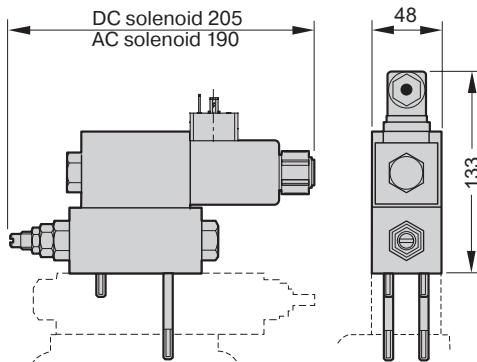
**Warning:** Risk of damaging bolt holes! Prior design series will need UNC bolts for pumps with threadcode "3".

## Dimensions

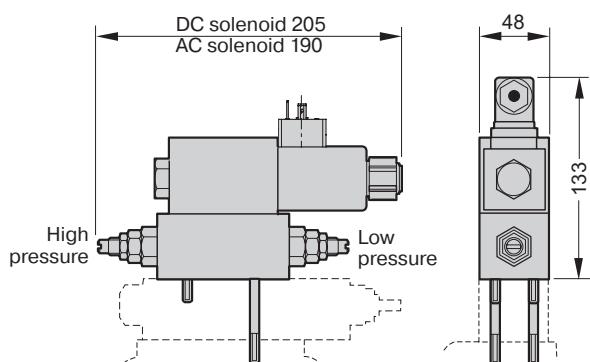
**PVAC1P\***



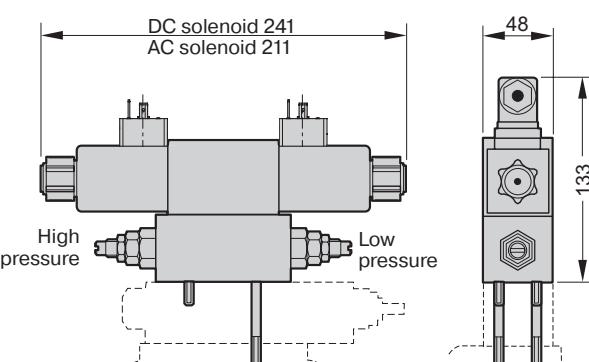
**PVAC1E\***



**PVAC2P\***

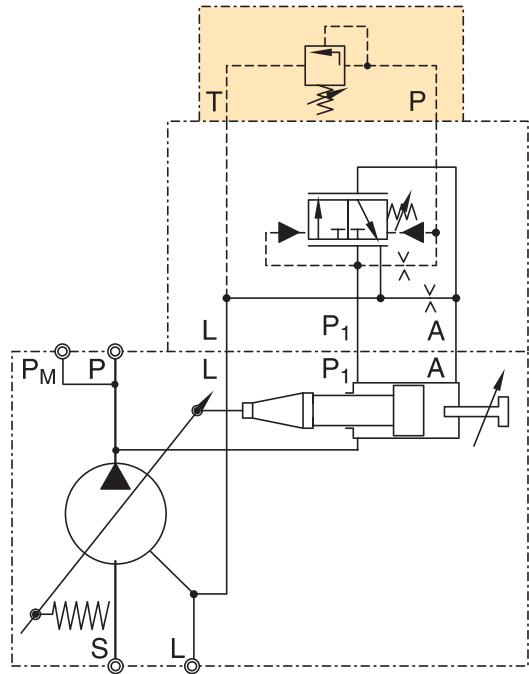


**PVAC2M\*/PVAC2E\***

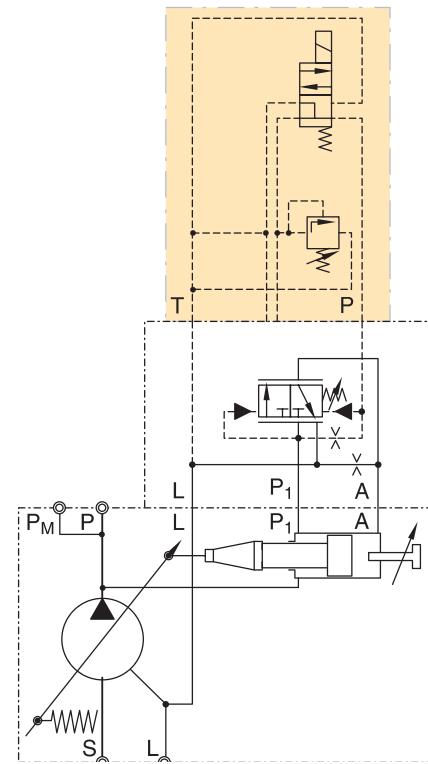


# ACCESSORIES CONTROL

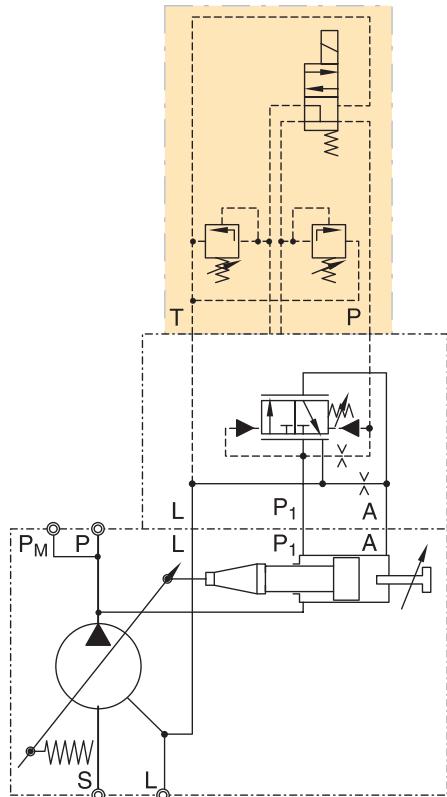
Schematics PVAC1P\*



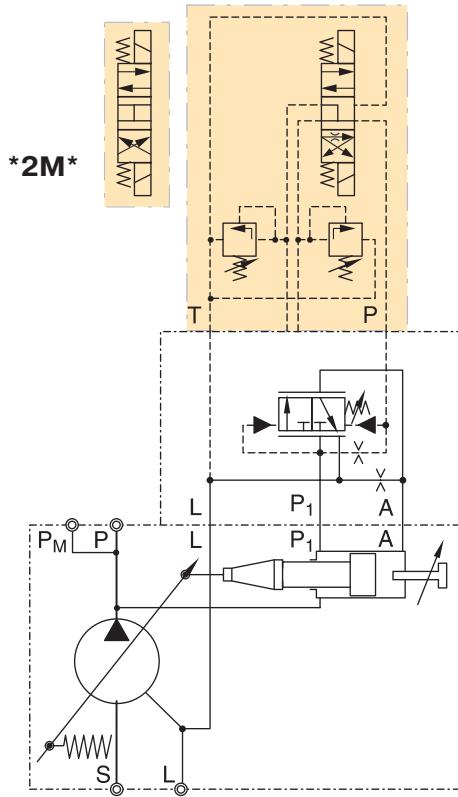
Schematics PVAC1E\*



Schematics PVAC2P\*



Schematics PVAC2M\*/PVAC2E\*



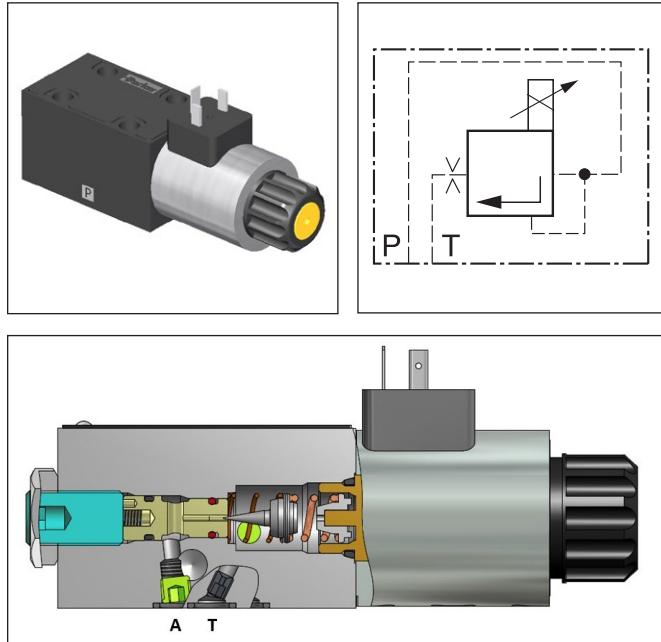
# PROPORTIONAL PRESSURE RELIEF VALVE PVACRE\*

## Proportional pressure relief valve PVACRE\*

The pressure relief valve PVACRE\* is a direct operated proportional valve, which is typically used for a remote pressure control.

### Function

When the pressure in port P exceeds the pressure setting at the solenoid, the cone opens to port T and limits the pressure in port P to the adjusted level. The optimum performance can be achieved in combination with the digital amplifier module PCD00A-400.

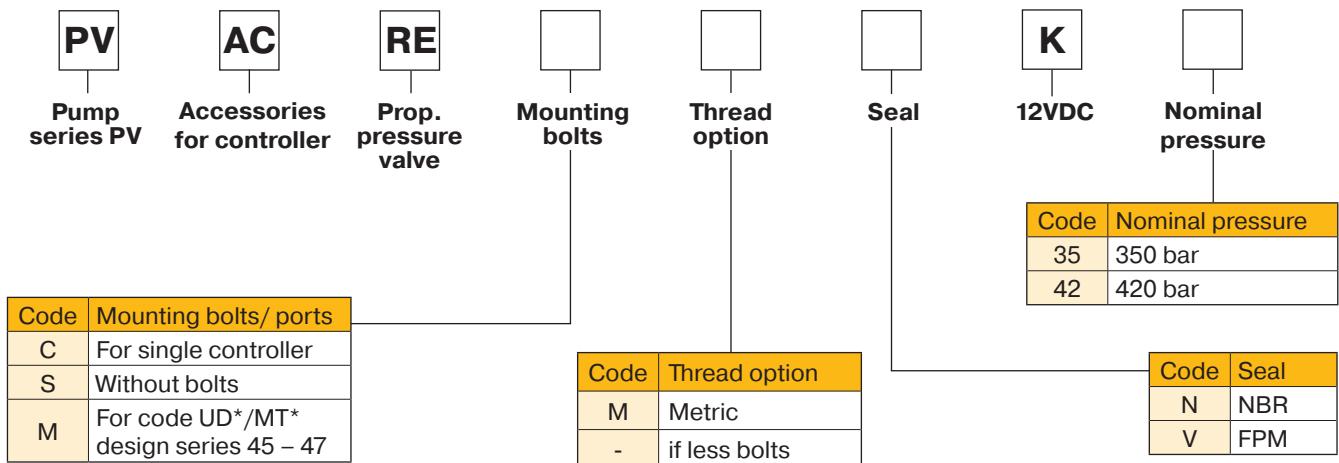


### Technical data

General		
Nominal size		DIN NG06 / CETOP03 / NFPA D03
Mounting position		as desired, horizontal mounting preferred
Ambient temperature	[°C]	-20 ... +70
Weight	[kg]	1.8
Hydraulic		
Max. operating pressure	[bar]	Port P up to 420; port T depressurized
Pressure stages	[bar]	350, 420
Fluid		Hydraulic oil as per DIN 51524 ... 525
Viscosity, recommended permitted	[cSt]/ [mm <sup>2</sup> /s]	30 ... 80
	[cSt]/ [mm <sup>2</sup> /s]	12 ... 380
Fluid temperature	[°C]	-20 ... +60
Filtration		ISO 4406 (1999), 18/16/13
Linearity	[%]	±4
Repeatability	[%]	±2
Hysteresis	[%]	±4.5 of p <sub>max</sub>
Electrical		
Duty ratio	[%]	100 ED
Protection class		IP 65 in accordance with EN 60529 (plugged and mounted)
Nominal voltage	[V]	12 (2.2 A for nominal pressure)
Coil resistance	[Ohm]	4.4 at 20°C
Solenoid connection		Connector as per EN 175301-803
Power amplifier, recommended		PCD00A-400 (open loop – NO sensor), PWDXXA-400 (closed loop – with pressure sensor)
Recommended dither frequency	[Hz]	60
Recommended dither amplitude	[%]	4

# PROPORTIONAL PRESSURE RELIEF VALVE PVACRE\*

## Ordering code proportional pressure relief valve

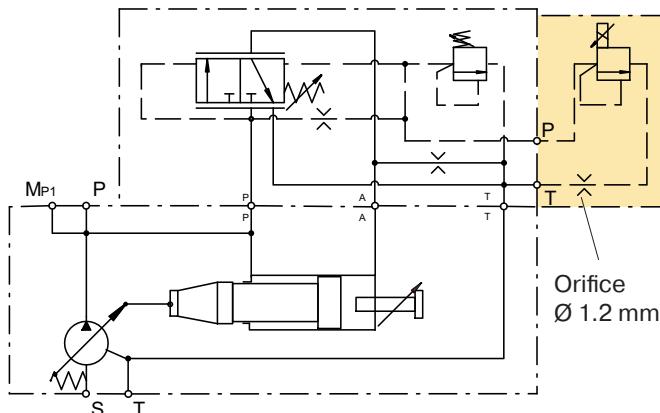


### Warning:

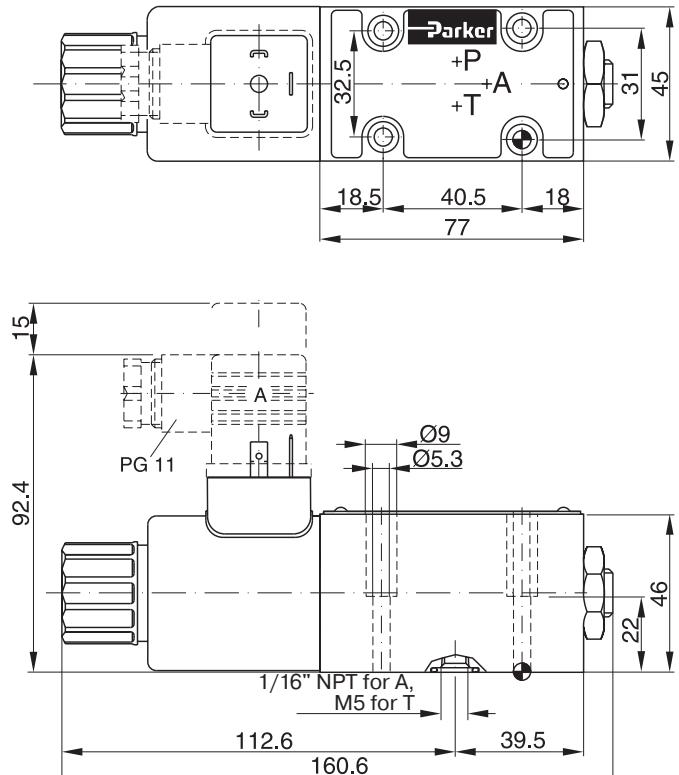
Risk of damaging bolt holes! Prior design series will need UNC bolts for pumps with threadcode "3".

## Schematic PVACRE\*

### Example for PVACRE\* mounted



## Dimensions PVACRE\*



# PROPORTIONAL PRESSURE RELIEF VALVE PVACRE\*T

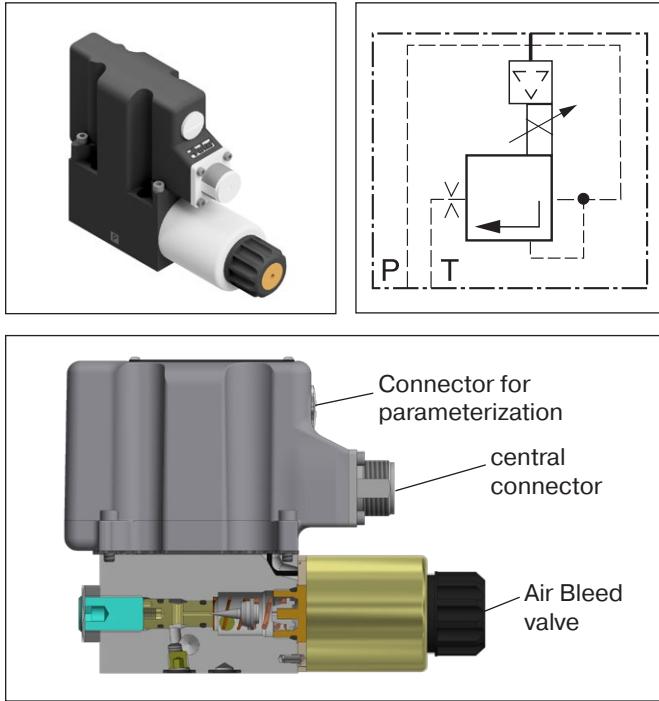
## Proportional pressure relief valve with OBE PVACRE\*T

The direct operated proportional pressure valves of the RE06M\*T series with integrated electronics are based on the functionality of the PVACRE series. The digital onboard electronic are securely housed in a robust metal box and can also be used under harsh ambient conditions. The optimized linearization and the set valve parameters were specifically adapted to the pumps of the PVplus series.

Valve parameters can be adjusted and diagnostic valves displayed by using the ProPxD software and the optionally available parameterization cable.

### Function

When the pressure in port P exceeds the pressure setting at the solenoid, the cone opens to port T and limits the pressure in port P to the adjusted level.

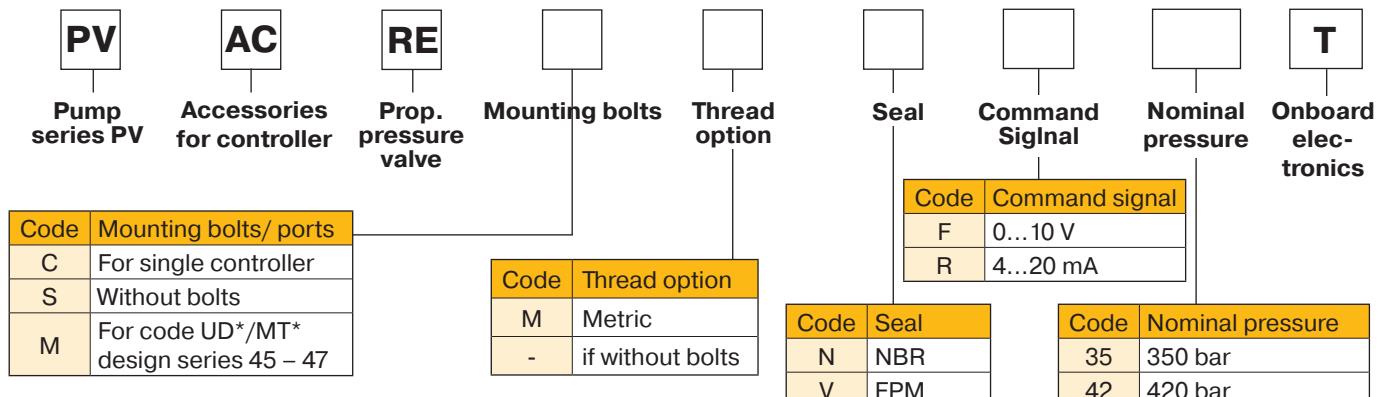


### Technical data

General		
Nominal size		DIN NG06 / CETOP03 / NFPA D03
Mounting position		as desired, horizontal mounting preferred
Ambient temperature	[°C]	-20 ... +70
Weight	[kg]	2.2
Hydraulic		
Max. operating pressure	[bar]	Port P up to 420; port T up to 30
Pressure stages	[bar]	350, 420
Fluid		Hydraulic oil as per DIN 51524 ... 525
Viscosity, recommended permitted	[cSt]/ [mm <sup>2</sup> /s]	30 ... 80
	[cSt]/ [mm <sup>2</sup> /s]	12 ... 380
Fluid temperature	[°C]	-20 ... +60
Filtration		ISO 4406 (1999), 18/16/13
Linearity	[%]	±4
Repeatability	[%]	±2
Hysteresis	[%]	±4.5 of p <sub>max</sub>
Electrical		
Duty ratio	[%]	100 ED
Protection class		IP 65 in accordance with EN 60529 (plugged and mounted)
Nominal voltage	[V]	18 ... 30 (2 A for nominal pressure)
Coil resistance	[Ohm]	4.4 at 20°C
Solenoid connection		Connector as per EN 175301-803

# PROPORTIONAL PRESSURE RELIEF VALVE PVACRE\*T

## Ordering code proportional pressure relief valve with OBE

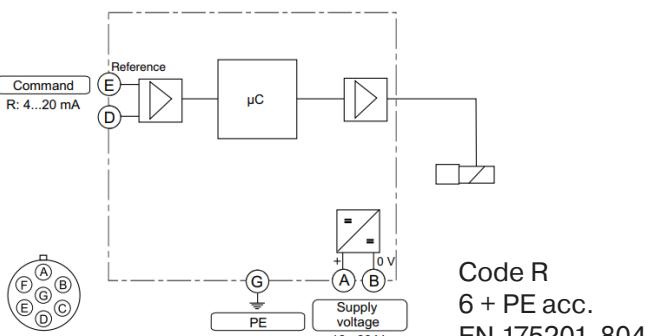
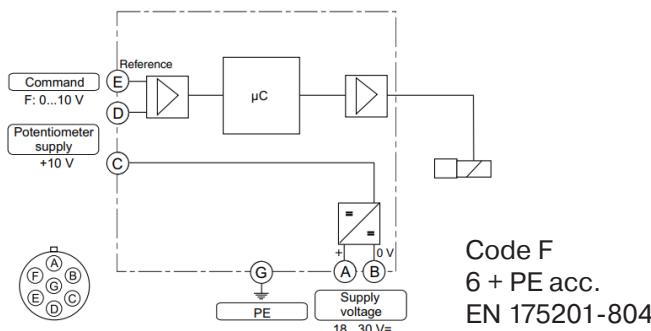
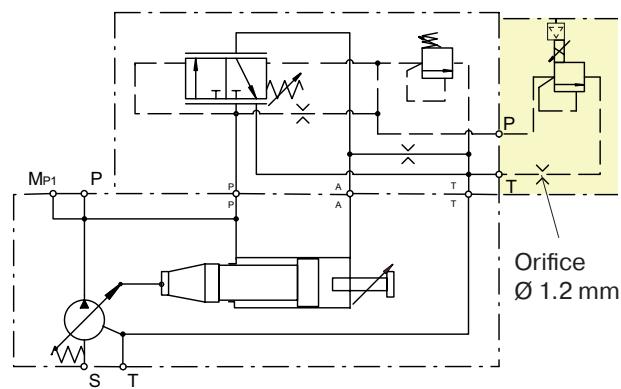


## Warning:

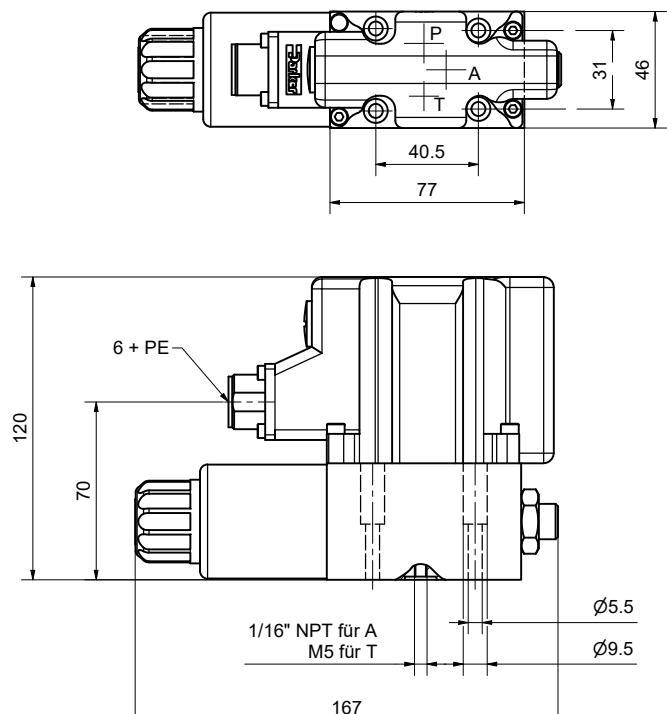
Risk of damaging bolt holes! Prior design series will need UNC bolts for pumps with threadcode "3".

## Schematic PVACRE\*T

### Example for PVACRE\* T mounted



## Dimensions PVACRE\*T



# ELECTRONIC MODULE PQDXXA

## Features

- Digital control circuit
- Covers all displacements
- Covers all available functions (pressure, displacement, power)
- Predefined parameter sets (Plug & Play)
- Connection via USB cable (USB-A/USB-B)
- Ramp time up to 60 seconds
- Compliant to the relevant european EMC specifications
- Offline editing of parameter sets
- Error diagnosis
- Easy hands on control tuning due to online monitoring of PID gains
- All settings (ramps, MIN/MAX, control parameters) can be stored digitally and recalled from a PC to duplicate settings to other modules

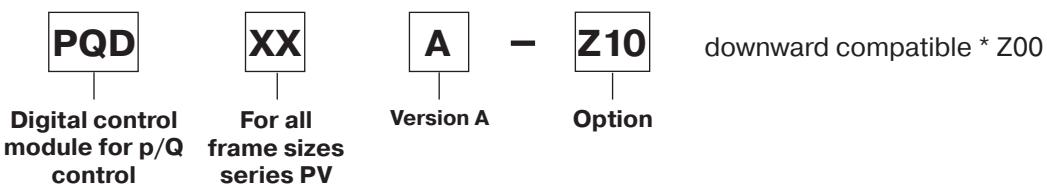


## Technical data

Mounting style	Snap-on mounting for EN50022 rail	
Body material	Polycarbonate	
Inflammation class	V2...V0 acc. UL 94	
Mounting position	any	
Env. temperature range	[°C]	-20...+55
Protection class	IP 20 acc. DIN 40 050	
Weight	[g]	260
Duty ratio	[%]	100
Supply voltage	[V]	18...30 VDC, ripple <5 % eff.
Rush in current	[A]	22 for 0.2 ms
Current consumption	[A]	< 4 for p/Q control ; < 2 for Q-control
Resolution Input Command	[%]	0.025 (power 0.1)
Interface	USB-Typ B	
EMC	EN 50 081-2, EN 50 082-2	
Connctors	Screw terminals 0.2...2.5 mm <sup>2</sup> , plug in style	
Cables	[mm <sup>2</sup> ]	Supply and solenoid cables; 1.5 mm <sup>2</sup> (AWG16) overall braid shield. Sensor and command signals; 0.5 mm <sup>2</sup> (AWG20) overall braid shield
Max. cable length	[m]	50

For programming the module via PC an interface cable is needed, please order part number PQDXXA-ZXX-KABEL separately.

## Ordering code



## Programming software

The programming of the p/Q control module is done in an easy to learn mode. To select the pump model and size and to set the control parameters the program ProPVplus must be started. The program runs under common windows systems.

Latest software available at: [www.parker.com/pmde](http://www.parker.com/pmde)

## Features

- Display and documentation of parameter sets
- Save and reload of optimized parameter sets
- Offers oscilloscope function for easy performance evaluation and optimization
- Parameter sets for all PVplus pumps are pre-installed in the modules

# ELECTRONIC MODULE PQDXXA-PROFINET-Z10

## Features

- Control, monitor and parameter setting via Profinet ® interface
- Covers all displacements and controls (pressure, displacement, power)
- Quick and easy integration with available GSDML and predefined and online available function blocks for I/Os as well as parametrization
- Full integration into overlaying machine control (PLC + HMI) Process parameter, Static Parameter, Conditions
- Predefined data sets for Plug&Play commissioning
- Quick and easy wiring with Push in contact blocks
- Switch function with two RJ45 ports
- Alternative Connection via USB cable (USB-A/USB-B)
- Compatible to the relevant european EMC specification
- Certified by Profibus User Organisation
- Easy error diagnosis

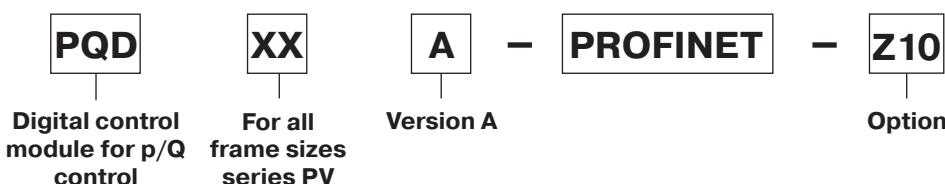


## Technical data

Mounting style	Snap-on mounting for EN50022	
Body material	Polyamide PA6.6	
Inflammation class	V0 acc. UL 94	
Mounting position	any	
Env. temperature range	[°C]	-20...+55
Protection class	IP 20 acc. DIN 40 050	
Weight	[g]	260
Duty ratio	[%]	100
Supply voltage	[V]	18...30 VDC, ripple <5 % eff.
Rush in current	[A]	22 for 0.2 ms
Current consumption	[A]	< 4 for p/Q control ; < 2 for Q-control
Resolution Input Command	[%]	0.025 (power 0.1)
Interface	2 x RJ45, USB-B	
EMC	EN61000-6-2: 2005 (Immunity), EN61000-6-3: 2007 +A1: 2010 (Emission)	
Connectors	Push in terminals 0.2...2.5 mm <sup>2</sup> , plug in style	
Cables	[mm <sup>2</sup> ]	Supply and solenoid cables; 1.5 mm <sup>2</sup> (AWG16) overall braid shield. Sensor and command signals; 0.5 mm <sup>2</sup> (AWG20) overall braid shield
Max. cable length	[m]	50

Further information at bulletin MSG30-3256-INST/UK

## Ordering code



## Programming software

The programming of the p/Q control module is done in an easy to learn mode. To select the pump model and size and to set the control parameters the program ProPVplus must be started. The program runs under common windows systems.

Latest software available at: [www.parker.com/pmde](http://www.parker.com/pmde)

## Features

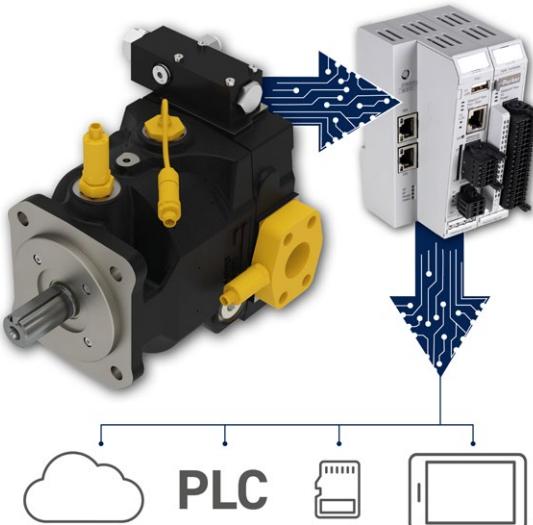
- Display and documentation of parameter sets
- Save and reload of optimized parameter sets
- Offers oscilloscope function for easy performance evaluation and optimization
- Parameter sets for all PVplus pumps are pre-installed in the modules

# PVPLUS CONDITION MONITORING

## PVplus Condition Monitoring

Parker's Condition Monitoring Solution is added to a PVplus pump and consists of a PAC120 controller, a suite of sensors and an easy-to-install mounting kit to track and monitor PVplus under all operating conditions.

This solution provides a cost-effective package to increase pump's lifespan and minimizes the risk of unplanned downtime in high availability applications.



## Key Features

- Threat Detection with Limits Checks and Warnings
- Live Data Monitoring
- Trend Data Tracking
- Graphical User Interface
- Communication Protocols (PROFINET, ETHERCAT, ETHERNET/IP)
- OPC UA functionality

## Technical data

Model		
Basic		Data Tracking, Limit Check, Trend Data, Standard Communication Protocols
Advanced	On demand	Basic + Anomaly Detection
Components		
Pressure Sensor	Housing	-1..15 bar, 4..20 mA, round plug M12x1.4 pin
	Inlet	-1..15 bar, 4..20 mA, round plug M12x1.4 pin
	Outlet	0..600 bar, 4..20 mA, round plug M12x1.4 pin
Displacements	Housing	CIP Sensor, 4..20 mA, round plug M12x1.4 pin
Controller		Control module, 24 V DC (19,2... 28,8)
	Network	1 x Ethernet 10/100 MBit-RJ45, OPC UA
	Fieldbus	Profinet IO/IRT Slave, EtherCAT Slave* or EtherNet/IP Adapter*
	Housing/protection type	Aluminum carrier, plastic, IP20
	Mounting	35 mm DIN rail
	Mounting position	Vertical, stackable
	Operating temperature	0 °C...+55 °C

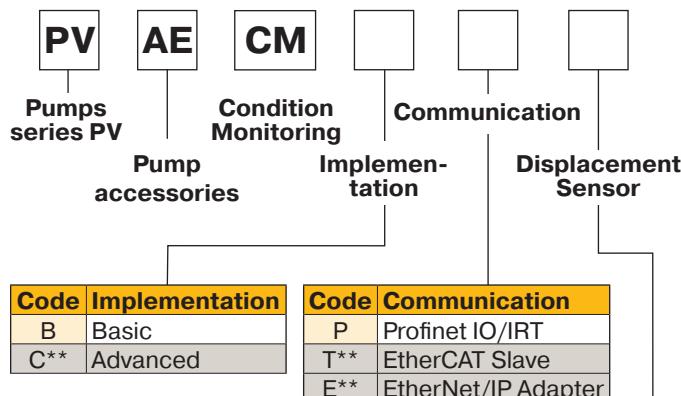
Excluded: Signal Converter

\* on demand, please ask Parker Hannifin for more information

# PVPLUS CONDITION MONITORING

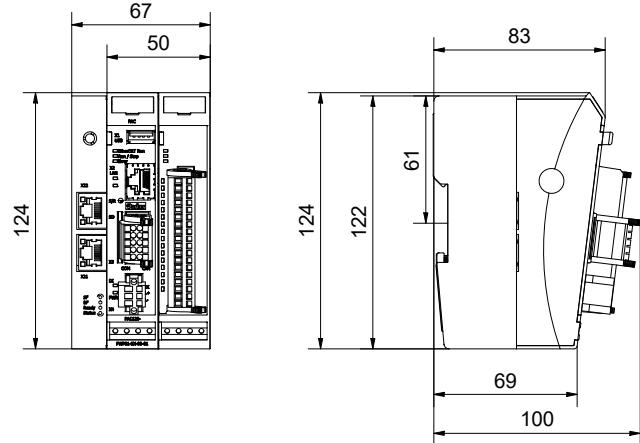
## Evaluation electronics

### Ordering code



\*\* on demand, please ask Parker Hannifin for more information

### Dimensions



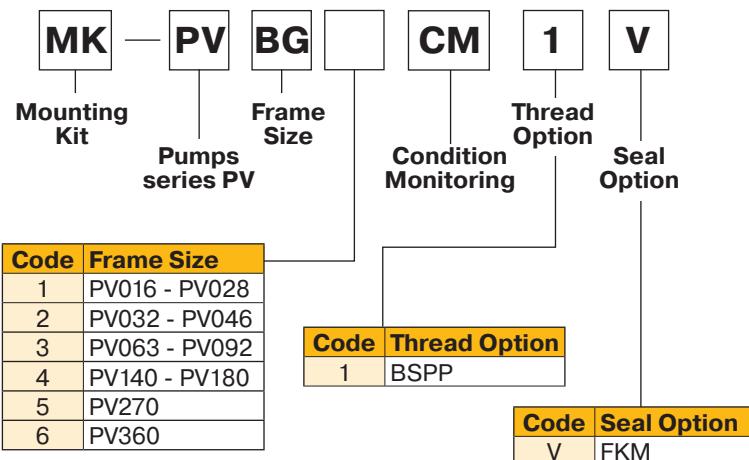
Code	Displacement Sensor
1	w/o Electronic displacement sensor (CIP)*
4	with Electronic displacement sensor (CIP)

\* only for attachments to pumps already equipped with CIP sensor

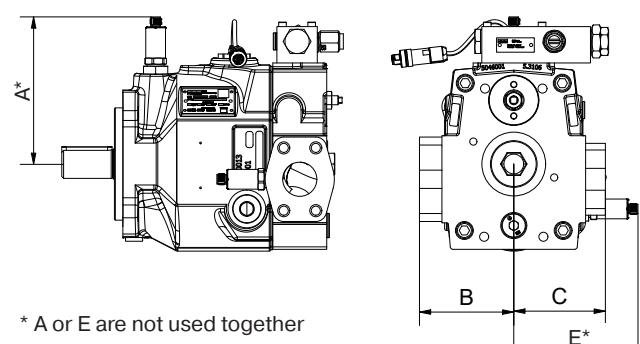
Evaluation kit contains PAC120, PACIO, software, pressure Sensors, (Displacement Sensor)

## Mounting Kit

### Ordering code



### Dimensions



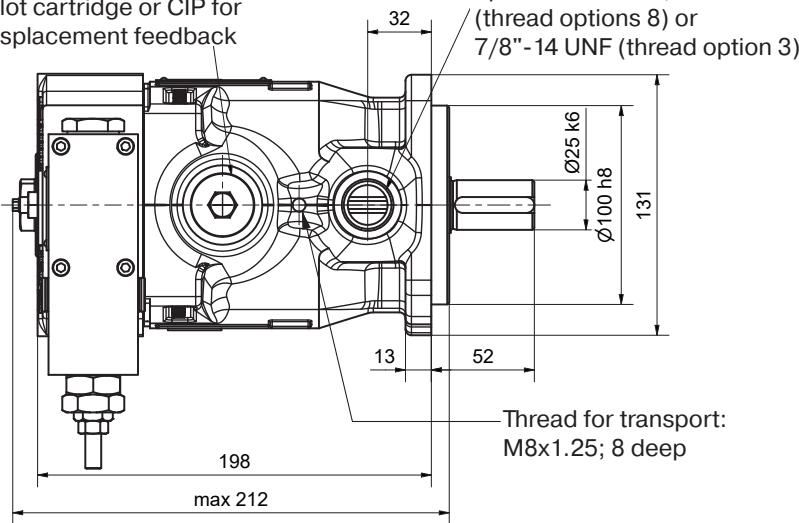
Mounting kit contains flange for inlet and outlet and adapter for drain port

Dimensions						
Frame Size	1	2	3	4	5	6
Dimensions						
A	149	159	181	206	233	233
B	86	105	125	125	152	152
C	88	102	126	126	155	155
D	118	133	146	159	177	177

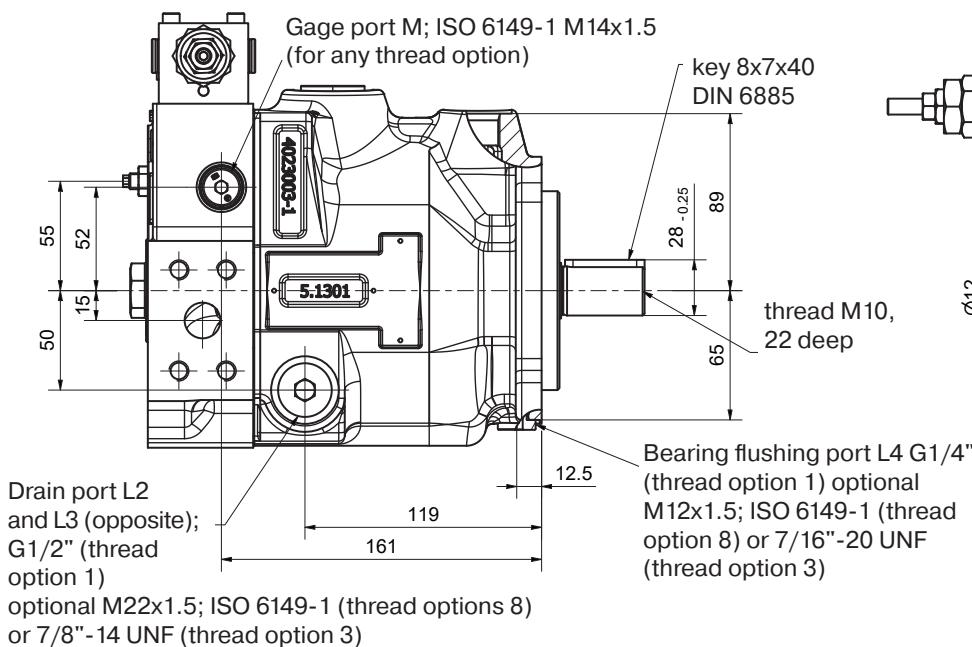
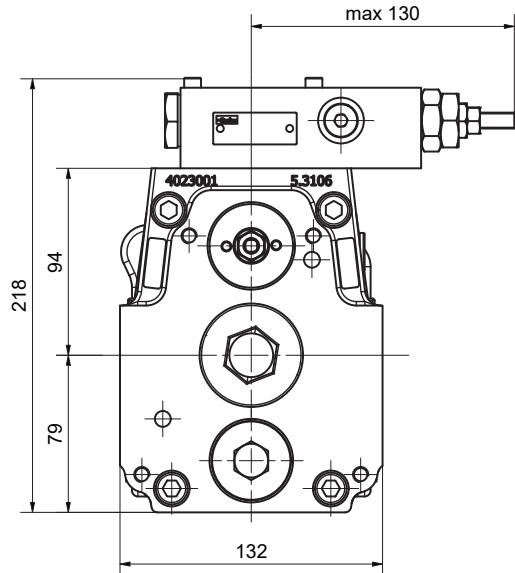
# PUMP DIMENSIONS

## PV016-028, metric version

Interface for horse power pilot cartridge or CIP for displacement feedback



Drain port L1; G1/2"  
optional M22x1.5; ISO 6149-1  
(thread options 8) or  
7/8"-14 UNF (thread option 3)

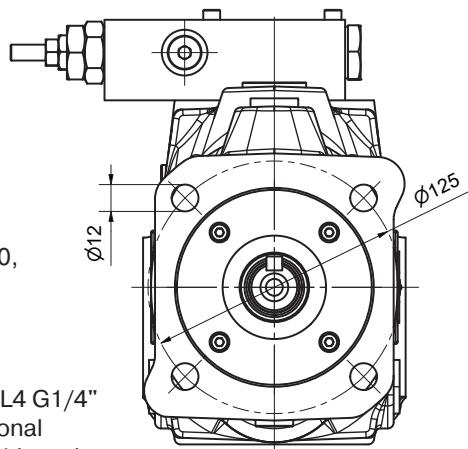


Drain port L2  
and L3 (opposite);  
G1/2" (thread  
option 1)  
optional M22x1.5; ISO 6149-1 (thread options 8)  
or 7/8"-14 UNF (thread option 3)

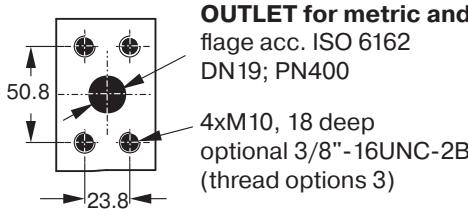
Gage port M; ISO 6149-1 M14x1.5  
(for any thread option)

key 8x7x40  
DIN 6885

Bearing flushing port L4 G1/4"  
(thread option 1) optional  
M12x1.5; ISO 6149-1 (thread  
option 8) or 7/16"-20 UNF  
(thread option 3)

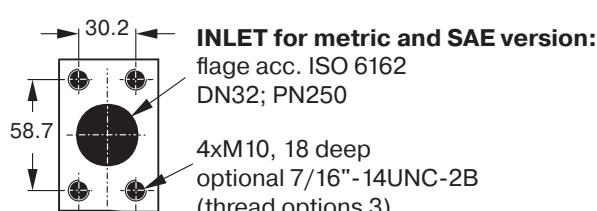


The pump shown above has  
**Mounting option K**  
and **through drive variation T**  
(prepared for through drive)



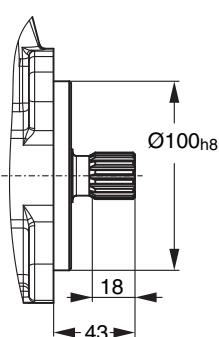
**OUTLET for metric and SAE version:**  
flange acc. ISO 6162  
DN19; PN400

4xM10, 18 deep  
optional 3/8"-16UNC-2B  
(thread options 3)



**INLET for metric and SAE version:**  
flange acc. ISO 6162  
DN32; PN250

4xM10, 18 deep  
optional 7/16"-14UNC-2B  
(thread options 3)

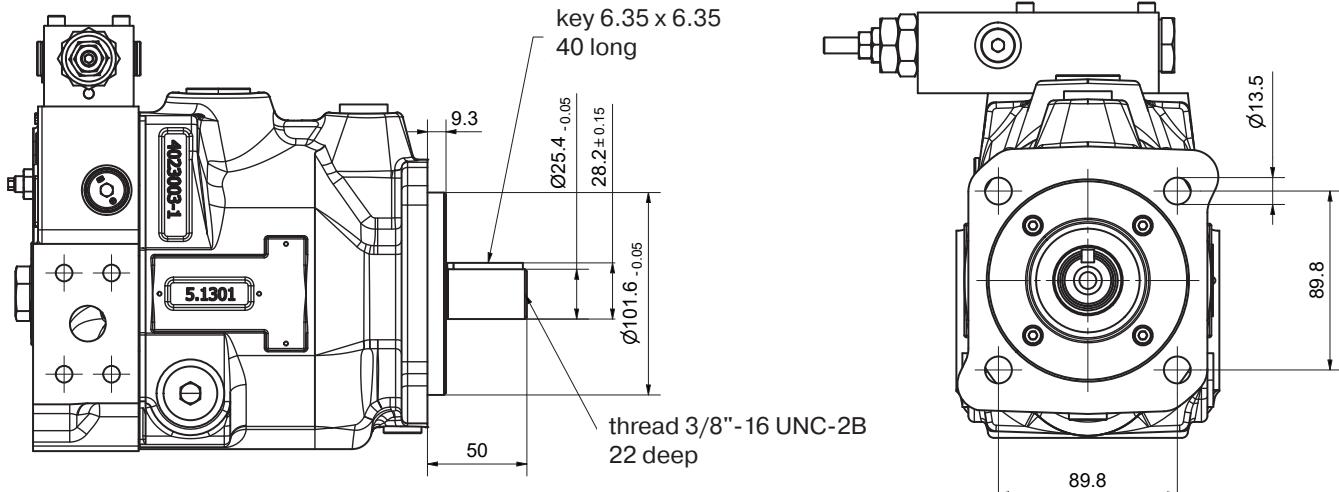


**Mounting optional L**  
splined shaft W25x1.5x15x8f  
DIN 5480

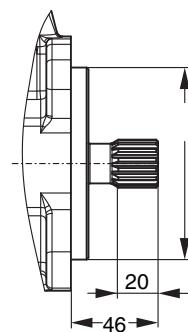
Shown is a clockwise rotating pump with standard pressure compensator. Counter clockwise rotating pumps have inlet, outlet and gage port reversed.

# PUMP DIMENSIONS

## PV016-028, SAE version

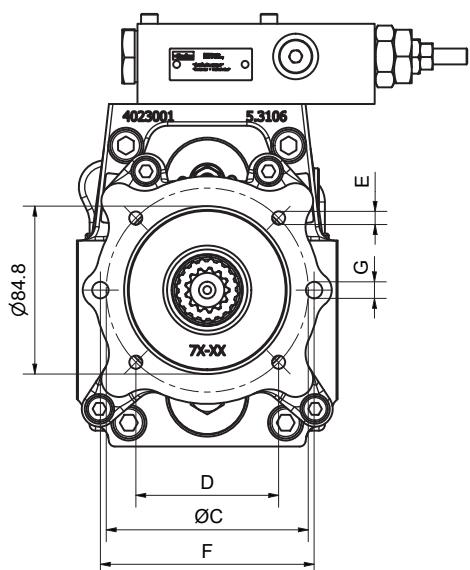
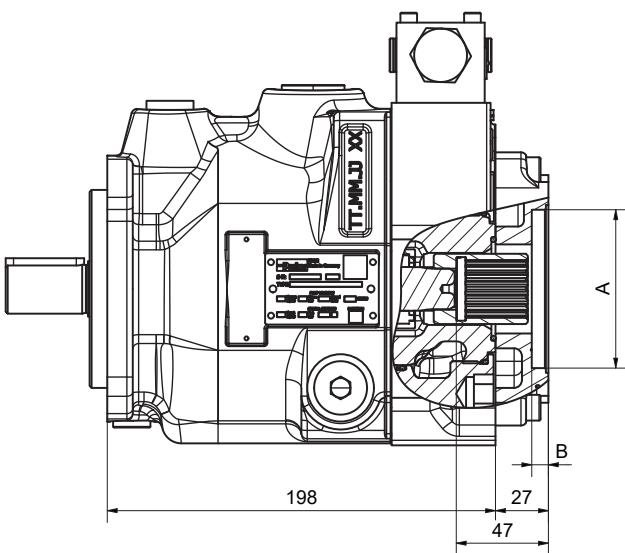


Shown above is  
**Mounting option D**



**Mounting option E**  
Splined shaft 15T-16/32 DP,  
flat root, side fit ANSI B92.1

## Variation with through drive



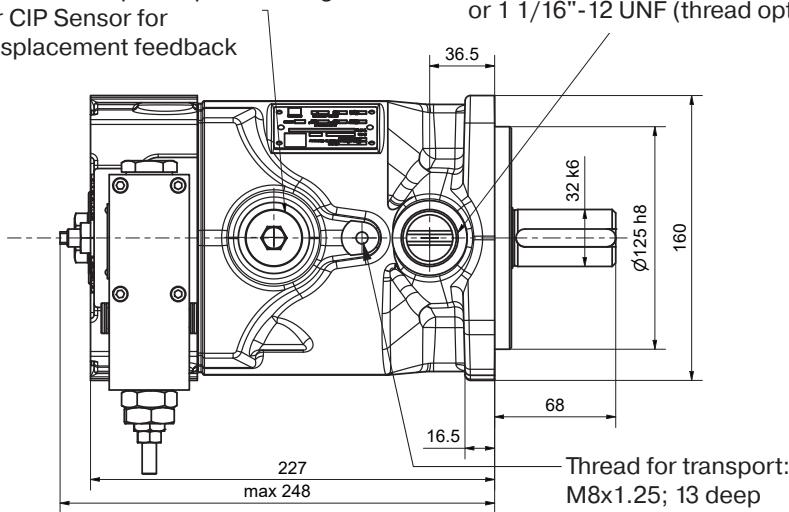
### Through drive adaptors are available with the following dimensions

Through drive option	Drawing Dimension	A	B	C	D	E	F	G	Remark
A		82.55	8	-	-	-	106	M10	SAE A 2-Bolt
B		101.6	10.5	127	89.8	M12	-	-	SAE B 4-Bolt
J		100	10.5	125	88.4	M10	-	-	4-Bolt

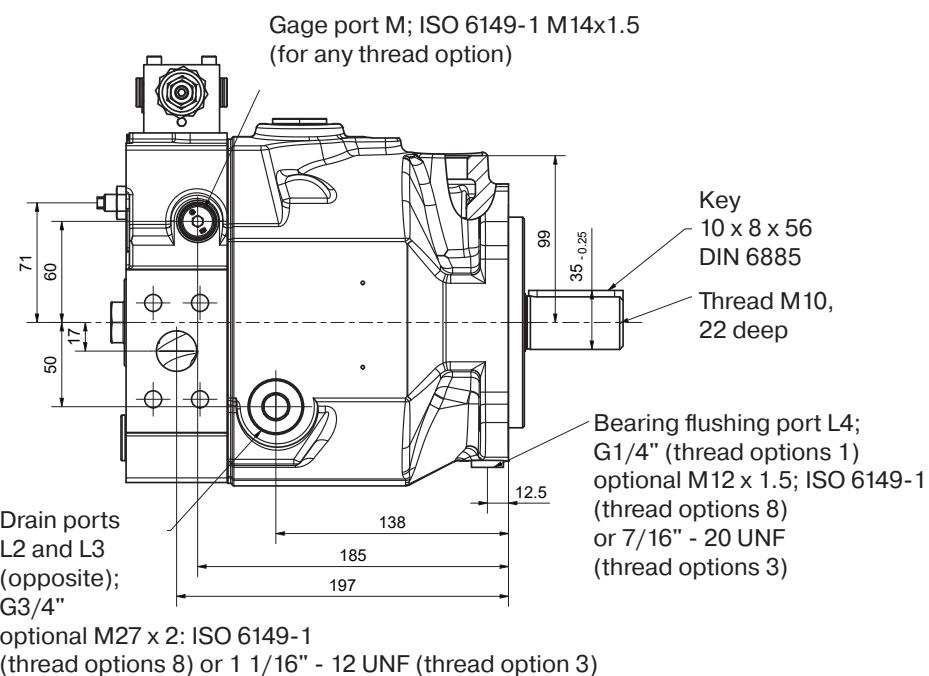
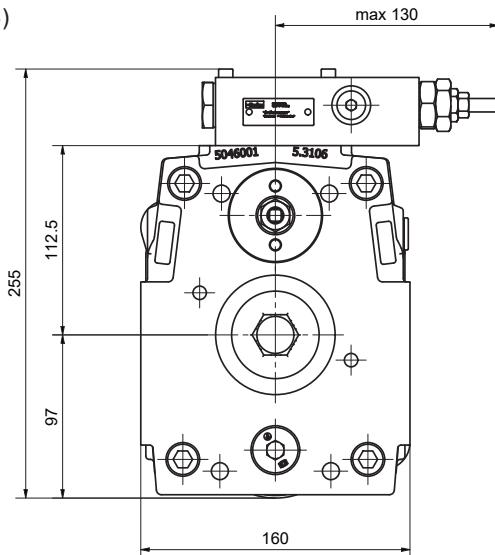
# PUMP DIMENSIONS

## PV032-046, metric version

Interface for power pilot cartridge  
or CIP Sensor for  
displacement feedback

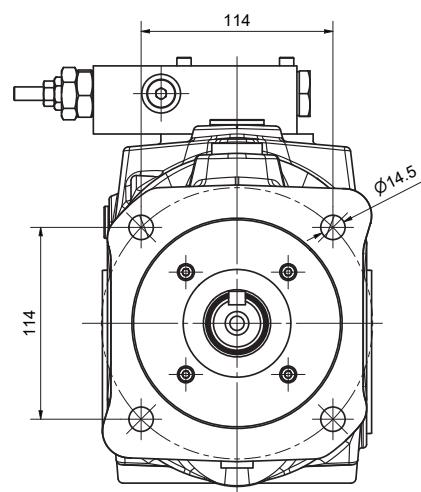


Drain port L1; G3/4" optional M27 x 2;  
ISO 6149-1 (thread options 8)  
or 1 1/16"-12 UNF (thread option 3)

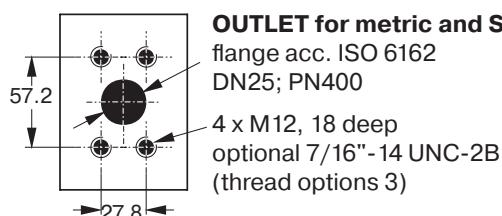


Drain ports  
L2 and L3  
(opposite);  
G3/4"  
optional M27 x 2: ISO 6149-1  
(thread options 8) or 1 1/16"-12 UNF (thread option 3)

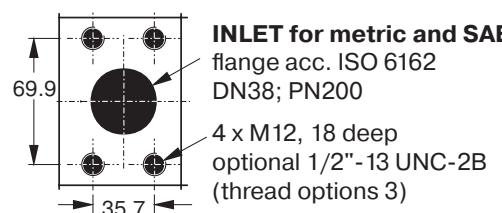
Key  
10 x 8 x 56  
DIN 6885  
Thread M10,  
22 deep  
Bearing flushing port L4;  
G1/4" (thread options 1)  
optional M12 x 1.5; ISO 6149-1  
(thread options 8)  
or 7/16"-20 UNF  
(thread options 3)



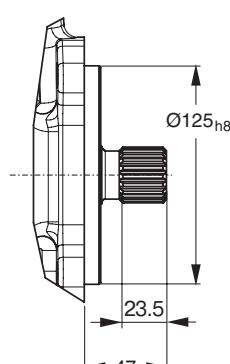
The pump shown above has  
**Mounting option K** and  
**through drive variation T**  
(prepared for through drive)



**OUTLET for metric and SAE version:**  
flange acc. ISO 6162  
DN25; PN400  
4 x M12, 18 deep  
optional 7/16"-14 UNC-2B  
(thread options 3)



**INLET for metric and SAE version:**  
flange acc. ISO 6162  
DN38; PN200  
4 x M12, 18 deep  
optional 1/2"-13 UNC-2B  
(thread options 3)

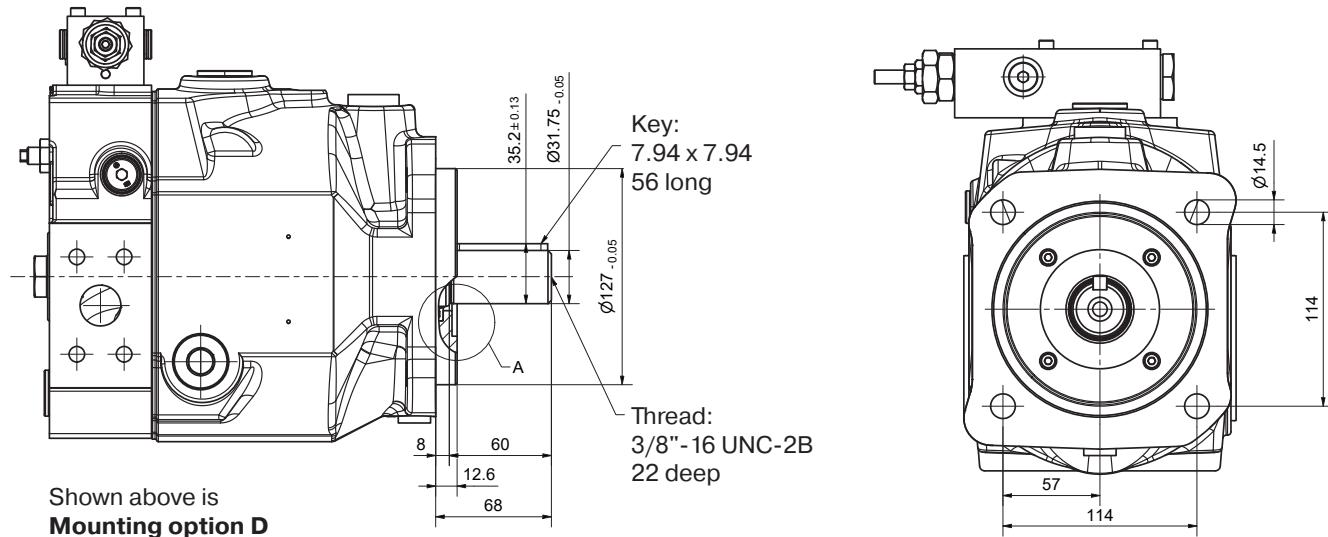


**Mounting optional L**  
splined shaft W32x1.5x20x8f  
DIN 5480

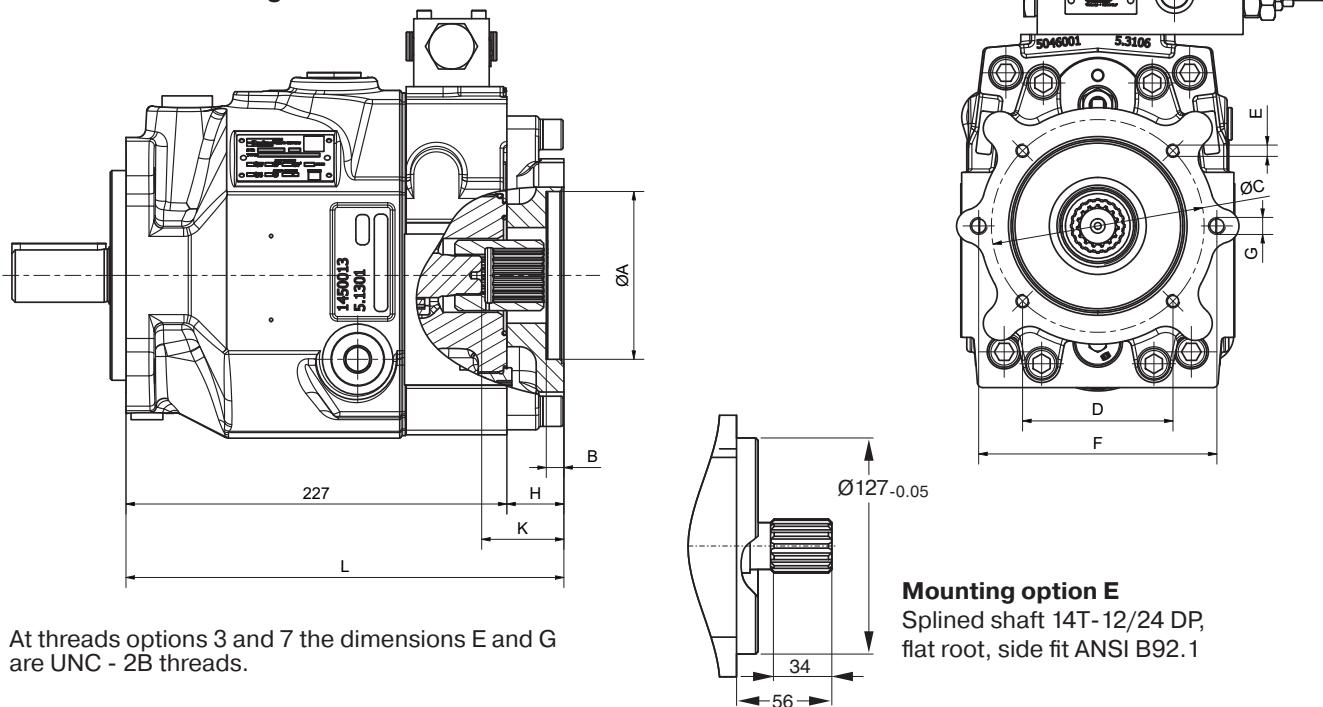
Shown is a clockwise rotating pump with standard pressure compensator. Counter clockwise rotating pumps have inlet, outlet and gage port reversed.

# PUMP DIMENSIONS

## PV032-046, SAE version



### Variation with through drive



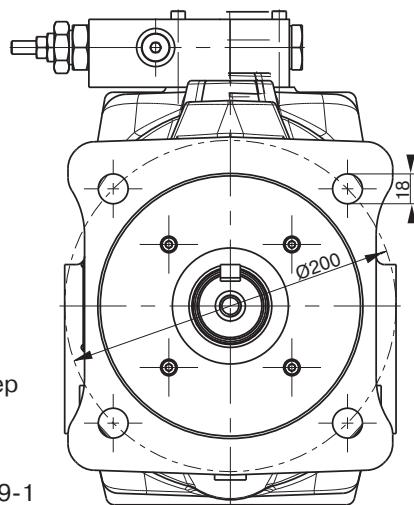
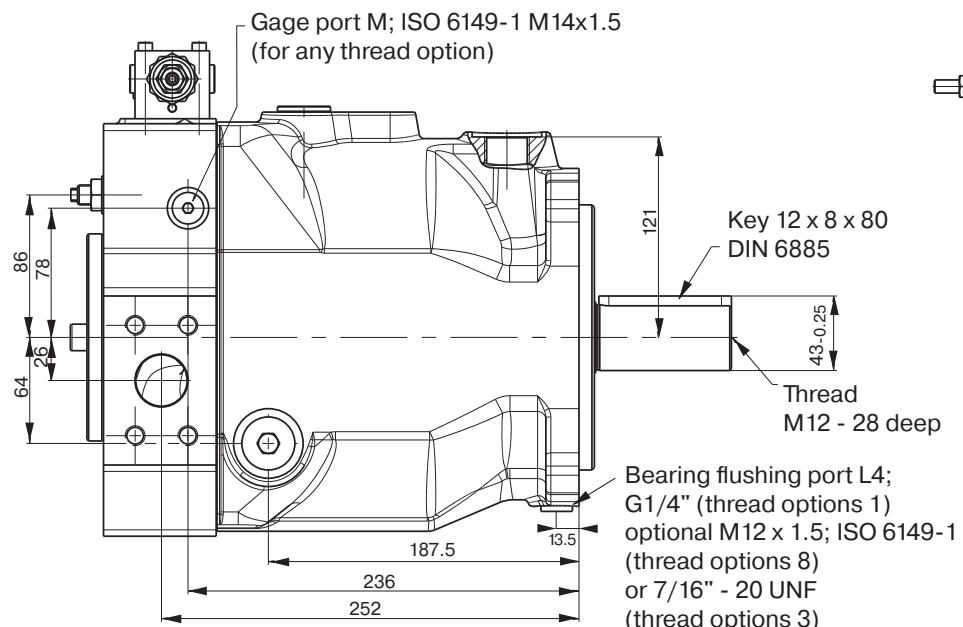
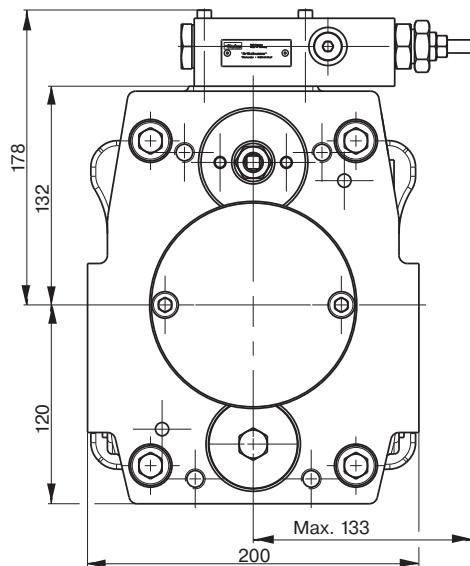
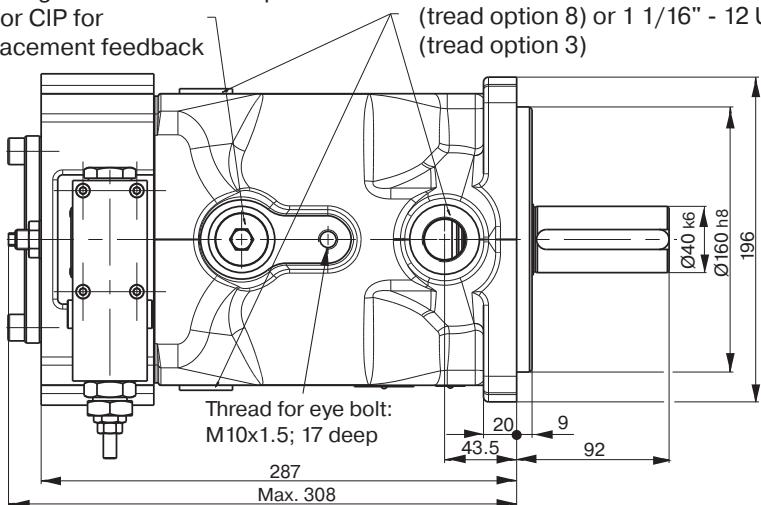
Through drive adaptors are available with the following dimensions												
Through drive option	Drawing Dimension	A	B	C	D	E	F	G	H	K	L	Remark
A	82.55	8	-	-	-	106	M10	34	48	261	SAE A 2-Bolt	
B	101.6	11	127	89.8	M12	146	M12	34	48	261	SAE B 2/4-Bolt	
C	127	13.5	162	114.6	M12	-	-	49	63	276	SAE C 4-Bolt	
J	100	10.5	125	88.4	M10	140	M12	34	48	261	2/4-Bolt	
K	125	10.5	160	113.1	M12	-	-	34	48	261	4-Bolt	

# PUMP DIMENSIONS

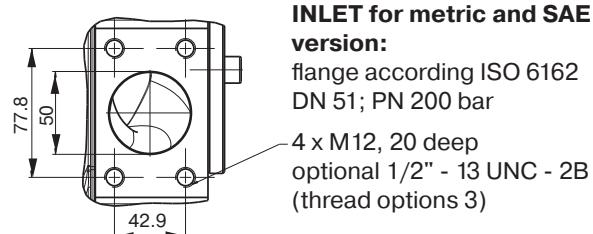
## PV 063-092, metric version

Mounting interface for horse power pilot or CIP for displacement feedback

Drain ports L1, L2 and L3; G3/4" optional M27 x 2; ISO 6149-1 (tread option 8) or 1 1/16" - 12 UNF (tread option 3)

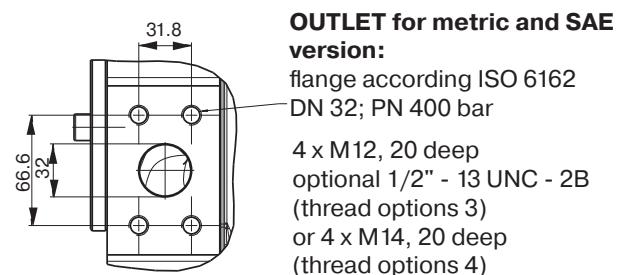
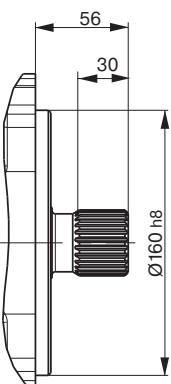


The pump shown above has **Mounting option K** and **through drive variation T** (prepared for through drive)



### INLET for metric and SAE version:

flange according ISO 6162  
DN 51; PN 200 bar  
4 x M12, 20 deep  
optional 1/2" - 13 UNC - 2B  
(thread options 3)



### OUTLET for metric and SAE version:

flange according ISO 6162  
DN 32; PN 400 bar  
4 x M12, 20 deep  
optional 1/2" - 13 UNC - 2B  
(thread options 3)  
or 4 x M14, 20 deep  
(thread options 4)

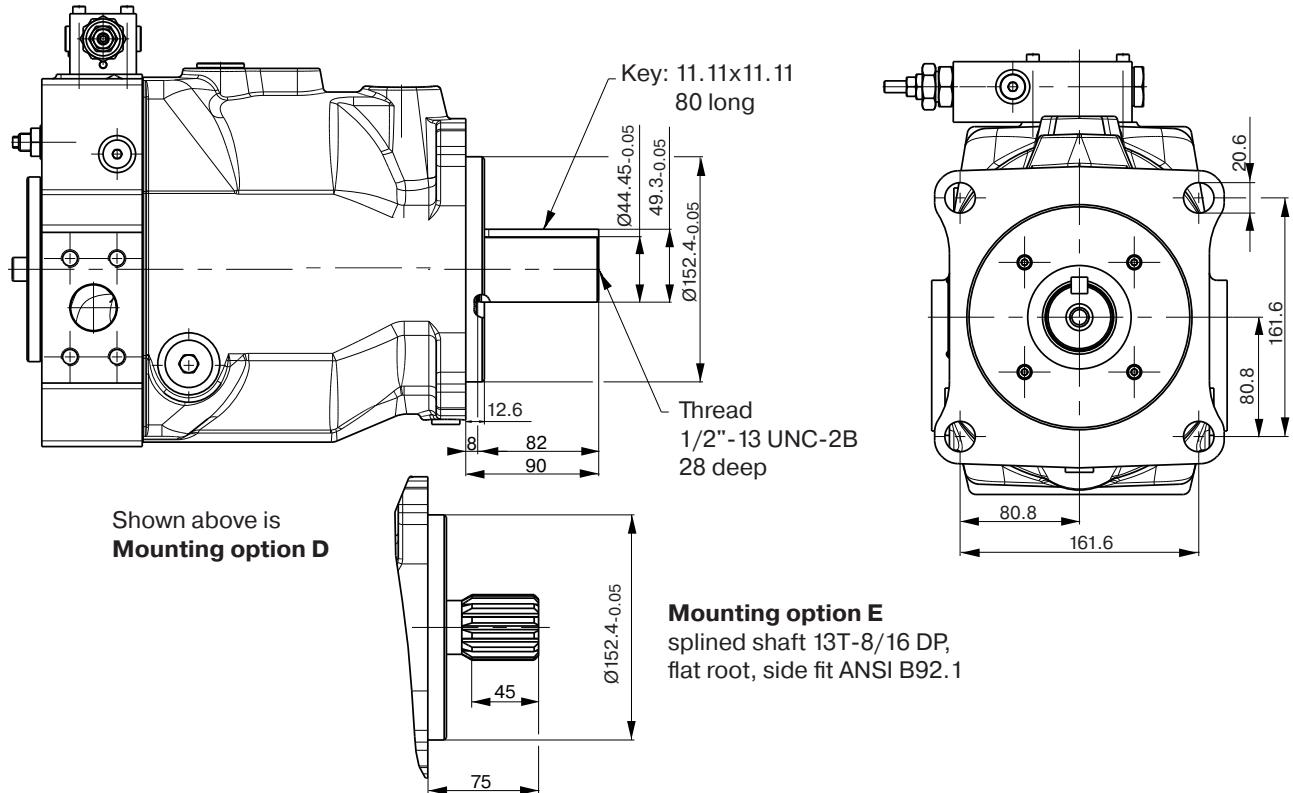
### Mounting option L, splined shaft

W40 x 1.5 x 25 x 8f DIN 5480

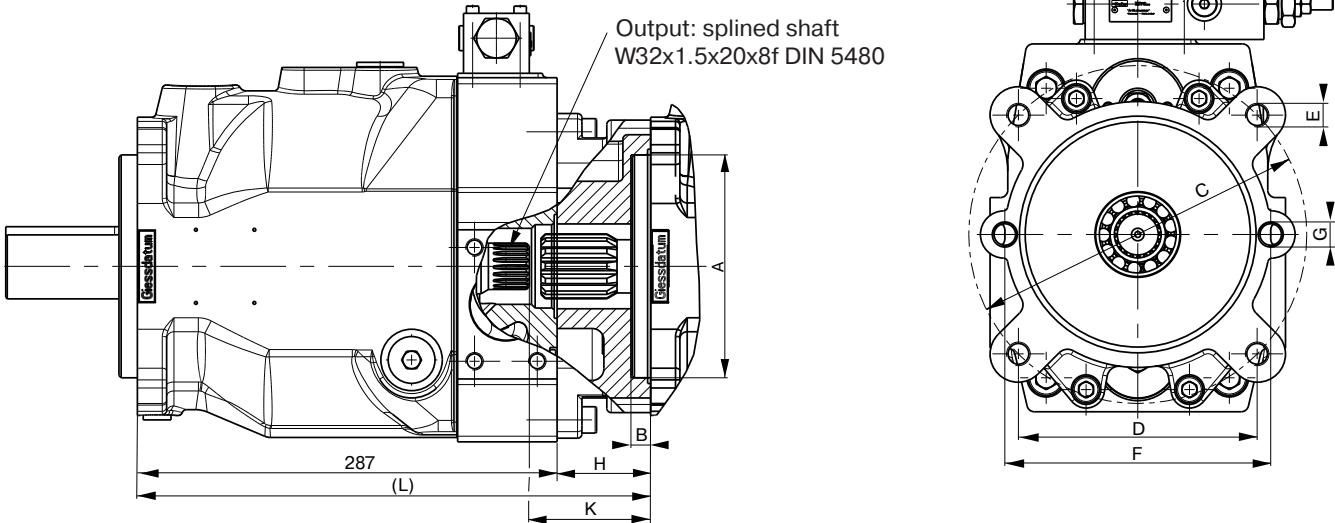
Shown is a clockwise rotating pump with standard pressure compensator. Counter clockwise rotating pumps have inlet, outlet and gage port reversed.

# PUMP DIMENSIONS

## PV 063-092 SAE Version



## Variation with through drive

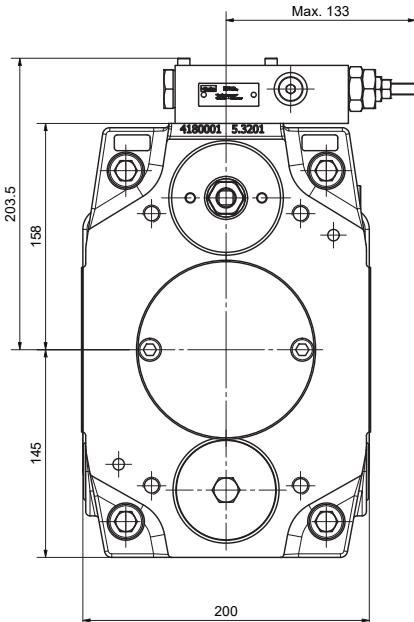
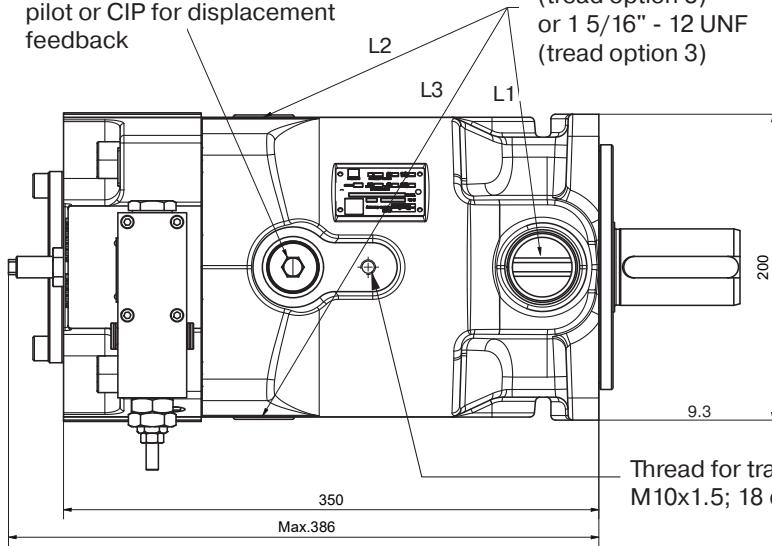


Through drive adaptors are available with the following dimensions											
Drawing Dimension	A	B	C	D	E	F	G	H	K	L	Remark
A	82.55	8	-	-	-	106	M10	39	58	326	SAE A 2-Bolt
B	101.6	11	127	89.8	M12	146	M12	39	58	326	SAE B 2/4-Bolt
C	127	13.5	162	114.6	M12	181	M16	39	58	326	SAE C 2/4-Bolt
D	152.4	13.5	228.5	161.6	M16	-	-	64	83	351	SAE D 4-Bolt
J	100	10.5	125	88.4	M10	140	M12	39	58	326	2/4-Bolt
K	125	10.5	160	113.1	M12	180	M16	39	58	326	2/4-Bolt
L	160	13.5	200	141.4	M16	-	-	39	58	326	4-Bolt

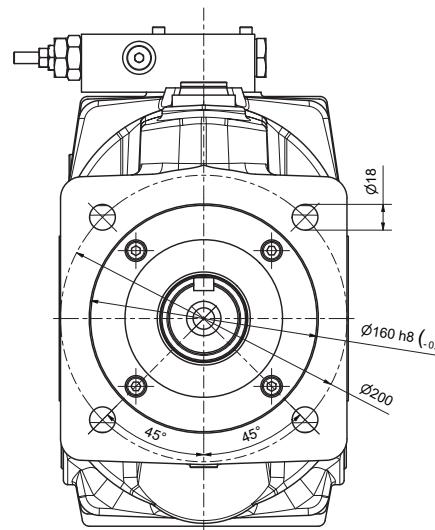
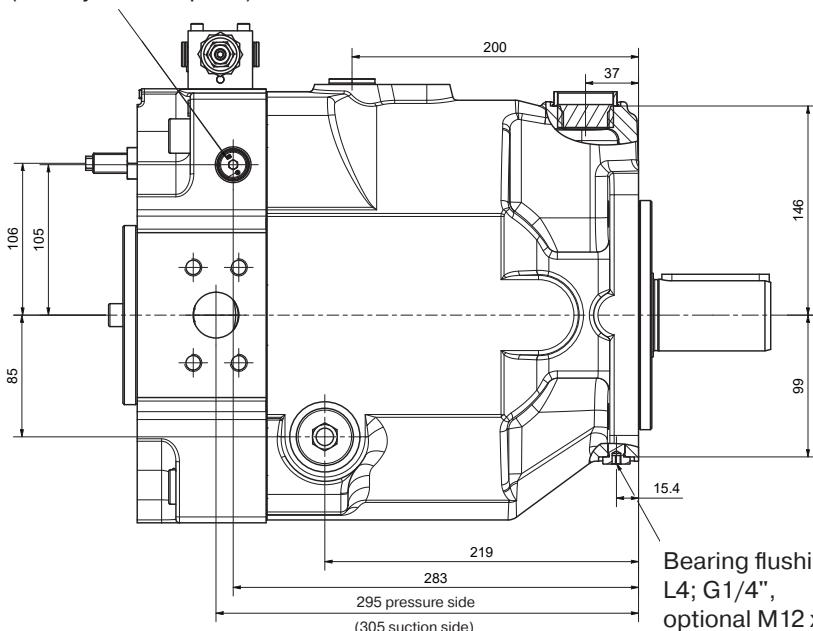
# PUMP DIMENSIONS

## PV 140-180, metric version

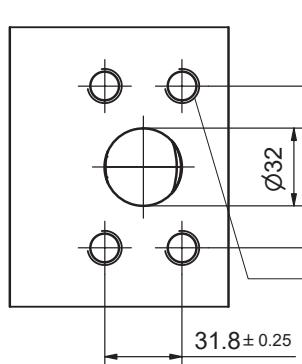
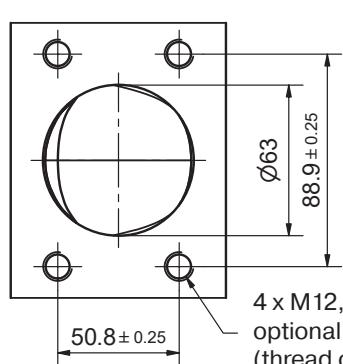
Mounting interface for horse power pilot or CIP for displacement feedback



Gage port M; ISO 6149-1 M14x1.5 (for any thread option)



Flange according DIN ISO 3019-2 metric for mounting interface code K and L

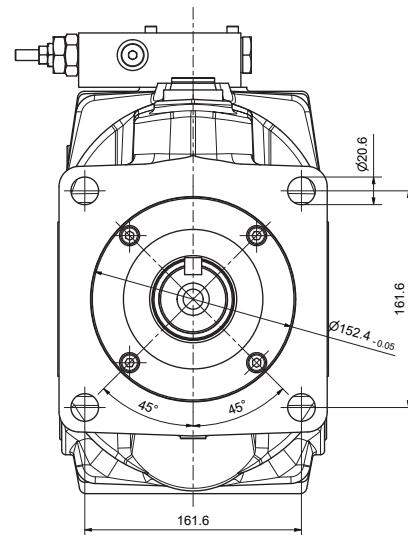
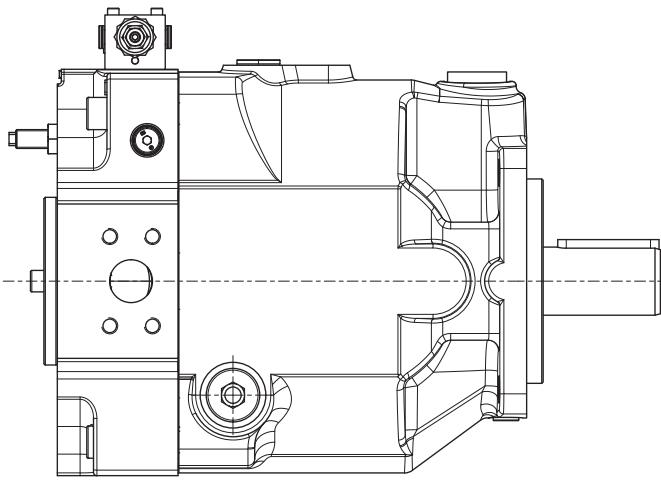


# PUMP DIMENSIONS

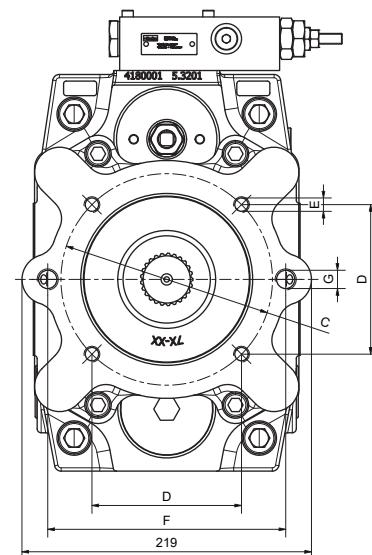
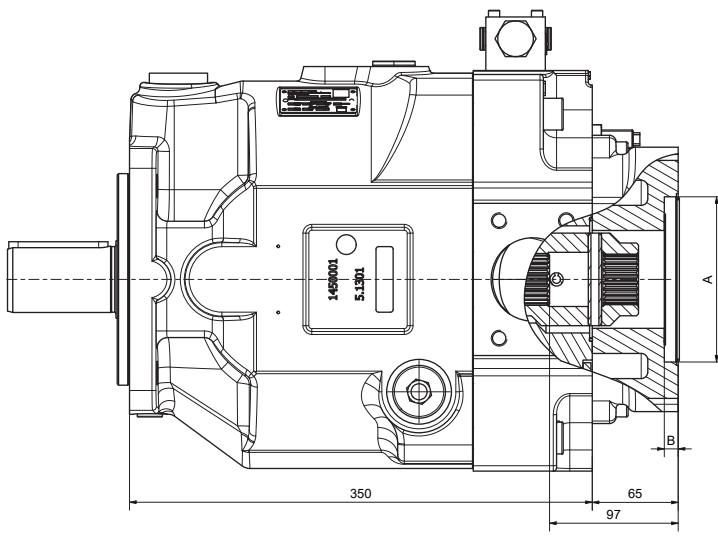
## PV 140-180 SAE Version

Flange according DIN ISO 3019-1 SAE  
for mounting interface code D, E, F and G

Shown are clockwise rotating pumps. Counter clockwise rotating pumps have inlet, outlet and gage port reversed.



## **Variation with through drive**



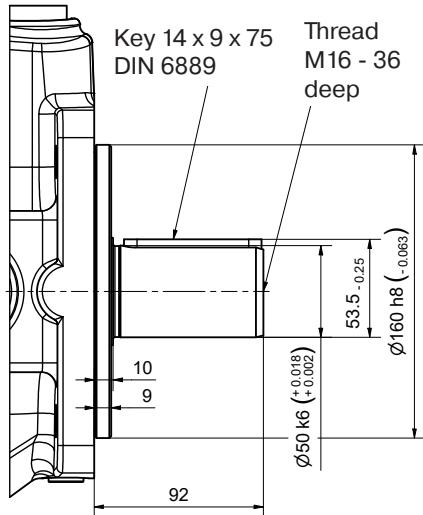
Through drive adaptors are available with the following dimensions

Through drive adaptors are available with the following dimensions									
Through drive option	Drawing Dimension	A	B	C	D	E	F	G	Remark
	A	82.55	8	-	-	-	106	M10	SAE A 2-Bolt
	B	101.6	11	127	89.8	M12	146	M12	SAE B 2/4-Bolt
	C	127	13.5	162	114.6	M12	181	M16	SAE C 2/4-Bolt
	D	152.4	13.5	228.5	161.6	M16	-	-	SAE D 4-Bolt
	J	100	10.5	125	88.4	M10	140	M12	2/4-Bolt
	K	125	10.5	160	113.1	M12	180	M16	2/4-Bolt
	L	160	13.5	200	141.4	M16	-	-	4-Bolt

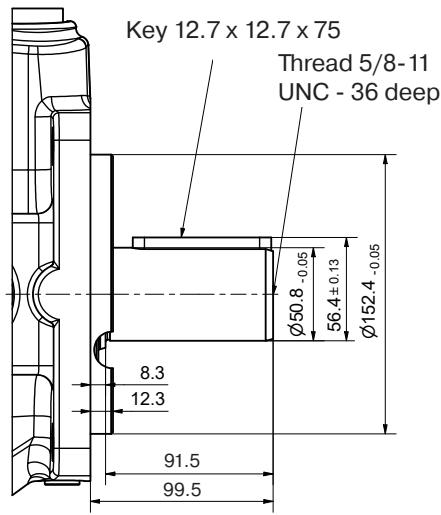
# PUMP DIMENSIONS

## PV 140-180 Mounting options

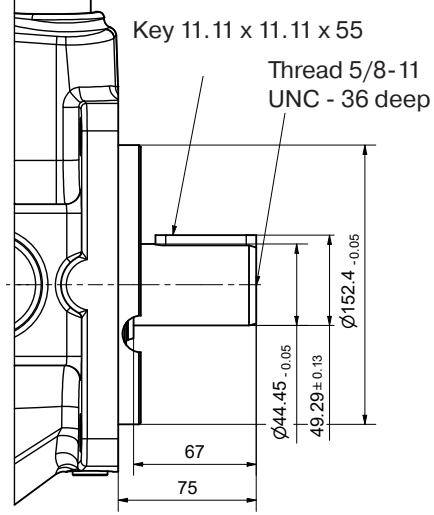
**Mounting option K**  
shaft keyed metric



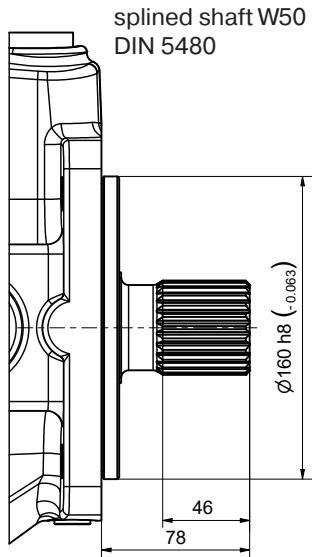
**Mounting option D**  
shaft keyed SAE



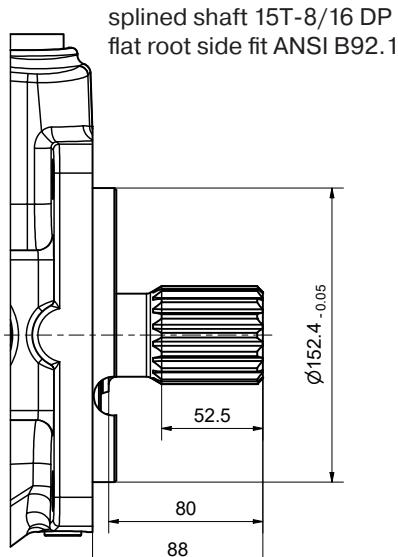
**Mounting option F**  
shaft keyed SAE



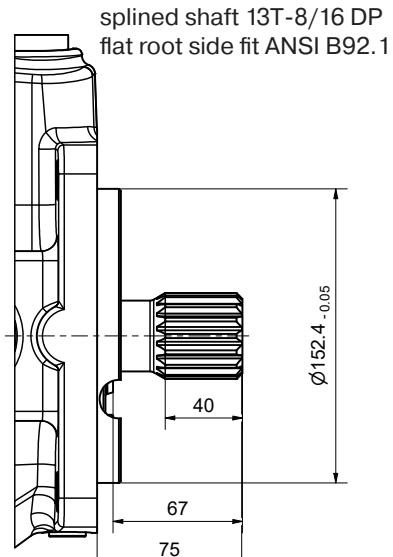
**Mounting option L**  
shaft splined metric



**Mounting option E**  
shaft splined SAE



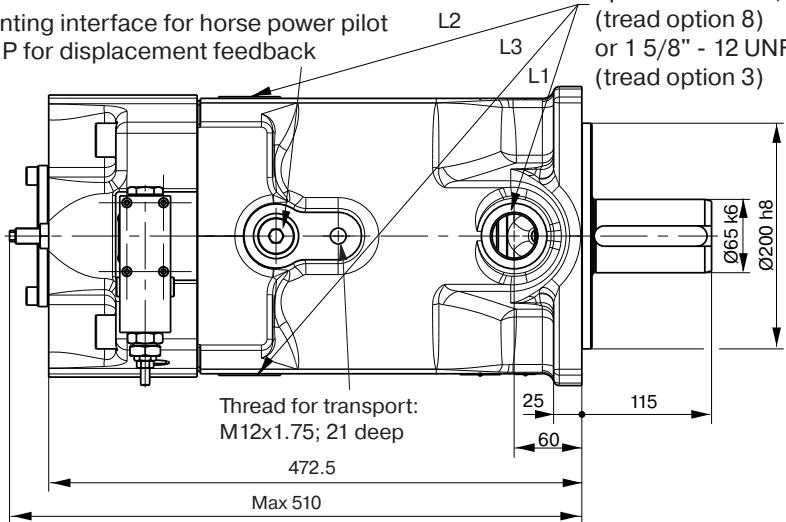
**Mounting option G**  
shaft splined SAE



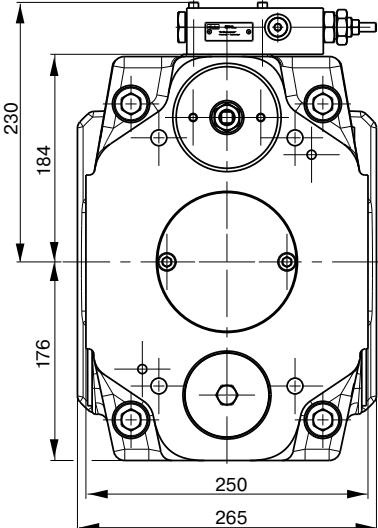
# PUMP DIMENSIONS

## PV 270, metric version

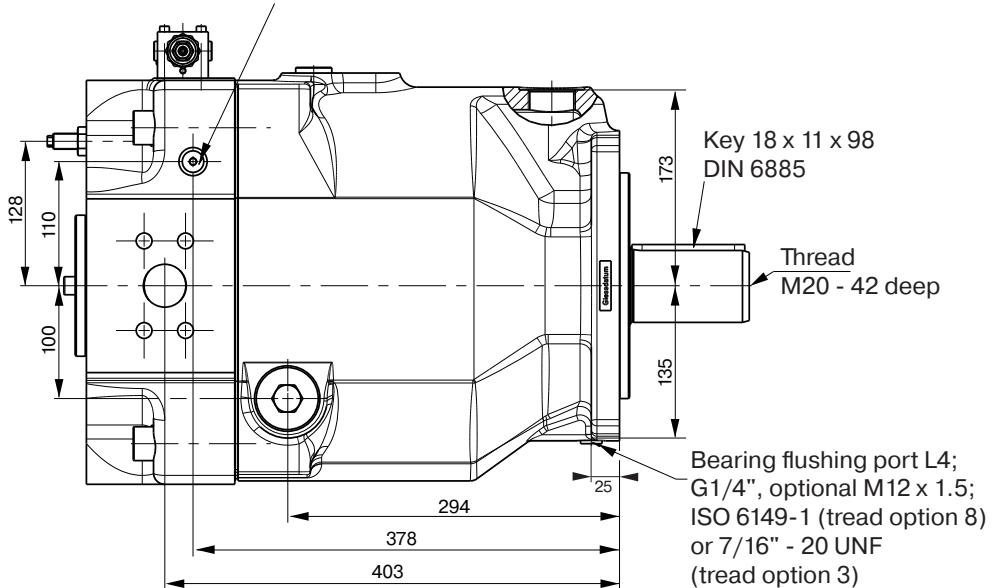
Mounting interface for horse power pilot or CIP for displacement feedback



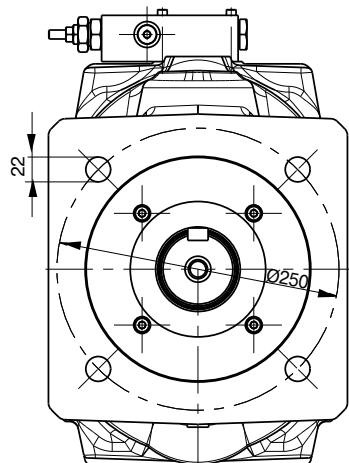
Drain ports L1, L2 and L3; G1 1/4" optional M42 x 2; ISO 6149-1 (tread option 8) or 1 5/8" - 12 UNF (tread option 3)



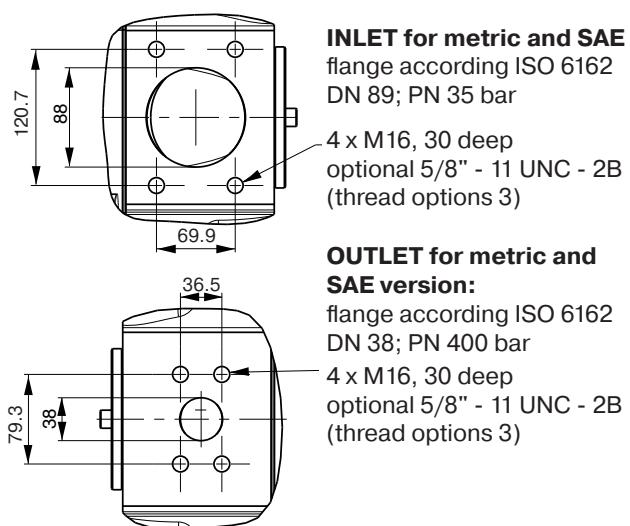
Gage port M; ISO 6149-1 M14x1.5 (for any thread option)



Key 18 x 11 x 98  
DIN 6885  
Thread  
M20 - 42 deep  
Bearing flushing port L4;  
G1/4", optional M12 x 1.5;  
ISO 6149-1 (tread option 8)  
or 7/16" - 20 UNF (tread option 3)



The pump shown above has  
**Mounting option K**  
and **through drive variation T**  
(prepared for through drive)



**INLET for metric and SAE version:**  
flange according ISO 6162  
DN 89; PN 35 bar

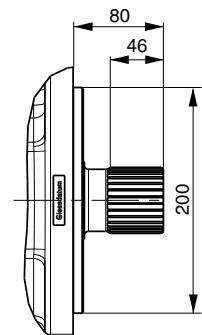
4 x M16, 30 deep  
optional 5/8" - 11 UNC - 2B  
(thread options 3)

**OUTLET for metric and**

**SAE version:**

flange according ISO 6162  
DN 38; PN 400 bar

4 x M16, 30 deep  
optional 5/8" - 11 UNC - 2B  
(thread options 3)

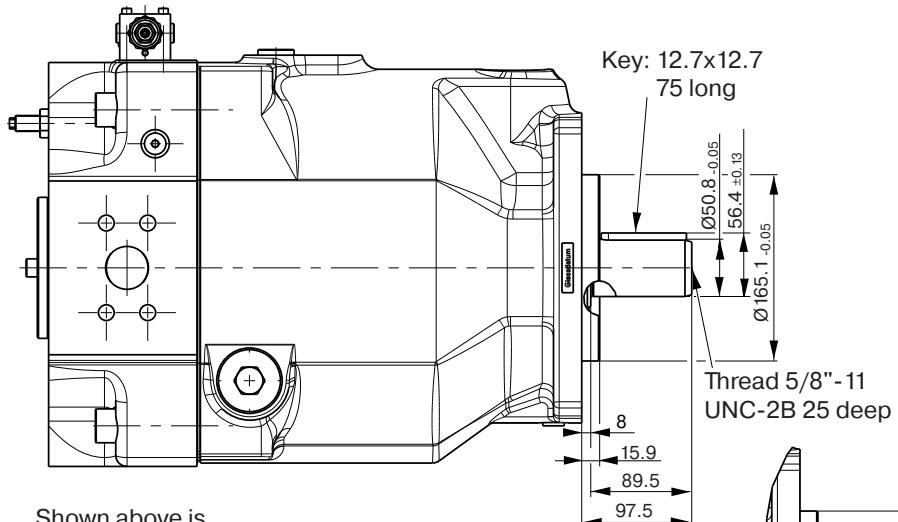


**Mounting option L,**  
splined shaft  
W60 x 2 x 28 x 9g DIN 5480

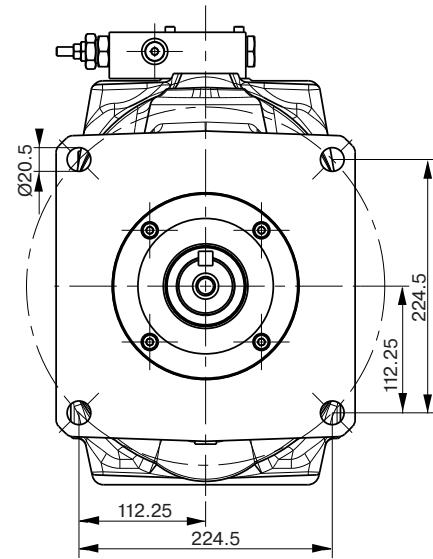
Shown is a clockwise rotating pump with standard pressure control. Counter clockwise rotating pump have inlet, outlet and gage port reversed.

# PUMP DIMENSIONS

## PV 270 SAE Version

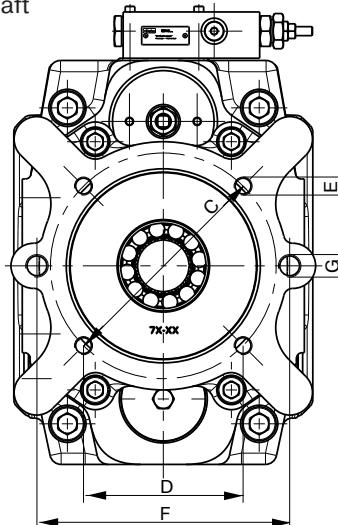
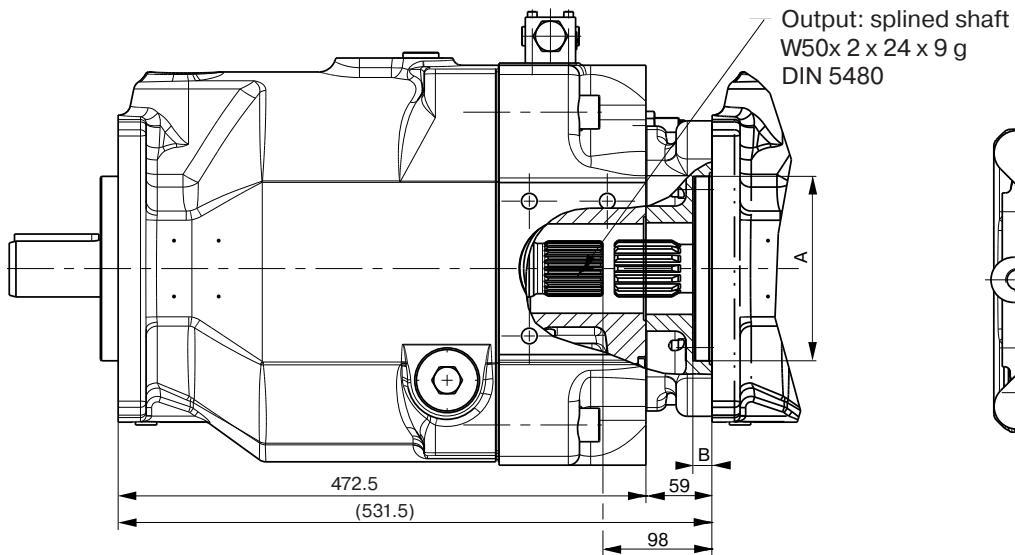


Shown above is  
**Mounting option D**



**Mounting option E**  
splined shaft 15T-8/16 DP,  
flat root, side fit ANSI B92.1

## Variation with through drive



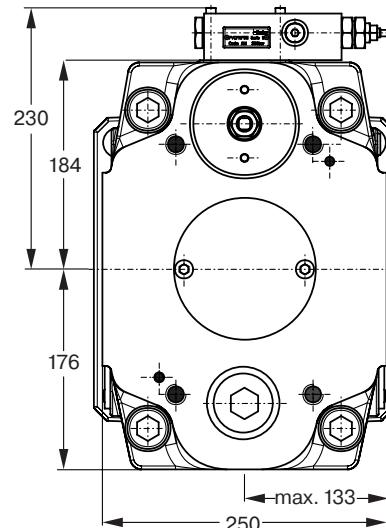
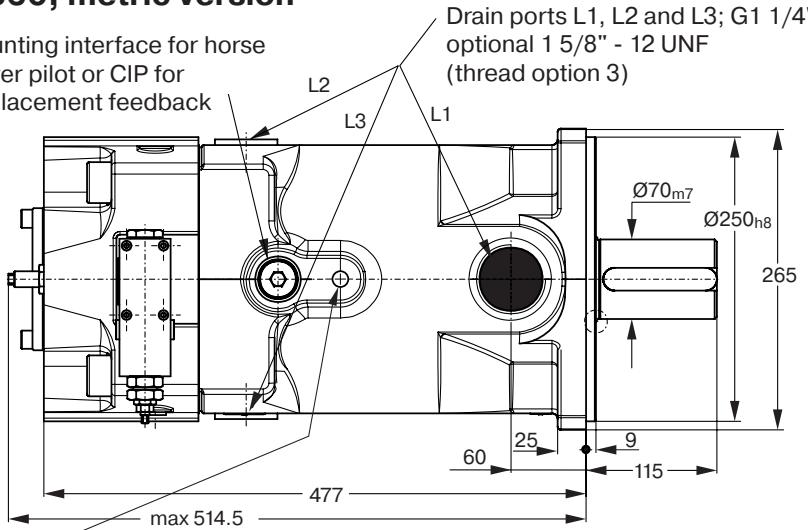
### Through drive adaptors are available with the following dimensions

Through drive option	Drawing Dimension	A	B	C	D	E	F	G	Remark
A	82.55	8	-	-	-	106	M10	SAE A 2-Bolt	
B	101.6	11	127	89.8	M12	146	M12	SAE B 2/4-Bolt	
C	127	13.5	162	114.6	M12	181	M16	SAE C 2/4-Bolt	
D	152.4	13.5	228.5	161.6	M16	229	M16	SAE D 2/4-Bolt	
E	165.1	17	317.5	224.5	M20	-	-	SAE E 4-Bolt	
J	100	10.5	125	88.4	M10	140	M12	2/4-Bolt	
K	125	10.5	160	113.1	M12	180	M16	2/4-Bolt	
L	160	13.5	200	141.4	M16	224	M20	2/4-Bolt	
M	200	13.5	250	176.8	M20	-	-	4-Bolt	

# PUMP DIMENSIONS

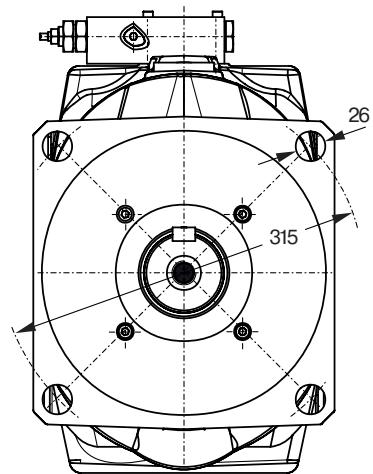
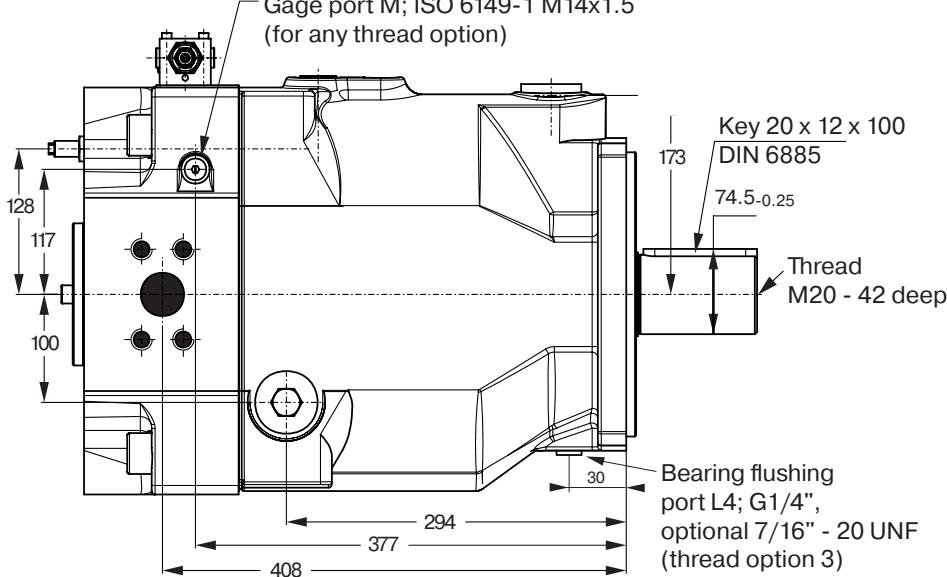
## PV 360, metric version

Mounting interface for horse power pilot or CIP for displacement feedback

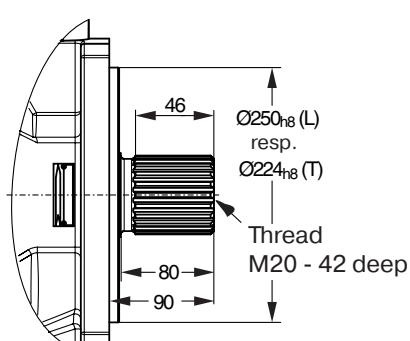
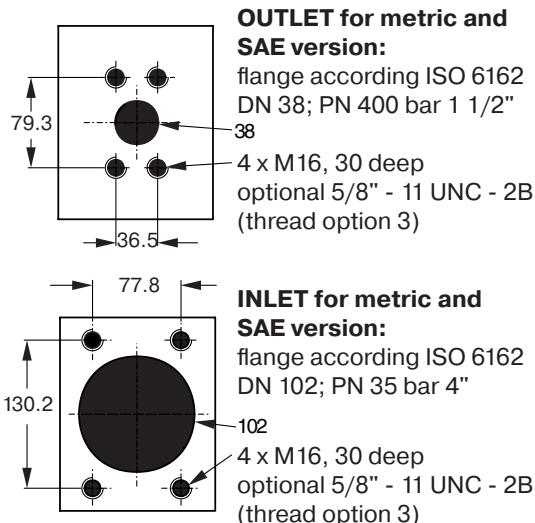


Thread for transport:  
M12x1.75; 21 deep

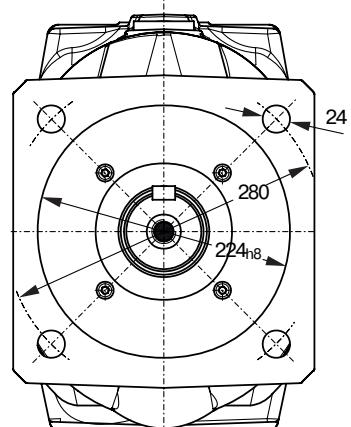
Gage port M; ISO 6149-1 M14x1.5  
(for any thread option)



The pump shown above has **Mounting option K** and **through drive variation T** (prepared for through drive)



**Mounting option L, T,**  
splined shaft  
W 70 x 3 x 22 x 8f DIN 5480

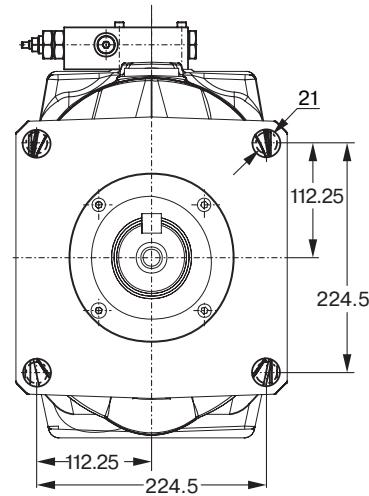
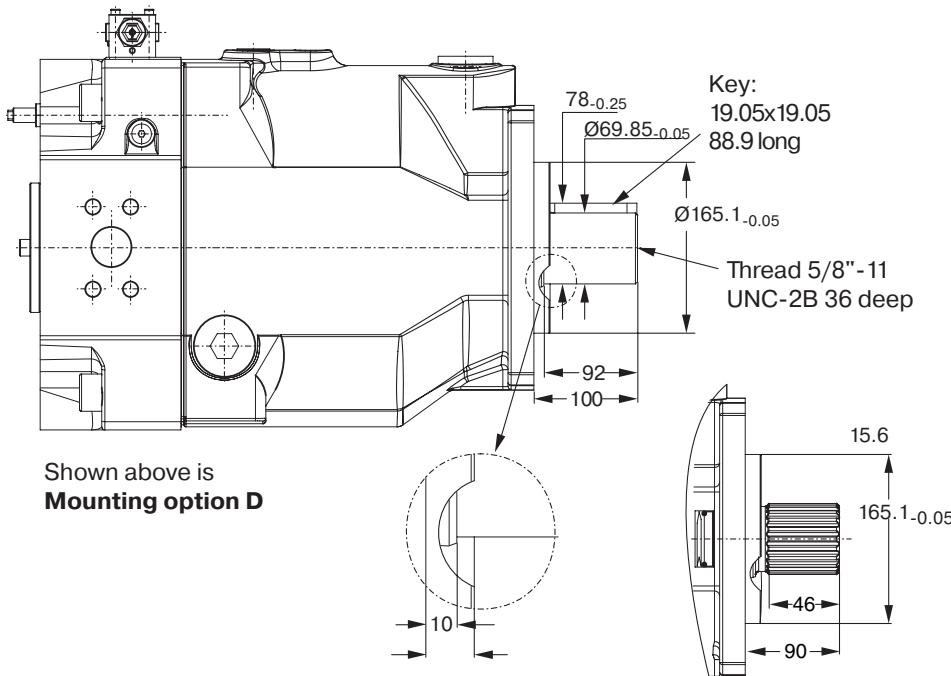


**mounting option R**  
pilot diameter Ø224 mm

Shown is a clockwise rotating pump with standard pressure control. Counter clockwise rotating pump have inlet, outlet and gage port reversed.

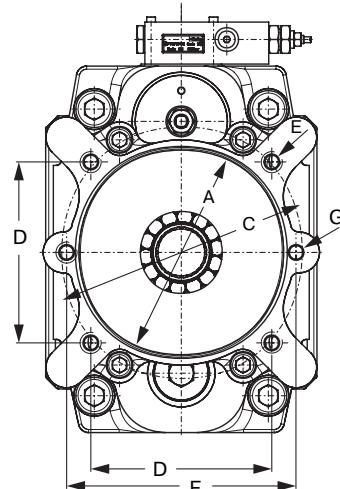
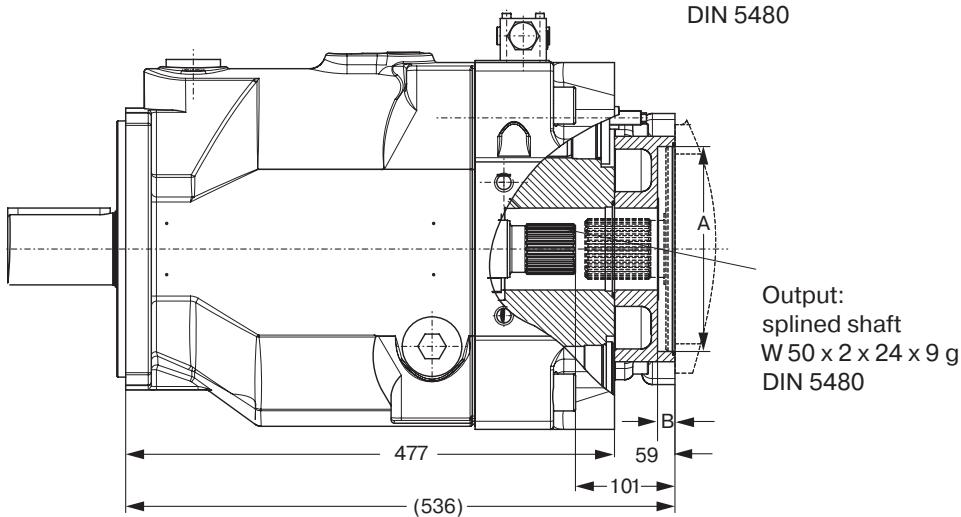
# PUMP DIMENSIONS

## PV 360 SAE Version



**Note:**  
The dimensions shown conform to ISO 3019/1 the actual hole dimensions conform to ISO 3019/2 (pitch Ø315, hole Ø26, see previous page) and cover ISO 3019/1 dimensions as well. Use washers when assembling pump.

## Variation with through drive

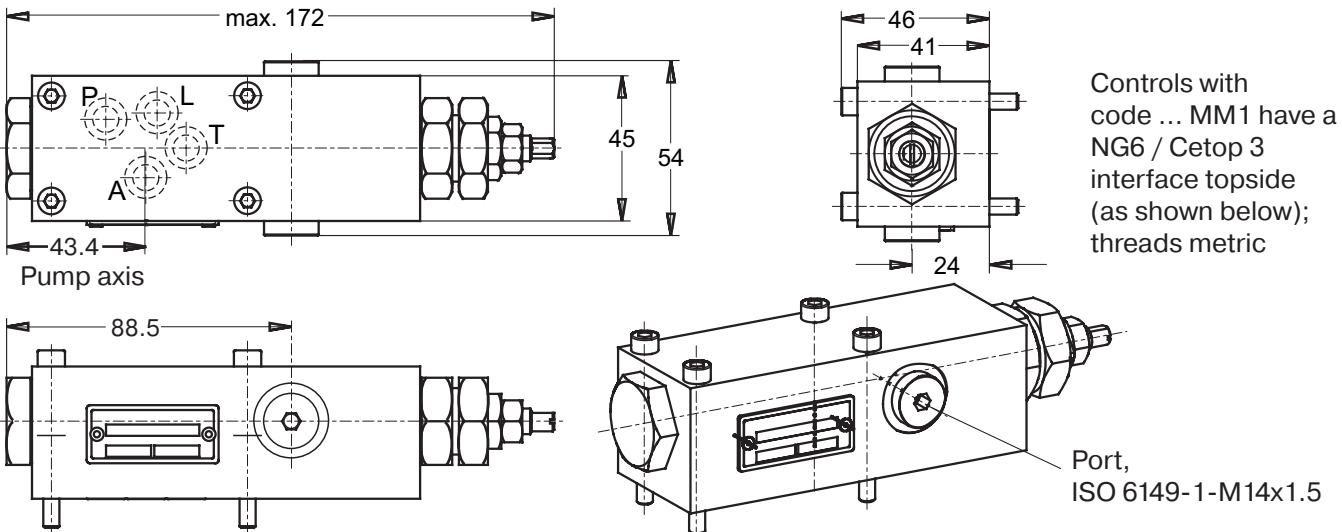


### Through drive adaptors are available with the following dimensions

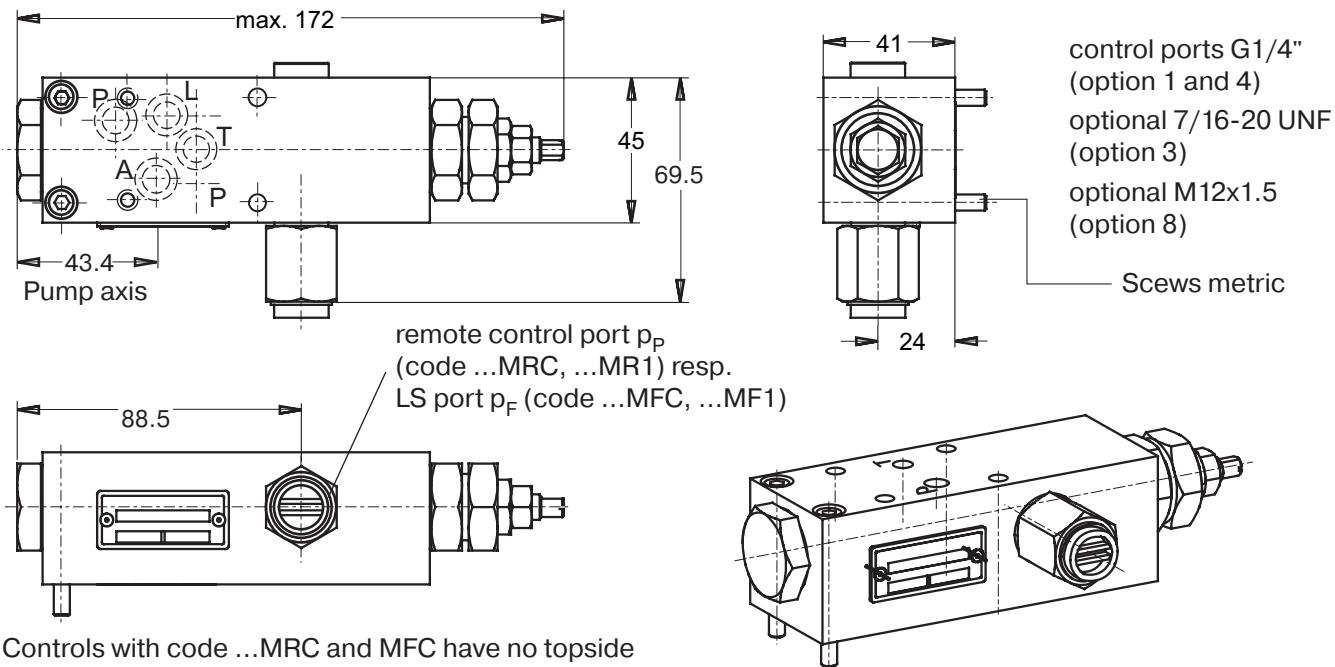
Through drive option	Drawing Dimension	A	B	C	D	E	F	G	Remark
A	82.55	8	-	-	-	106	M10	SAE A 2-Bolt	
B	101.6	11	127	89.8	M12	146	M12	SAE B 2/4-Bolt	
C	127	13.5	162	114.6	M12	181	M16	SAE C 2/4-Bolt	
D	152.4	13.5	228.5	161.6	M16	229	M16	SAE D 2/4-Bolt	
E	165.1	17	317.5	224.5	M20	-	-	SAE E 4-Bolt	
J	100	10.5	125	88.4	M10	140	M12	2/4-Bolt	
K	125	10.5	160	113.1	M12	180	M16	2/4-Bolt	
L	160	13.5	200	141.4	M16	224	M20	2/4-Bolt	
M	200	13.5	250	176.8	M20	-	-	4-Bolt	

# CONTROL DIMENSIONS

## Dimensions standard pressure control, code ...MMC

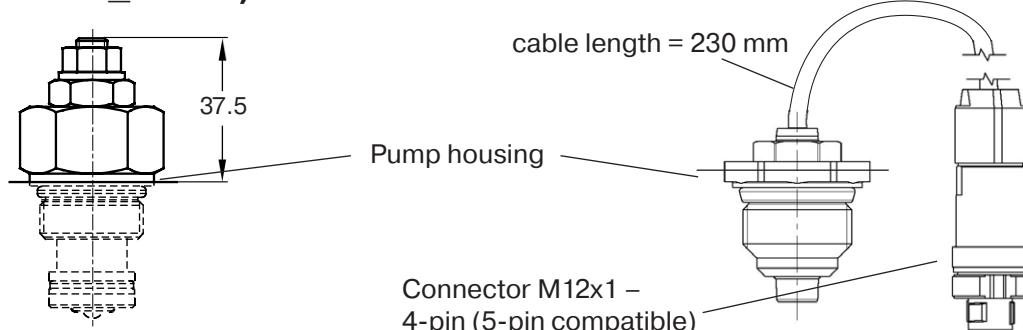


## Dimensions remote pressure and load sensing control, codes ...MR1, ...MF1



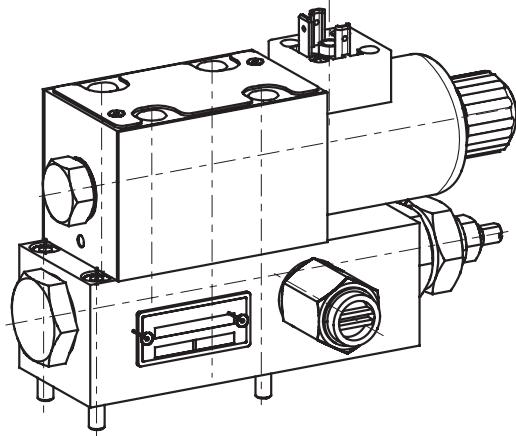
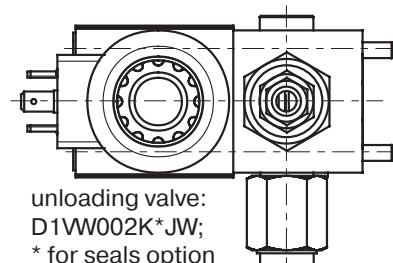
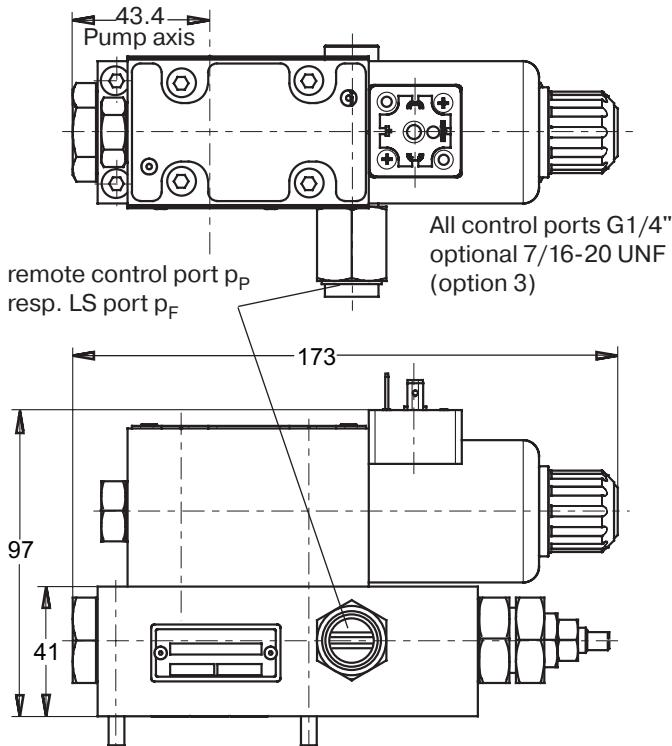
Controls with code ...MRC and MFC have no topside valve interface (as shown above)

## Dimensions horse power pilot cartridge, displacement sensor (Contactless Inductive Position)



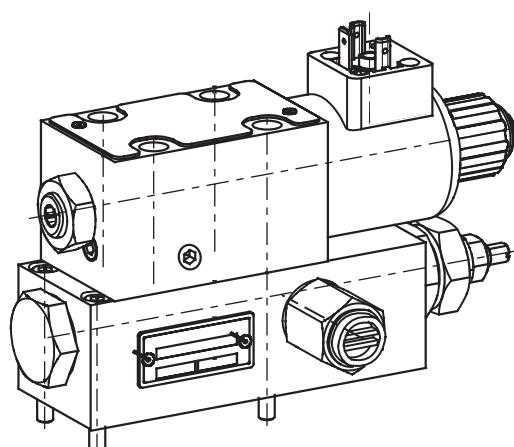
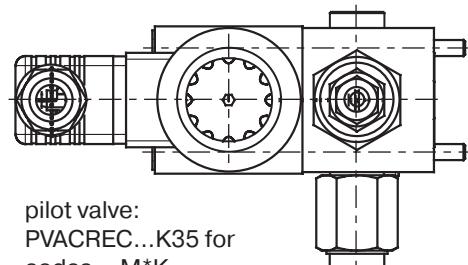
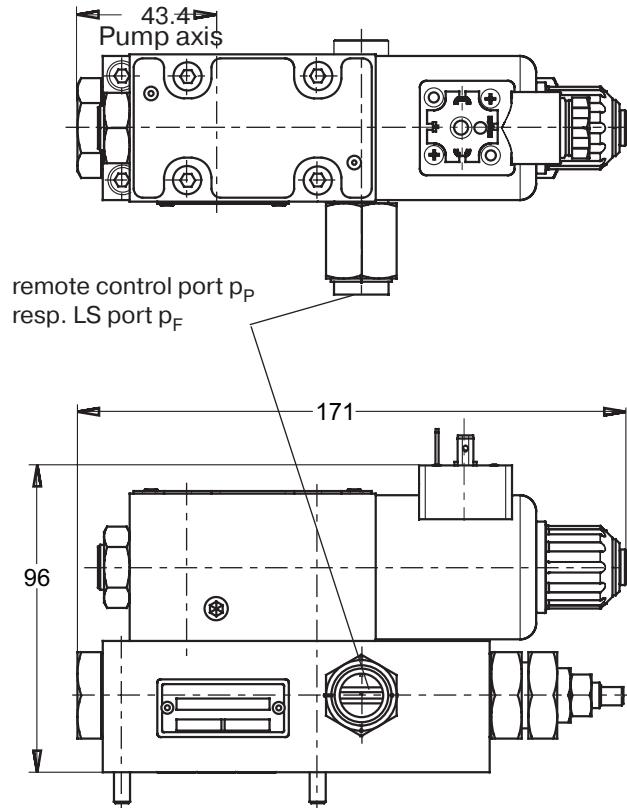
# CONTROL DIMENSIONS

## Dimensions for controls with unloading valve, codes ...M\*W



Shown in version MRW/MFW, version MMW has no remote control port.

## Dimensions for controls with proportional pressure pilot valve, codes ...M\*K



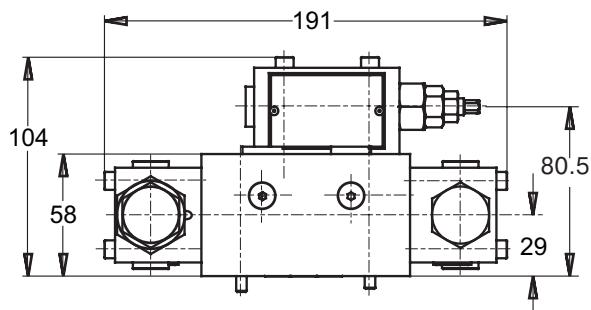
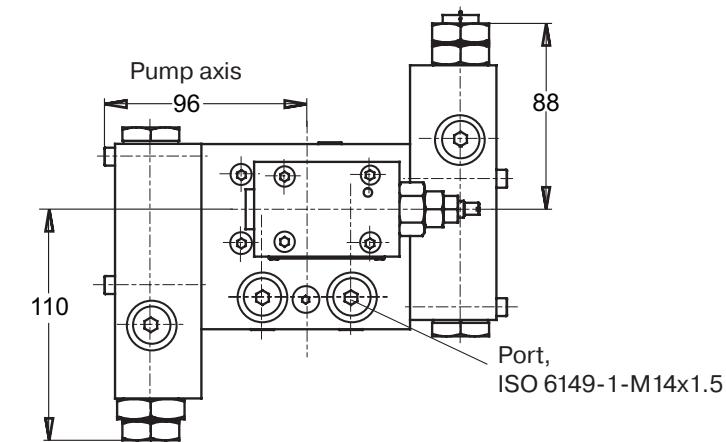
Shown in version MRK/MFK, version MMK has no remote control port.

Dimensions for horse power compensator \*L\* and \*C\* are identical to MM\* respectively MF\*.

# CONTROL DIMENSIONS

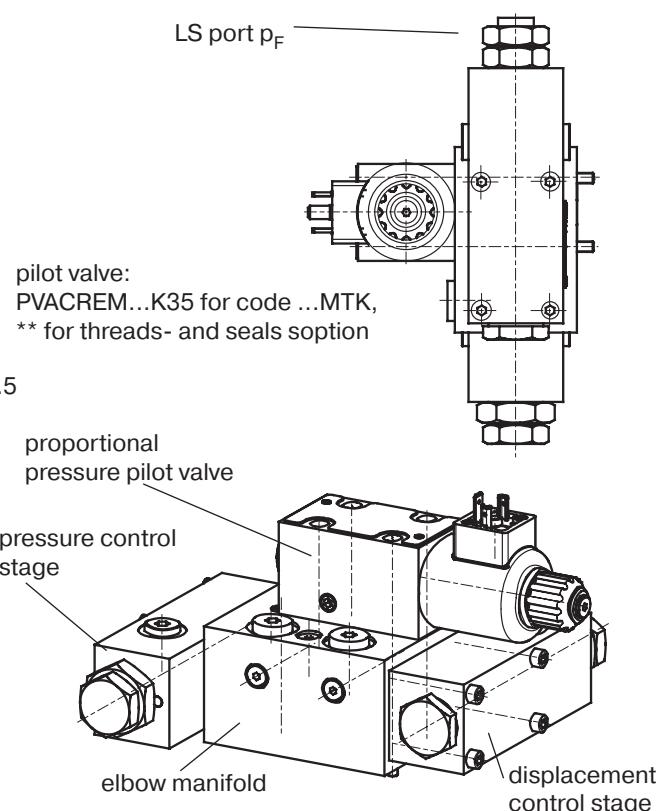
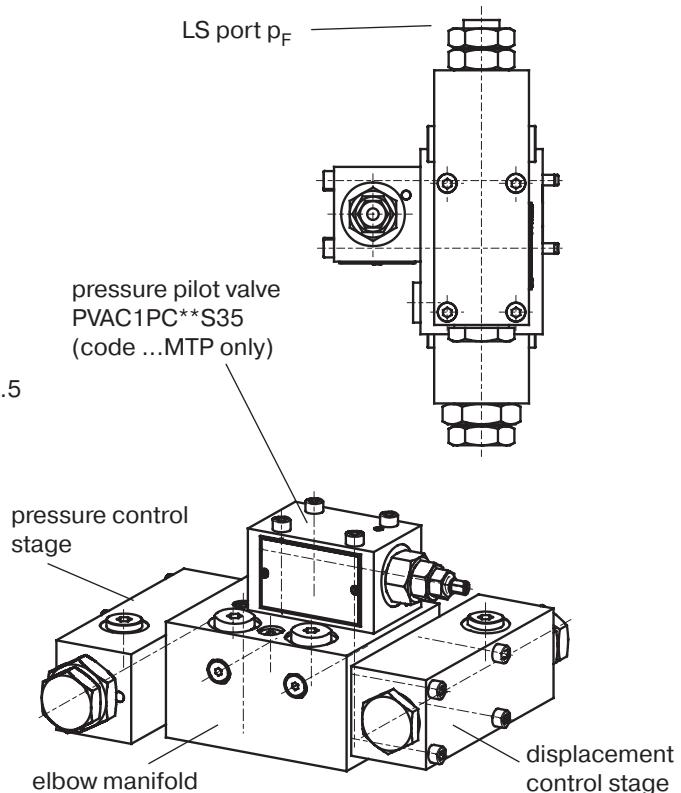
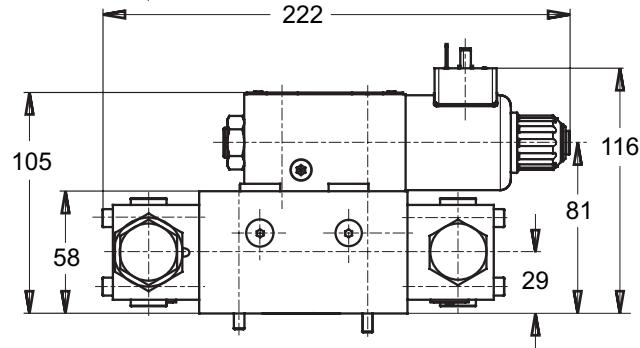
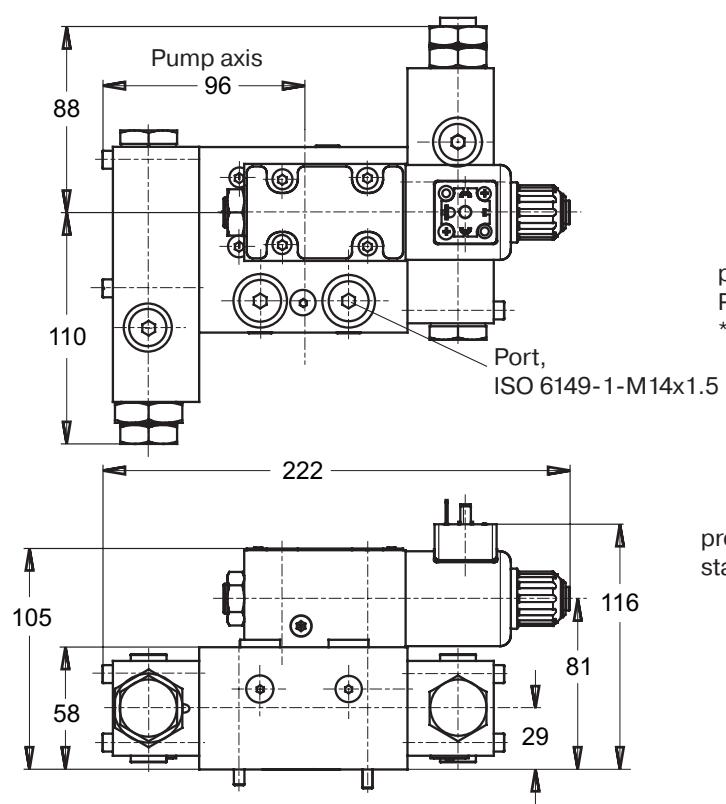
## Dimensions two spool load sensing control, code ...MTZ, ...MTP

All connecting screws metric



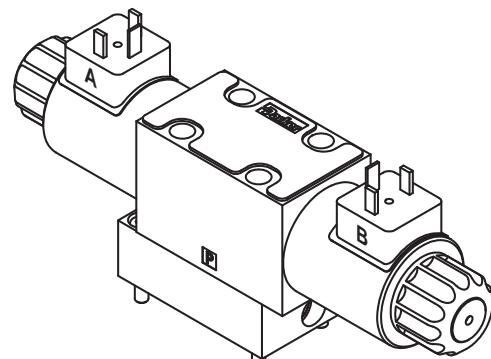
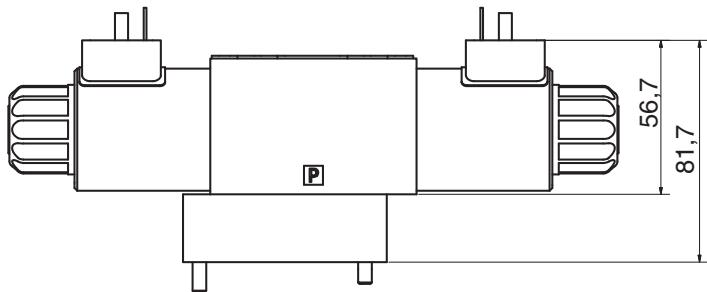
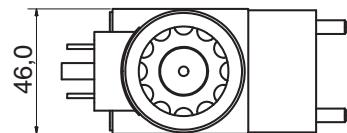
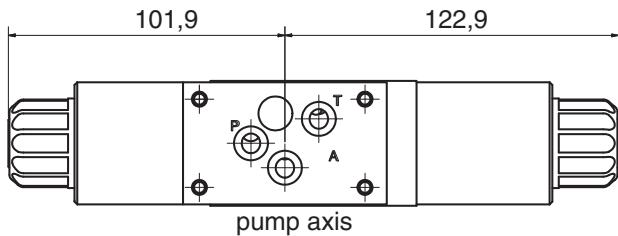
Shown version MTP

## Dimensions two spool load sensing control with proportional pressure pilot valve, code ...MTK – All connecting screws metric



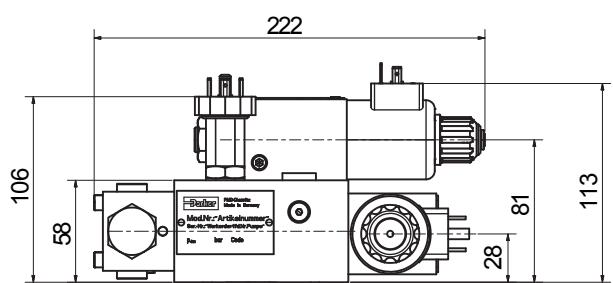
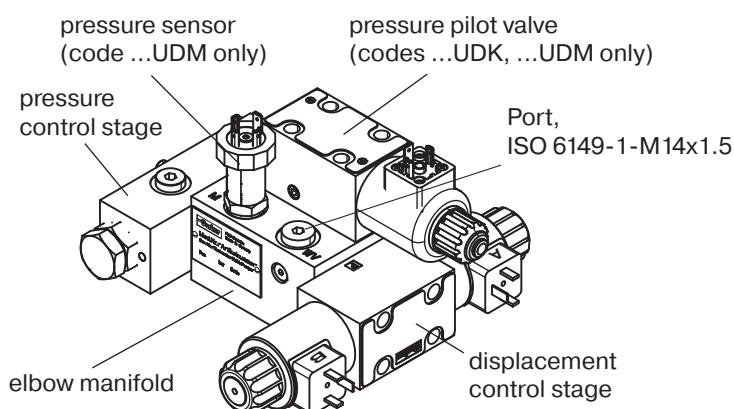
# CONTROL DIMENSIONS

Dimensions proportional displacement control, code ...FDV – All connecting screws metric

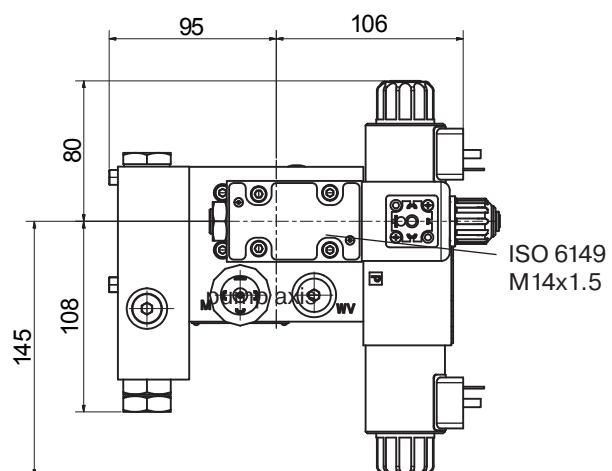
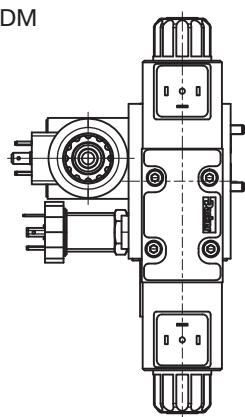


Dimensions proportional p/Q-control, codes ...UDR, ...UDK, ...UDM

All connecting screws metric

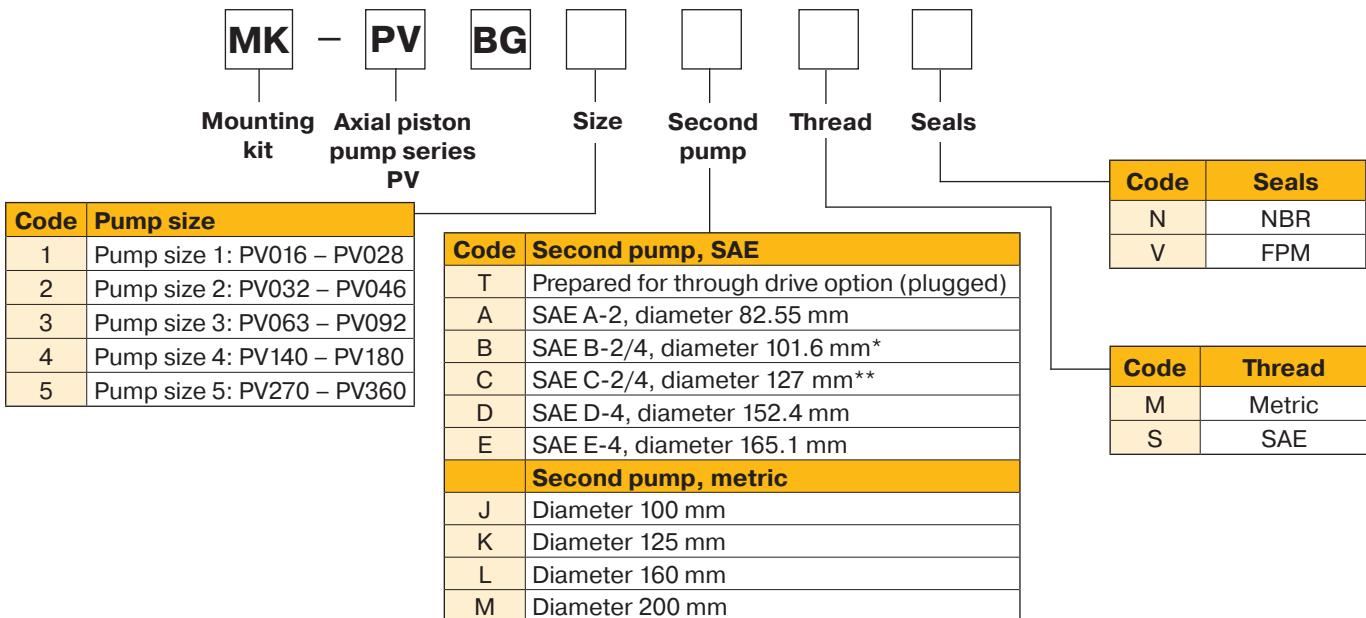


pilot valve:  
PVACREM...K35 for code ...UDK, UDM  
\*\* for threads- and seals option



# THROUGH DRIVE – MOUNTING KITS

## Mounting kits for multiple pumps, for second pump option

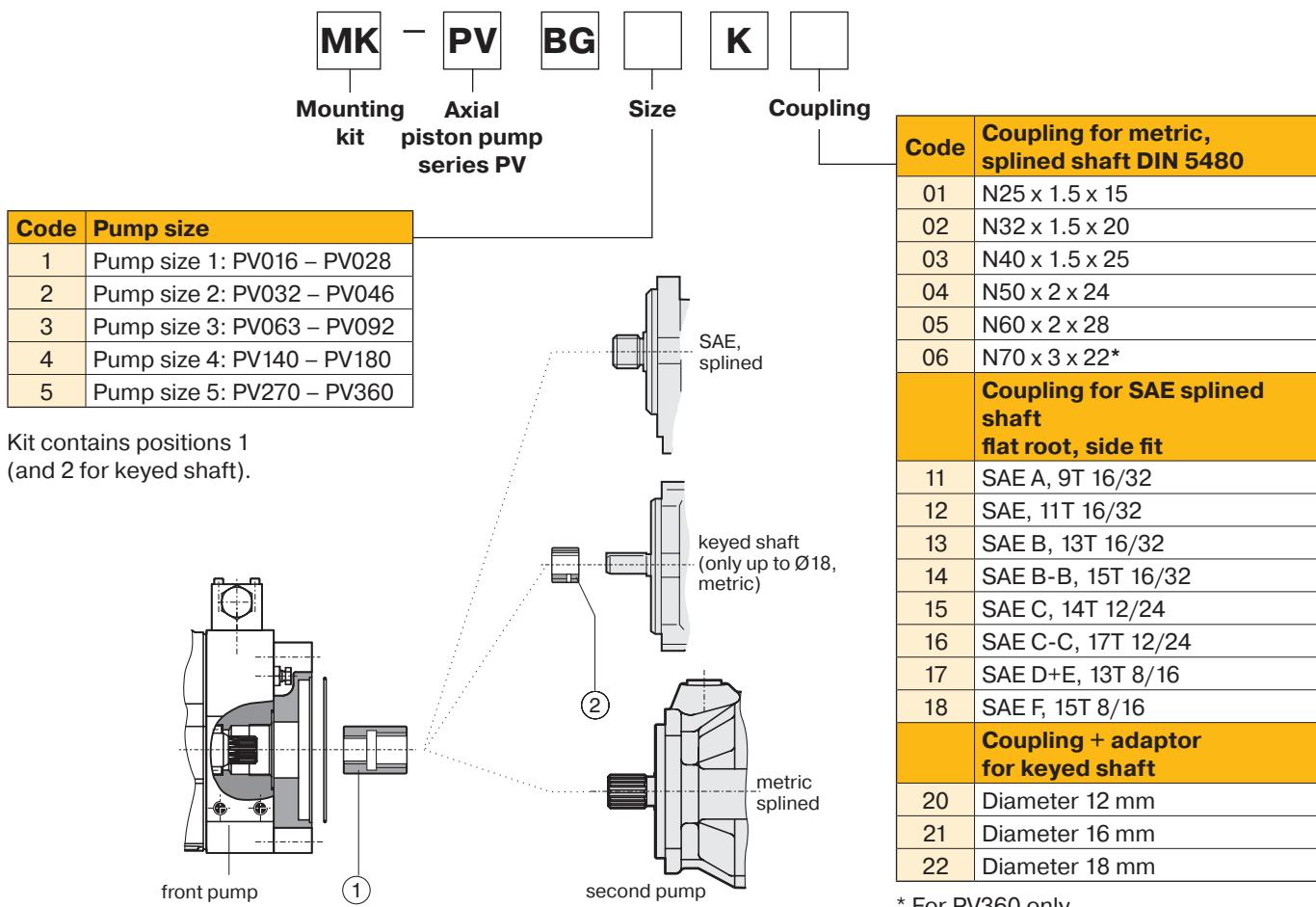


Kit contains positions 30, 69, 84, 85 and 87, see spare part list

\* PV016-PV028 only available with SAE B - 4 bolt, diameter 101,6 mm

\*\* PV032-PV046 only available with SAE C - 4 bolt, diameter 127 mm

## Mounting kits for multiple pumps, couplings



\* For PV360 only

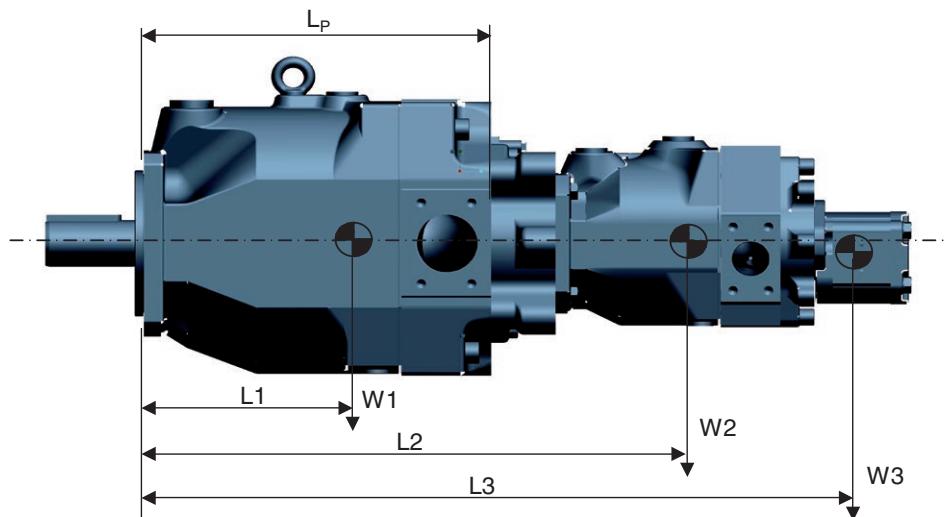
Availability of through drive flange and coupling please check with ordering code options per each pump size, starting at page 6

# THROUGH DRIVE – FLANGE LOAD LIMITATION

## Multiple Pump Combinations – Maximum Moment

Combinations of multiple pumps might require additional pump support to avoid high stress on the front mounting flange. Combinations of two PVplus pumps in the same frame size generally do not need additional support in an industrial application. For combinations of more pumps support is required.

In case of combinations of a PVplus pump with another type of pump it is recommended to calculate the moment for the combination and compare with the maximum moment in table 1 below.



$$\text{Moment } M = (L_1 \cdot W_1 + L_2 \cdot W_2 + L_3 \cdot W_3 + \dots)$$

**Note:** If the calculated moment M exceed the maximum moment in table 1 below, additional pump support is needed

**Table 1: Maximum Moment and Pump Dimensions**

	PV016-PV028	PV032-PV046	PV063-PV092	PV140-PV180	PV270	PV360
Maximum moment <sup>1)</sup> [Nm]	81	151	401	591	1686	1686
Weight W [N]	186	294	589	883	1687	1766
Distance L1 [mm to C/G]	106	119	178	184	234	238
Distance L <sub>p</sub> [mm]	197.5	227	287	350	472.5	477

<sup>1)</sup> at dynamic weight acceleration 10g = 98.1 m/sec<sup>2</sup>

**Table 2 Through Drive Adapter Plate Thickness [mm]**

Adapter option <sup>2)</sup>	PV016-PV028	PV032-PV046	PV063-PV092	PV140-PV180	PV270	PV360
A	27	34	39	65	59	59
B	27	34	39	65	59	59
C	-	49	39	65	59	59
D	-	-	64	65	59	59
E	-	-	-	-	59	59
G	27	34	39	-	-	-
J	27	34	39	65	59	59
K	-	34	39	65	59	59
L	-	-	39	65	59	59
M	-	-	-	-	59	59

<sup>2)</sup> See page 6 to 17 for reference per each frame size.

# THROUGH DRIVE – SHAFT LOAD LIMITATIONS

Maximum allowed transferable torque FRONT						
Shaft code	Shaft type	Transferable torque at FRONT shaft end. [Nm]				
		PV016-028	PV032-046	PV063-092	PV140-180	PV270
<b>D</b>	SAE - Key	300	650	1850	2150	2150
<b>E</b>	SAE - Spline	320	630	1700	2750	2800
<b>F</b>	SAE - Key				1200	
<b>G</b>	SAE - Spline				1700	
<b>R</b>	Metric - Key					3750
<b>T</b>	Metric - Spline					8100
<b>K</b>	Metric - Key	280	640	1200	1550	3300
<b>L</b>	Metric - Spline	320	720	1500	3050	5750
Maximum allowed transferable torque REAR						
Max. torque transmission cap. for rear mounted pump		350	520	1100	1550	3150
						3250

\* DIN5480 splined

## Important notice:

The max. allowable torque of the individual shaft must not be exceeded. For 2-pump combinations there is no problem because PV series offers 100 % through torque. For 3-pump combinations (and more) the limit torque could be reached or exceeded.

Therefore it is necessary to calculate the resulting input as well as through drive torque.

# NOTES

# NOTES



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